



MIT Medical Device Design

Prof. Alexander H. Slocum

Walter M. May (1939) and A. Hazel May Chair in Emerging Technologies
Director, Precision Engineering Research Group

meddevdesign.mit.edu



Designing better healthcare takes a team



Alexander Slocum, PhD
Professor
Mechanical Engineering
Precision Machine
Design Guru



Gio Traverso, MD
Professor
Mechanical Engineering
Gastroenterologist
Brigham & Women's



Ellen Roche, PhD
Professor
Institute for Medical
Engineering & Science
Therapeutic Technology
Design & Development



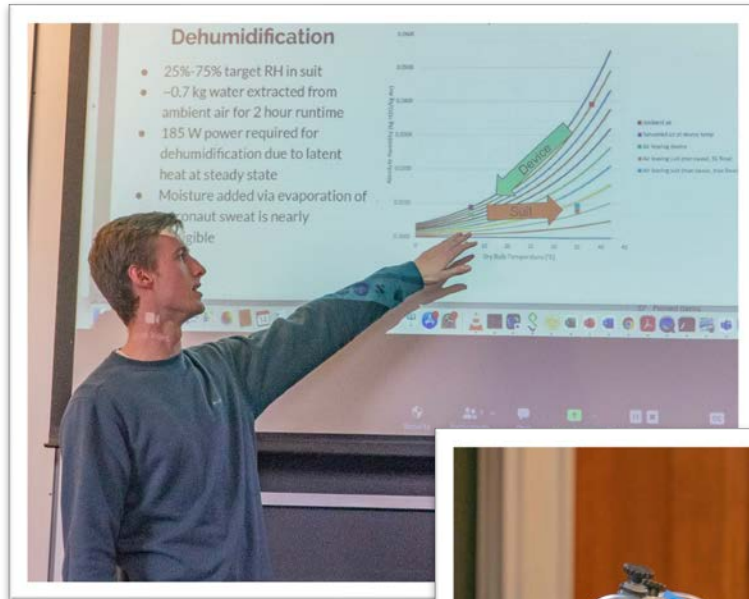
Nevan Hanumara, PhD
Research Scientist
Mechanical Engineering
Design, Human Factors,
Entrepreneurship



Anthony Pennes
Instructor
Electrical Engineering
Electronics Wizard



Our Mission: Prepare the next generation of healthcare innovators!



We bring together Clinicians, Companies, Engineers & Entrepreneurs

Experienced

Multidisciplinary

Inclusive

Clinically Driven

Competitive

Teamwork

Mentorship

Accelerated

Efficient

Engagement

Taught since 2003

MechE, EECS, HST, SDM, others

Open to Grads & Undergrads

I need solution to ...

Students select the projects

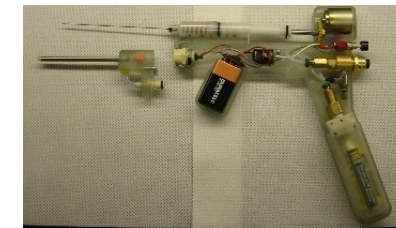
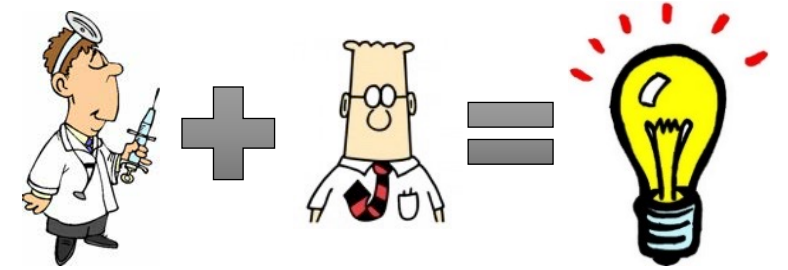
8 teams of 4-6 students

Course staff support each team

12 weeks to proof-of-concepts

\$4k budget/team

Industry participation essential

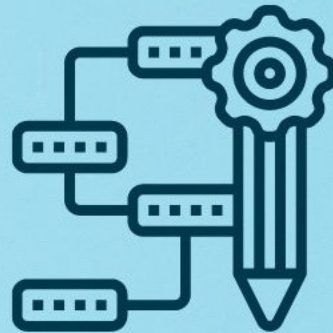


We follow an accelerated, industry-modeled design process: 12 Weeks – Three Phases



DISCOVER

Select a clinical challenge & dive deep



DEVELOP

Explore the options;
build your prototype

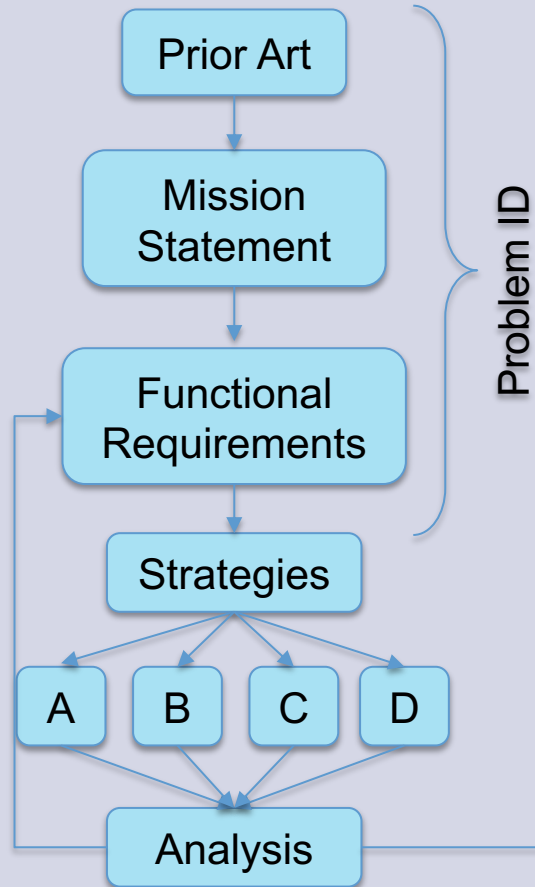


DEMONSTRATE

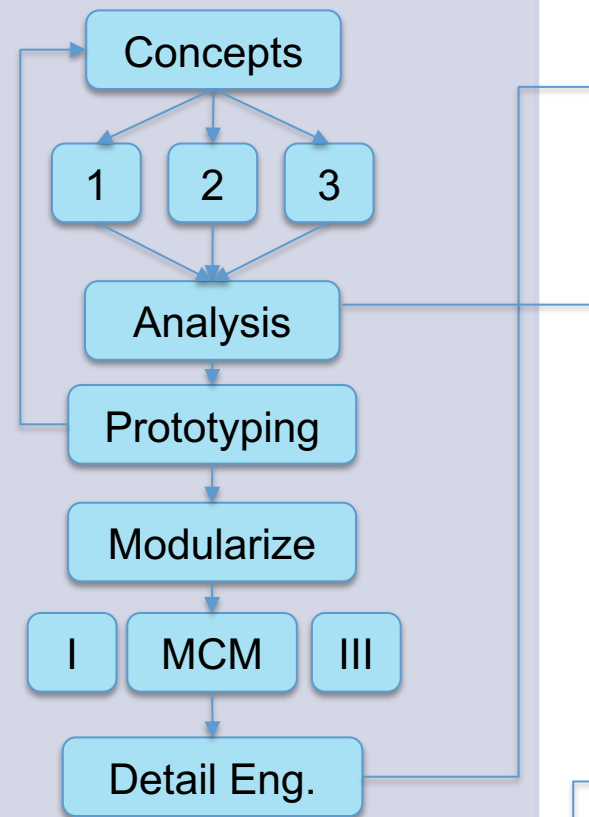
Test your design
and make it better

We learn and prototype together

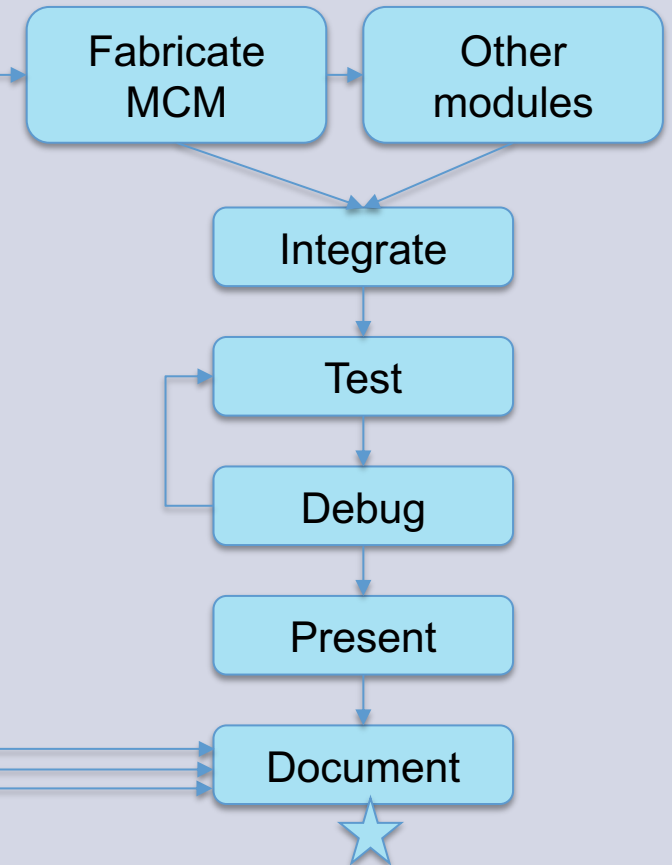
Discover



Develop

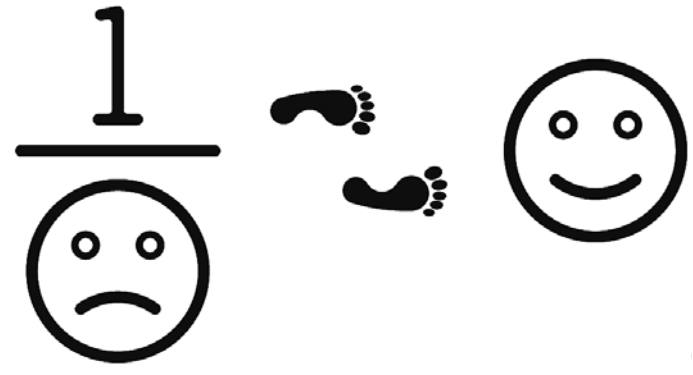
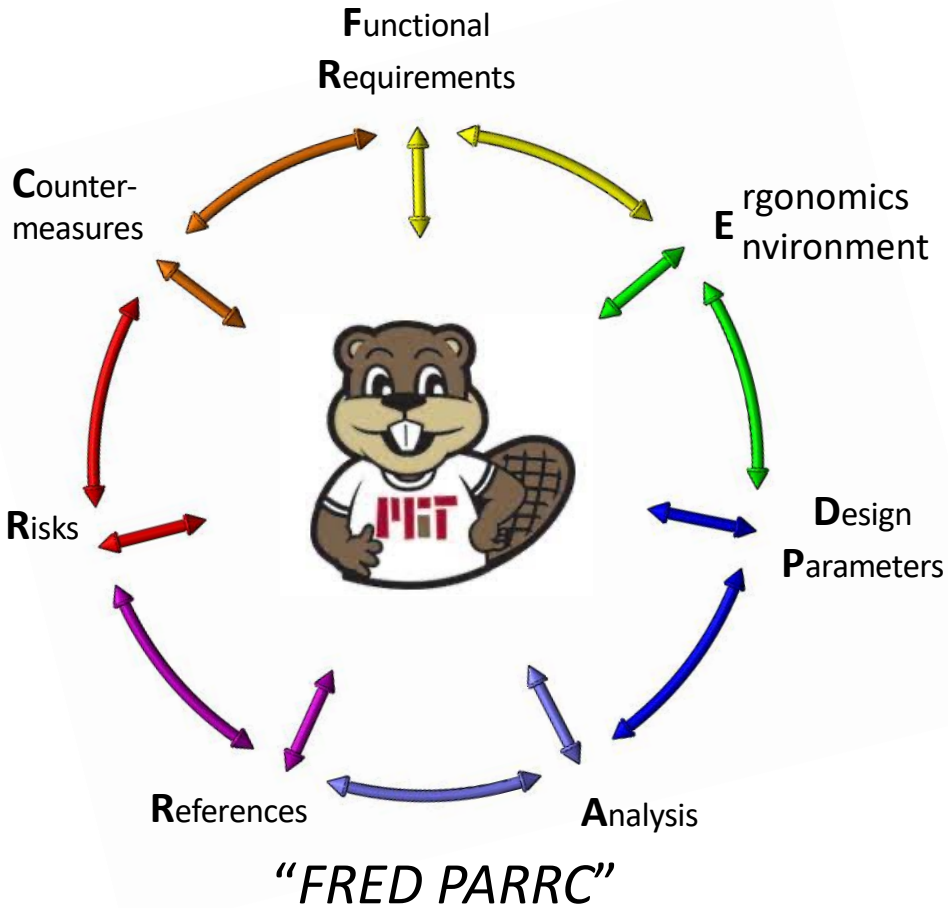


Demonstrate



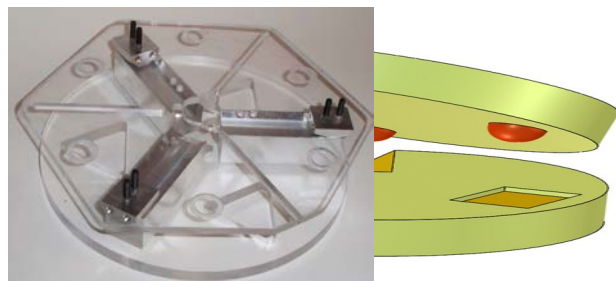
Increasing level of detail

We teach Deterministic Design & Teamwork

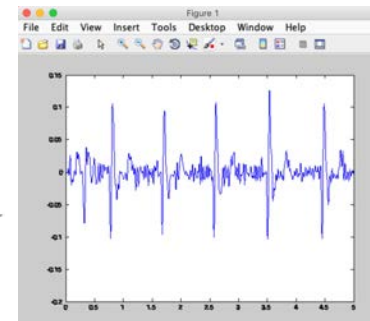
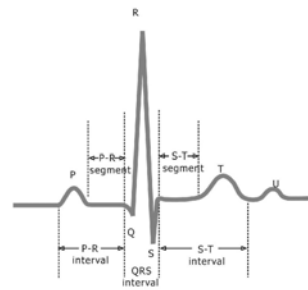
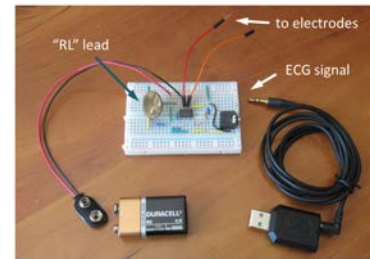
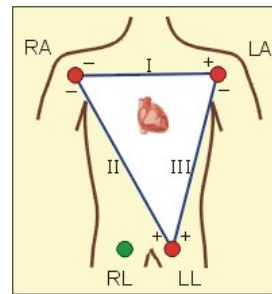


Labs reinforce the lectures

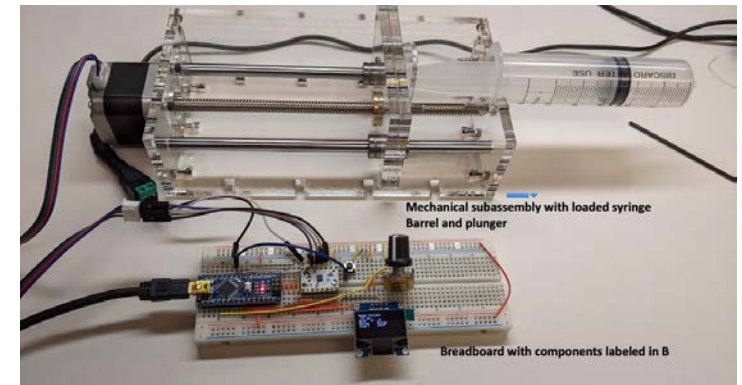
Precision Assembly *Kinematic Coupling*



Biomedical Sensing *Electrocardiogram*

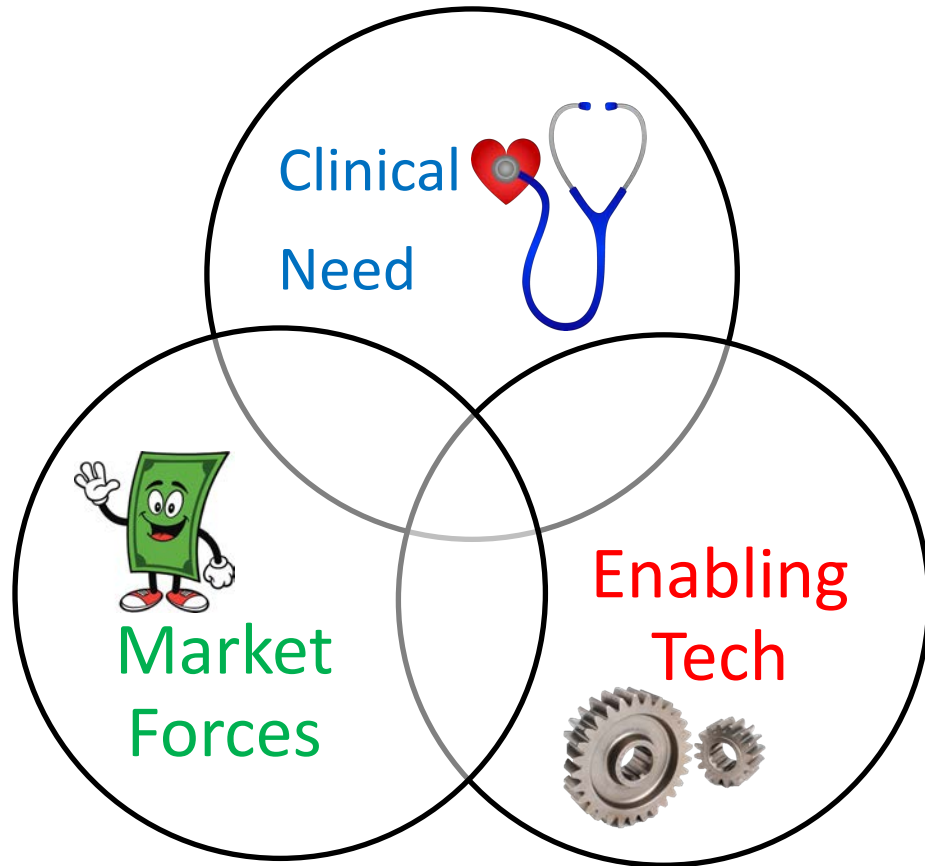


Mechatronics *Syringe Pump*



A. Pennes, K. Mendez, N. Hanumara, E.T. Roche, G. Traverso, D. Custer, G. Hom, "A hands-on medical mechatronics exercise to pump up student learnings," accepted for publication in *J. Biomedical Engineering Education*, Special Issue on Experiential Learning.

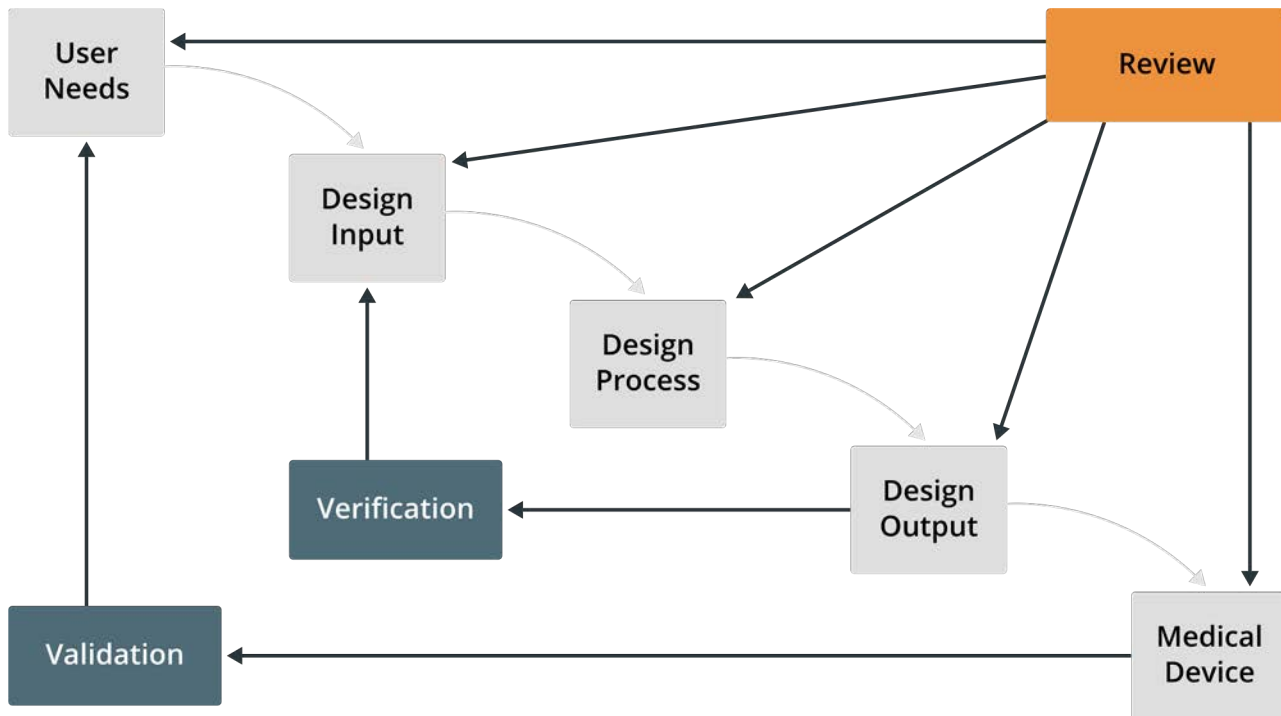
We teach best design practice in support of regulatory, IP reimbursement & business issues



The Medical Device Tripod

- What is the unmet clinical need?
- Why is the current technology insufficient?
- What is the clinical burden of proof?
- What technologies already exist?
- How much better do you need to be?
- What is your biggest technological risk?
- What is your regulatory and IP path?
- Who pays? – Patient, Doctor, Hospital, Insurer?
- Will it make money? ... Save money? ... Cost more?
- Beachhead? Total Addressable Market (TAM)?
- Who is likely to acquire you? When?

It is never too early to start your DHF (Design History File)



User requirement specifications
System architecture
Software architecture
Component drawings
Risk analysis and risk assessments
System tests
Component tests
Validation activities

www.fda.gov/regulatory-information/search-fda-guidance-documents/design-control-guidance-medical-device-manufacturers

www.simplerqms.com/design-history-file

Example 2022 Projects

BRIGHAM AND WOMEN'S HOSPITAL

Figure 1: Computer-Aided Design (CAD) of 3D Printed Device Without Balloon

Figure 2: Final Device Prototype at a Deflated and Inflated State

- Acrylic cover
- Electronics housing
- Temp sensor, IMU, + display
- Cooling sleeve + drug holder
- Insulated container
- Storage

Drug storage & reminder device

Low-cost capillary electrophoresis device for multiplexed DNA fragment analysis

Facilitating a screen and treat approach in cervical cancer

Improved Hydrocephalus ETV Procedure

Proton therapy patient positioning

Building a Novel Monitor for Infants with Congenital Heart Disease

2.75 Outcomes: Papers, Patents

- Su Jin Kim, Alexander H. Slocum, Benjamin B. Scott,, “A miniature kinematic coupling device for mouse head fixation,” *Journal of Neuroscience Methods*, Volume 372, 2022, <https://doi.org/10.1016/j.jneumeth.2022.109549>.
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- Oeding JF, Bockman S, Chiu H, Hua C, Connor J, Slocum A. “A Novel Approach to Open Reduction and Internal Fixation of Distal Radius Fractures Utilizing a Multi-Degree-of-Freedom Traction and Stabilization Device.” *J Med Device*. 2022 Jun 1;16(2):021006. doi: 10.1115/1.4052901. Epub 2022 Feb 3. PMID: 35284034; PMCID: PMC8905091.
- M. Das *et al.*, “A Low-Cost, Easily Deployable Vesicovaginal Fistula Occluding Device for Providing Interim Continence,” *Journal of Medical Devices*, vol. 16, no. 2, Mar. 2022, doi: [10.1115/1.4053603](https://doi.org/10.1115/1.4053603).
- J. Shen *et al.*, “Noninvasive Method and Metric for Monitoring Lung Condition,” in *2021 43rd Annual International Conference of the IEEE Engineering in Medicine & Biology Society (EMBC)*, Nov. 2021, pp. 6841–6844. doi: [10.1109/EMBC46164.2021.9630839](https://doi.org/10.1109/EMBC46164.2021.9630839).
- US10925655 Alexander Slocum, James Connor Jr., Jacob Mooney, NicholasWing-PingKwok , “Bone Reduction Forceps”, 02/23/2021

2.75 Outcomes: Papers, Patents

- Aggarwal, N. , Cavuto, M.L., Lia, M., Rodman, N.H., Slocum, A.H., Jee, K.W., Lub, H., “Design of a compact proton beam energy modulator for imaging”, Nuclear Instruments and Methods in Physics Research Section A: Accelerators, Spectrometers, Detectors and Associated Equipment, Vol. 955, 1 March 2020, 163269
<https://doi.org/10.1016/j.nima.2019.163269>
- M. Whalen *et al.*, “Device Prototype for Vaginal Delivery of Extremely Preterm Fetuses in the Breech Presentation,” *Journal of Medical Devices*, vol. 15, no. 021002, Dec. 2020, doi: [10.1115/1.4049086](https://doi.org/10.1115/1.4049086).
- S. Grown-Haeberli *et al.*, “Design and Applicability of a Mechanical Impedance Sensor for Vein Penetration Detection,” in *2020 42nd Annual International Conference of the IEEE Engineering in Medicine Biology Society (EMBC)*, Jul. 2020, pp. 4016–4019. doi: [10.1109/EMBC44109.2020.9175501](https://doi.org/10.1109/EMBC44109.2020.9175501).
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<https://doi.org/10.1115/1.4044402>.
- R. Singh *et al.*, “Noninvasive Assessment of Jugular Venous Pressure via Force-Coupled Single Crystal Ultrasound,” *IEEE Transactions on Biomedical Engineering*, vol. 65, no. 8, pp. 1705–1710, Aug. 2018, doi: [10.1109/TBME.2017.2767828](https://doi.org/10.1109/TBME.2017.2767828).
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2.75 Outcomes: Papers, Patents

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- Cervantes, T.M., E.K. Summers, R. Batzera, C. Simpson, R. Lewis, N.N. Dhanani, A.H. Slocum, “Evaluation of a Minimally Invasive Renal Cooling Device Using Heat Transfer Analysis and an *in vivo* Porcine Model,” *Medical Engineering & Physics*, Vol. 35(6), June 2013; dx.doi.org/10.1016/j.medengphy.2012.08.001; pp. 736-742.
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- *Begg, N.D., Slocum, A.H., “Audible Frequency Vibration of Puncture-Access Medical Devices,” *Medical Engineering & Physics*, 36 (2014) 371-377.

2.75 Outcomes: Papers, Patents

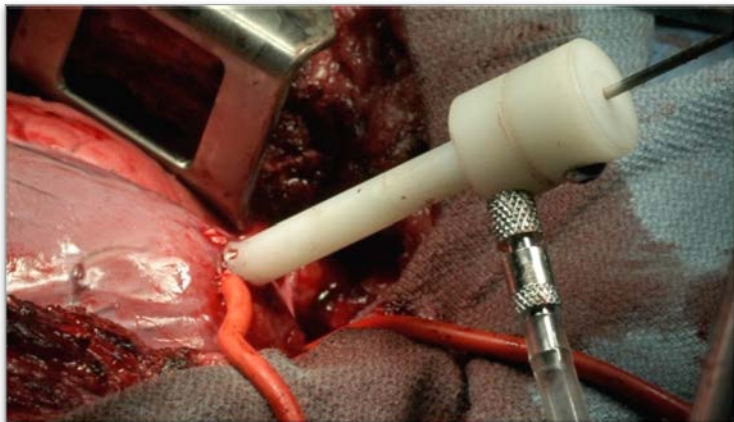
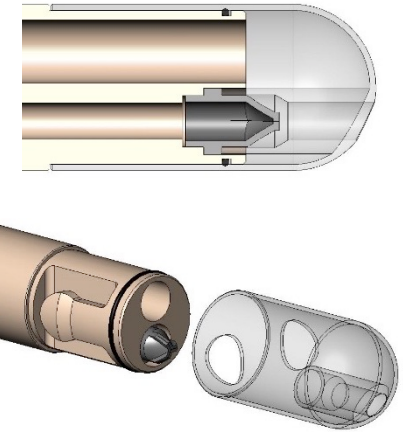
- Hanumara, N.C., A.H. Slocum, T. Mitamura, “Design of a Spherically Actuated Human Interaction Robot Head”, ASME Jou. Mech. Des., May 2012, Vol. 134
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- Vasilyev, N.V., M. Kawata, C. M. DiBiasio, K.V. Durand, J. Hopkins, Z. Traina, A.H. Slocum, P. J. del Nido, “A novel cardioport for beating-heart, image-guided intracardiac surgery”, J Thorac Cardiovasc Surg. 2011 Dec;142(6):1545-51, <https://www.ncbi.nlm.nih.gov/pubmed/21855093#>
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2.75 Products: CardioPort (2005)



I need a device to enable minimally invasive access to a beating heart that:

- Allows an exchange of tools
 - Maintains an airtight seal
 - Causes no bleeding or damage
- Dr. Pedro Del Nido, Boston Children's



Early proto
Testing in an
animal model

Gen 2 device designed

2017 – \$1.3 million SBIR + \$1.4 million
from Broadview Ventures

Patent Issued 2013 - [US20090275893A1](#)

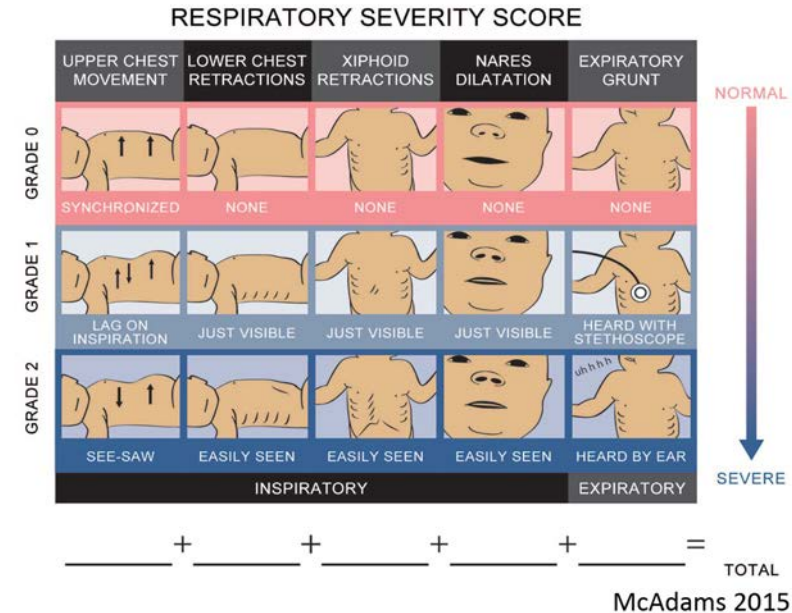
2022 – SEPIA (Solution for Epicardial
Ablation) Acquired by an undisclosed
medical device company

2.75 Products: InSync (2005)

“Assessing the work of breathing in a child in respiratory distress is more art than science.

We can objectively measure the respiratory rate, but the depth of a child's effort is all in the eyes of the beholder.”

- Dr. Ryan Carroll, MGH Pediatrics



Current state of the art relies on manual “scoring” infants.

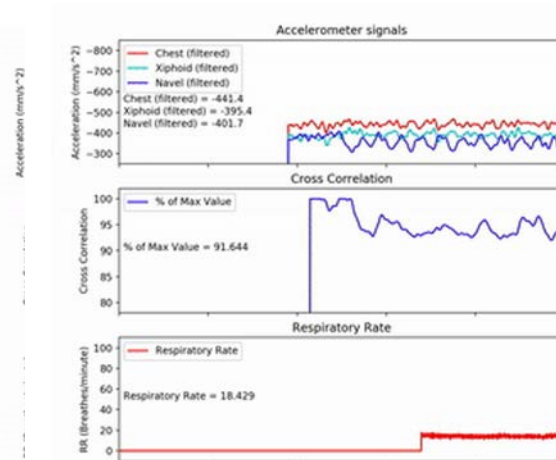
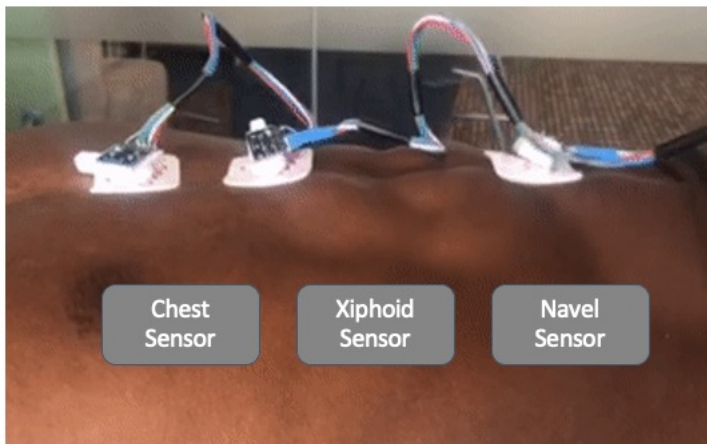
I need a way to measure the work of breathing in neonates that:

- Provides real-time information
- Is non-invasive & continuous
- Alerts at the onset of decline

Taking the **guesswork** out of respiratory care.

DISATI

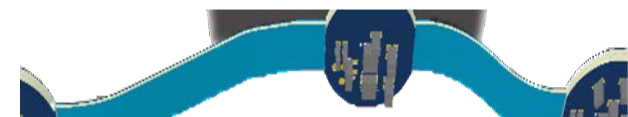
Identified the key physiological signature: See-saw chest motion
Developed novel 3 sensor package and monitoring algorithm



InSync has the potential to reduce the need for invasive ventilatory support, leading to shorter stays, up to 41%, and cost savings of \$18K/patient.

Patent Pending
[US20220288333A1](#)

Clinical trials ongoing at MGH



2.75 Products: Thor Tourniquet (2013) Traumatic Hemorrhage One-hand Response



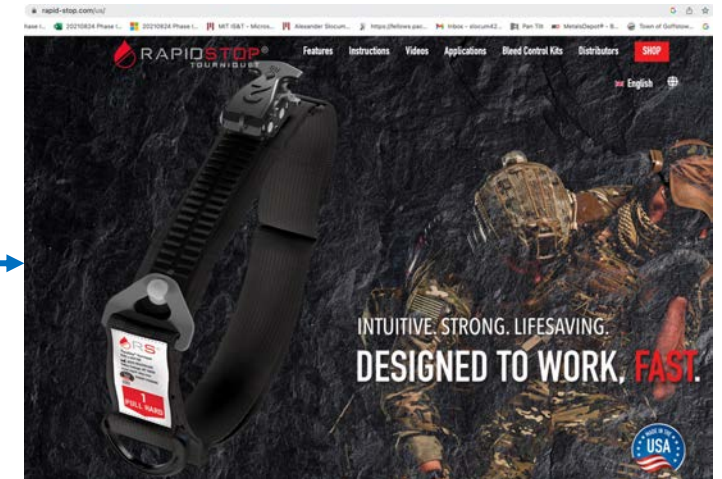
The Boston bombings highlighted the need for an easier to operate, faster to apply more reliable tourniquet.

- Dr. Jay Connor, Mt. Auburn Surgery



2.75 team created a unique one hand operable *Click, Pull & Tighten* design, suitable for use on trapped limbs, and nearly silent during operation.

Patent Issued 2019 - [US10278708B2](https://www.uspto.gov/patent/publications/details/us10278708B2)

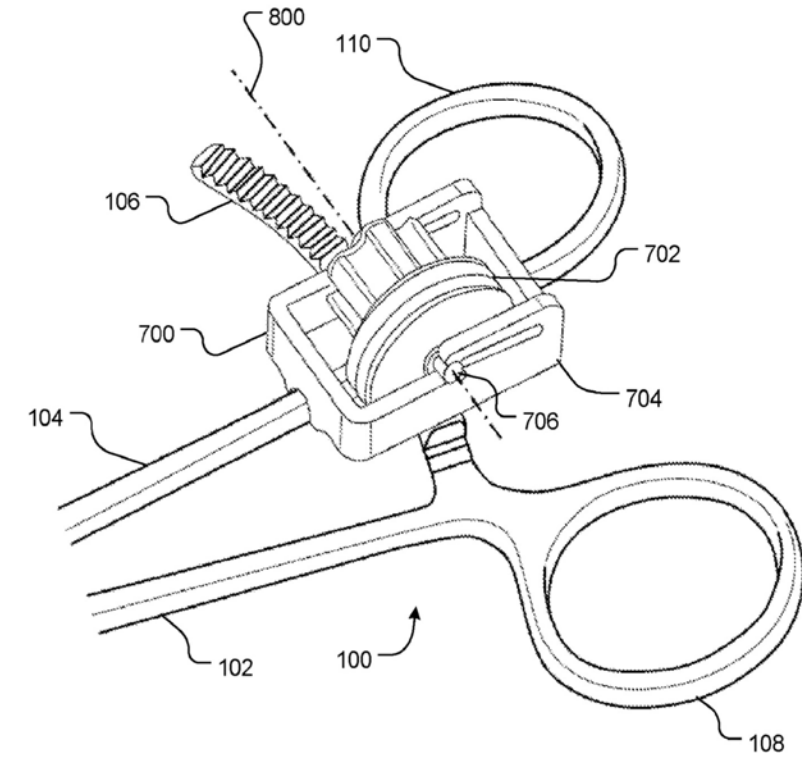


2022 – Available from
<https://rapid-stop.com/us/>



2.75 Products: RollForce Clamp

- Bone reduction forceps with continuously adjustable force
 - Product in development for release 2024
 - NewCo being started by doctors and Prof. Slocum to bring 2.75 concept to hands of surgeons



(12) **United States Patent**
Slocum et al.

(10) **Patent No.:** US 10,925,655 B2
(45) **Date of Patent:** Feb. 23, 2021

(54) **BONE REDUCTION FORCEPS**

(71) Applicant: **Massachusetts Institute of Technology**, Cambridge, MA (US)

(72) Inventors: **Alexander Henry Slocum**, Bow, NH (US); **James Francis Connor, Jr.**, Cambridge, MA (US); **Jacob Alexander Mooney**, Westford, MA (US); **Nicholas Wing-Ping Kwok**, Novato, CA (US)

(73) Assignee: **Massachusetts Institute of Technology**, Cambridge, MA (US)

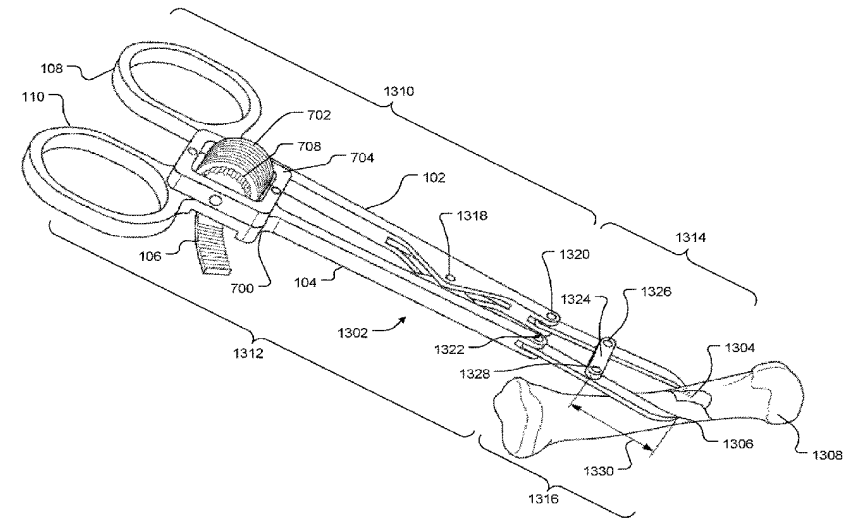
(52) **U.S. Cl.**
CPC *A61B 17/8866* (2013.01); *A61B 17/2812* (2013.01); *A61B 2017/00407* (2013.01); *A61B 2017/2837* (2013.01)

(58) **Field of Classification Search**
USPC 606/324–328, 151, 157, 51–52, 205–211
See application file for complete search history.

(56) **References Cited**

U.S. PATENT DOCUMENTS

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8,529,575 B2 9/2013 Tsai et al.
(Continued)



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The Teaching Team's Research - Examples

Featuring Prof. Ellen Roche



Alexander Slocum, PhD
Professor
Mechanical Engineering
Precision Machine
Design Guru



Gio Traverso, MD
Professor
Mechanical Engineering
Gastroenterologist
Brigham & Women's



Ellen Roche, PhD
Professor
Institute for Medical
Engineering & Science
Therapeutic Technology
Design & Development

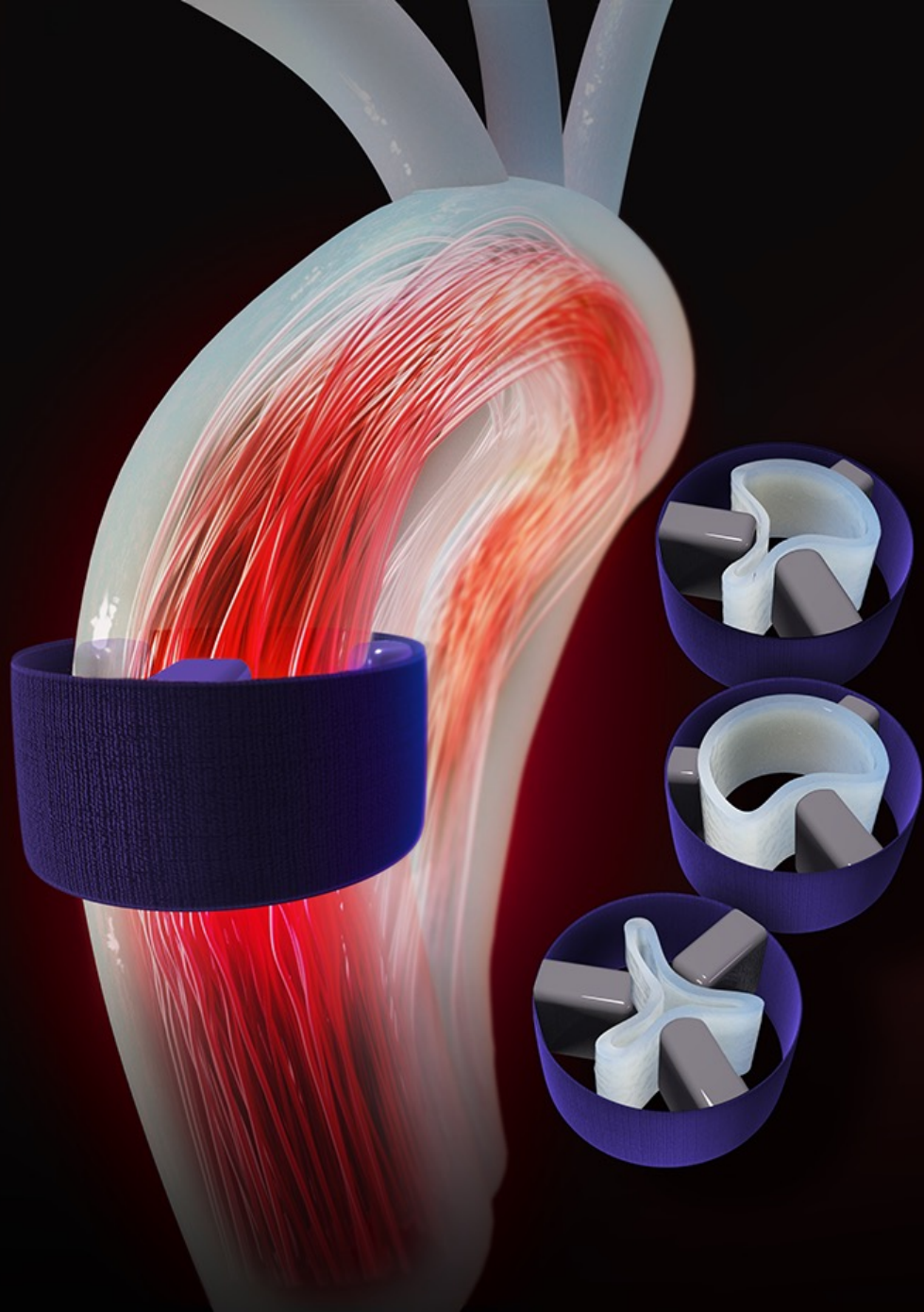


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Research Scientist
Mechanical Engineering
Design, Human Factors,
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Anthony Pennes
Instructor
Electrical Engineering
Electronics Wizard





Superimposing soft active materials with dynamic organs and biological systems

Ellen Roche

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Therapeutic Technology Design
and Development lab

ttdd.mit.edu



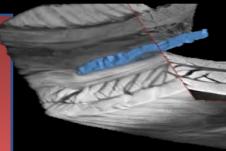
1

Mechanical augmentation of organ/system function



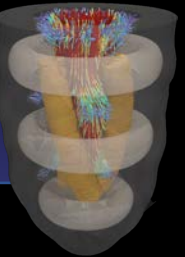
2

Structural/biological repair of tissue



3

Multimodal simulations of biomechanics





***An implantable ventilator
that assists the
diaphragm and mimics
breathing mechanics***

The clinical problem

5x risk of stroke

3. Clot blocks an artery in the brain, causing **STROKE**

2. Blood clot travels in the bloodstream

1. Blood clot can form during atrial fibrillation

Left Atrial Appendage



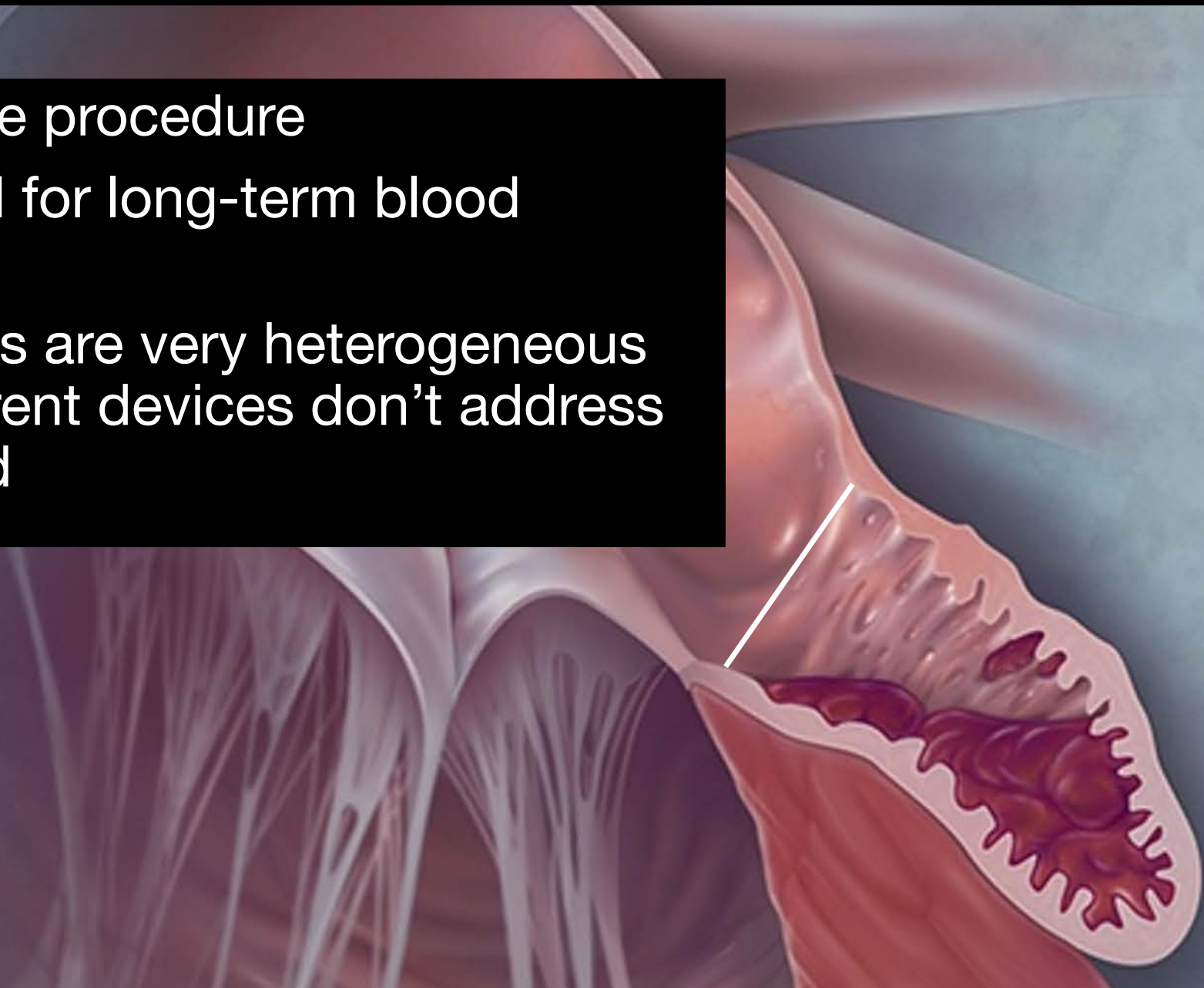
90% of stroke-causing clots originate here

Why?

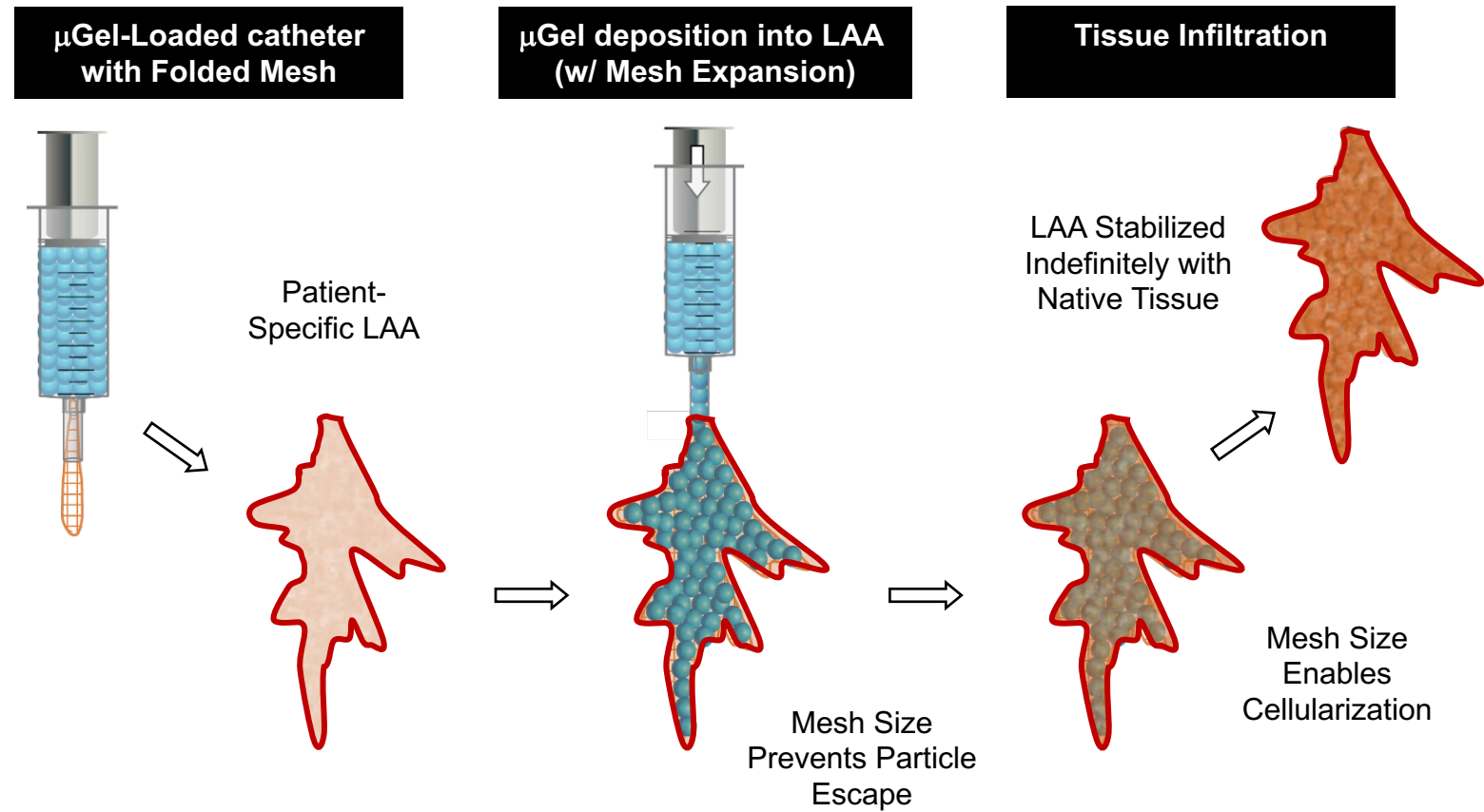
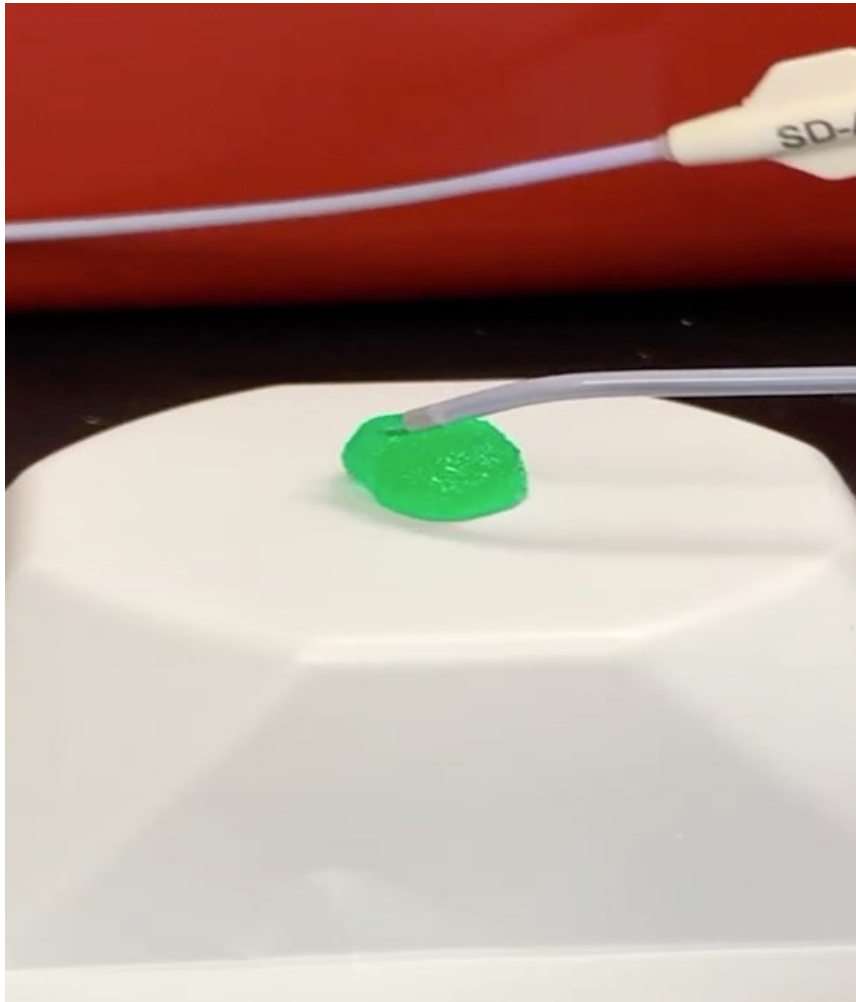
Block the LAA from the bloodflow

- One-time procedure
- No need for long-term blood thinners
- But LAAs are very heterogeneous and current devices don't address the need

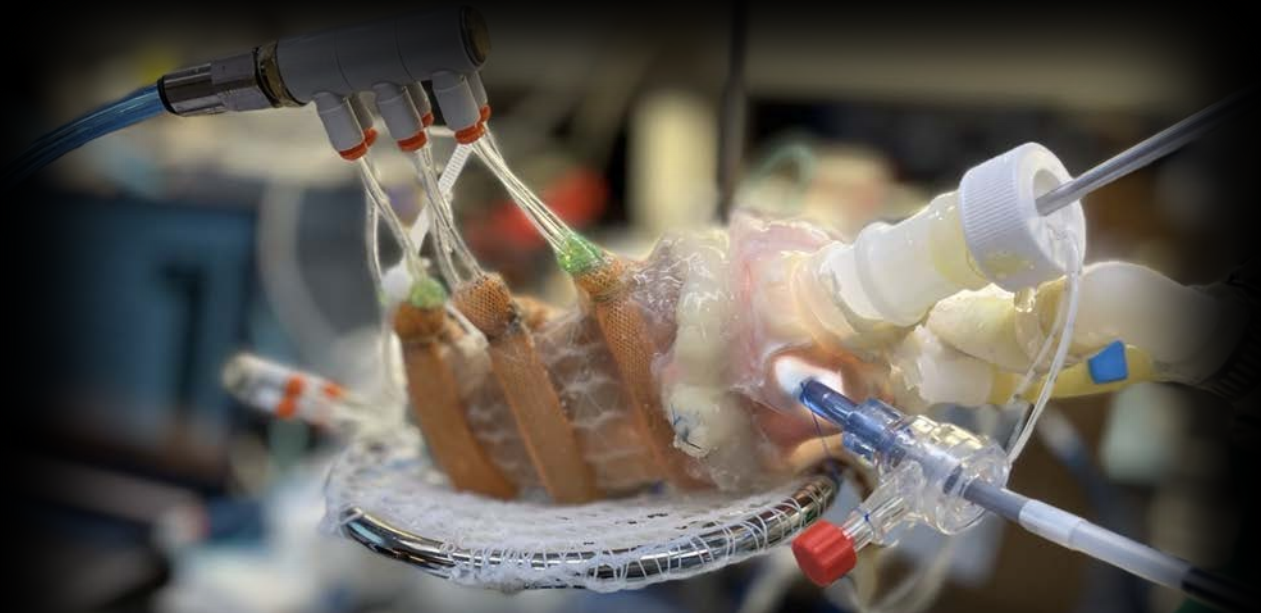
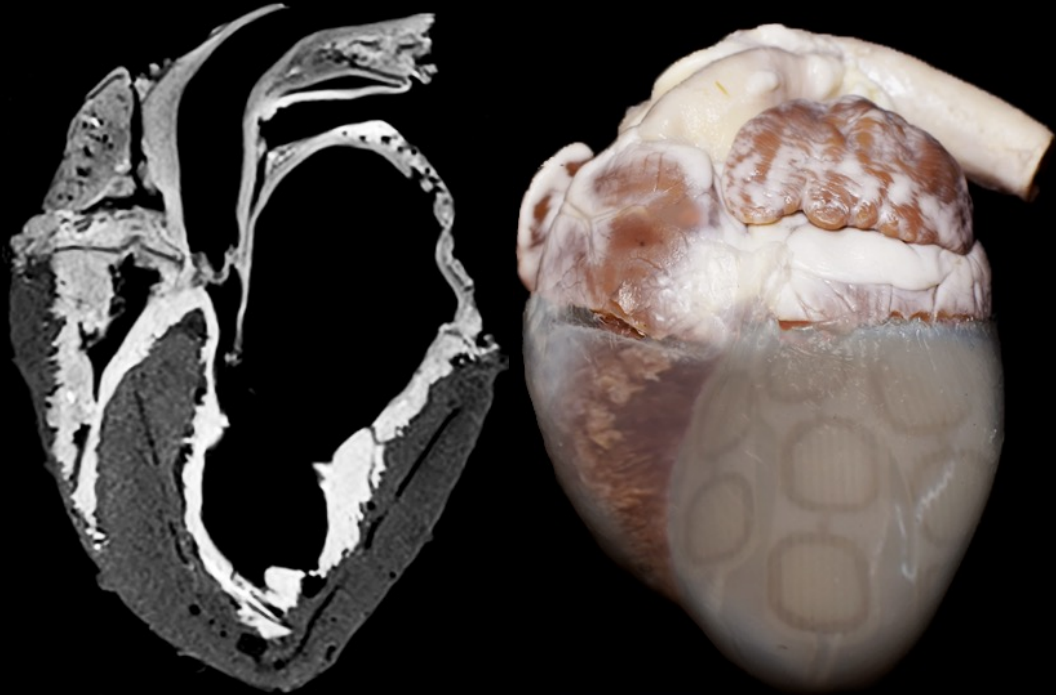
How?



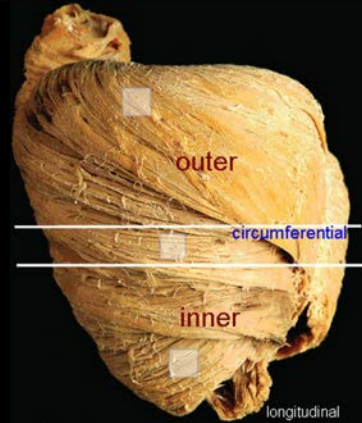
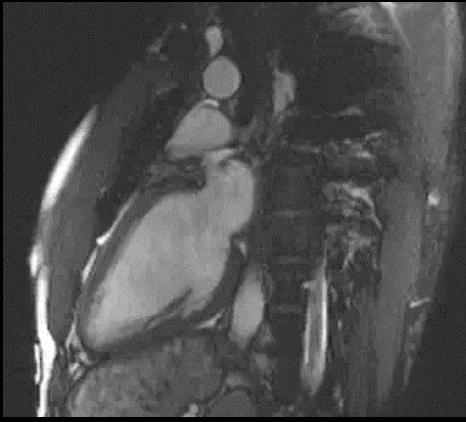
Jamming microgels for space filling and stabilization



Development of a high fidelity cardiovascular *in vitro* simulator

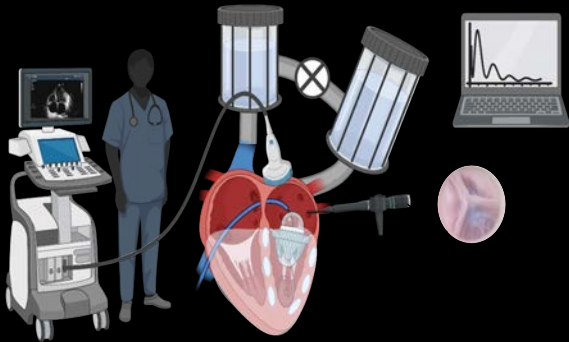


Problem



Difficult to replicate biomechanics and anatomy of the heart for a benchtop testing model

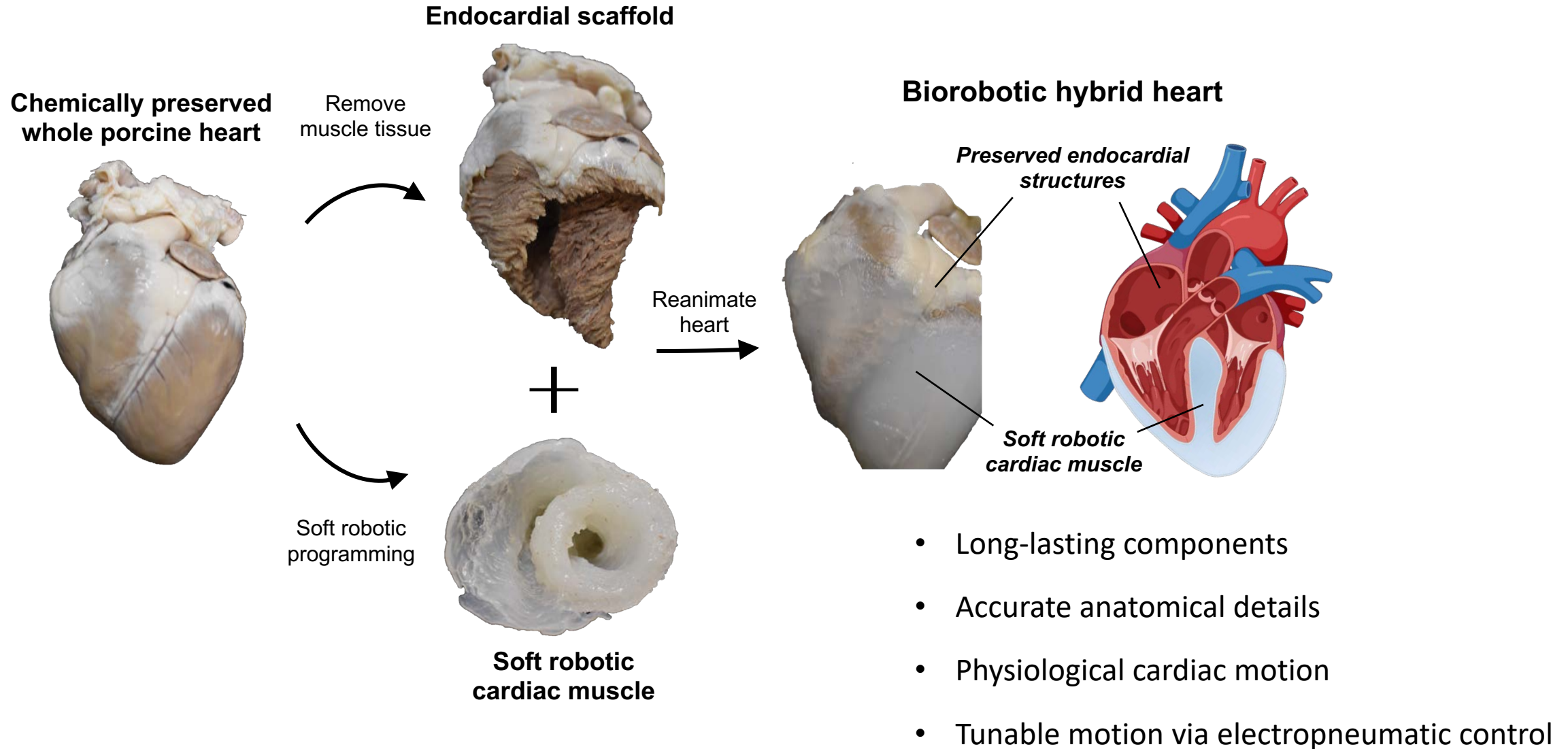
Need



Heart models are either not recapitulating biomechanics or not representing anatomy

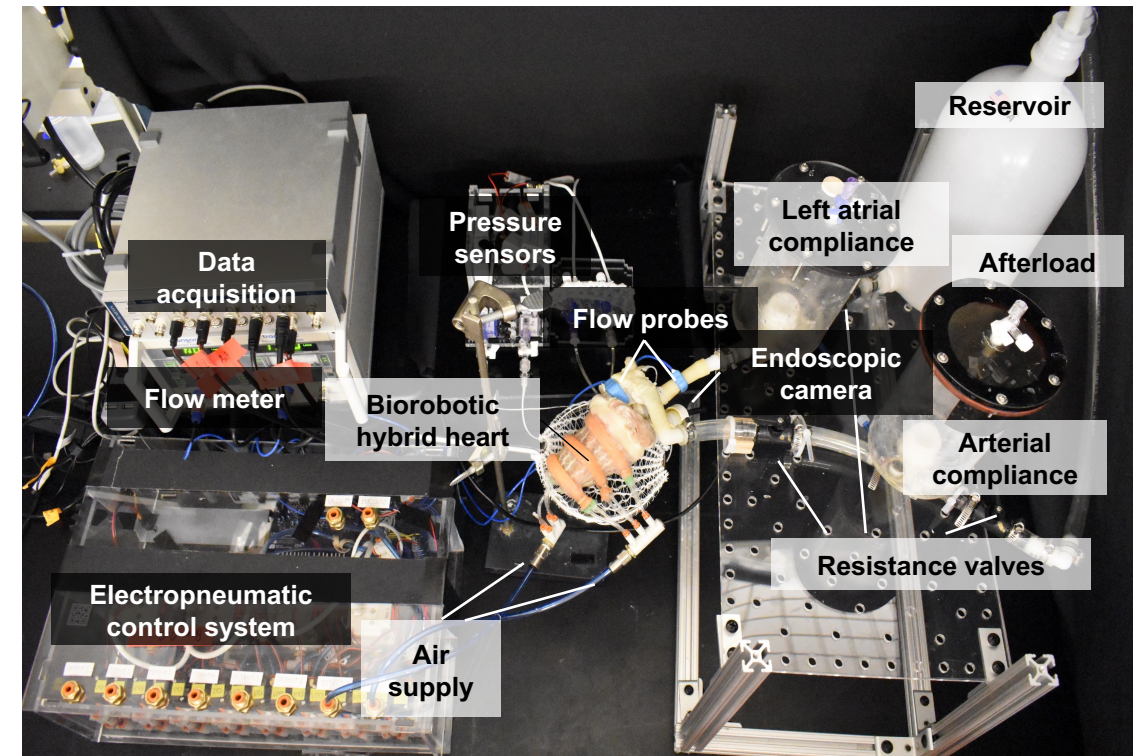
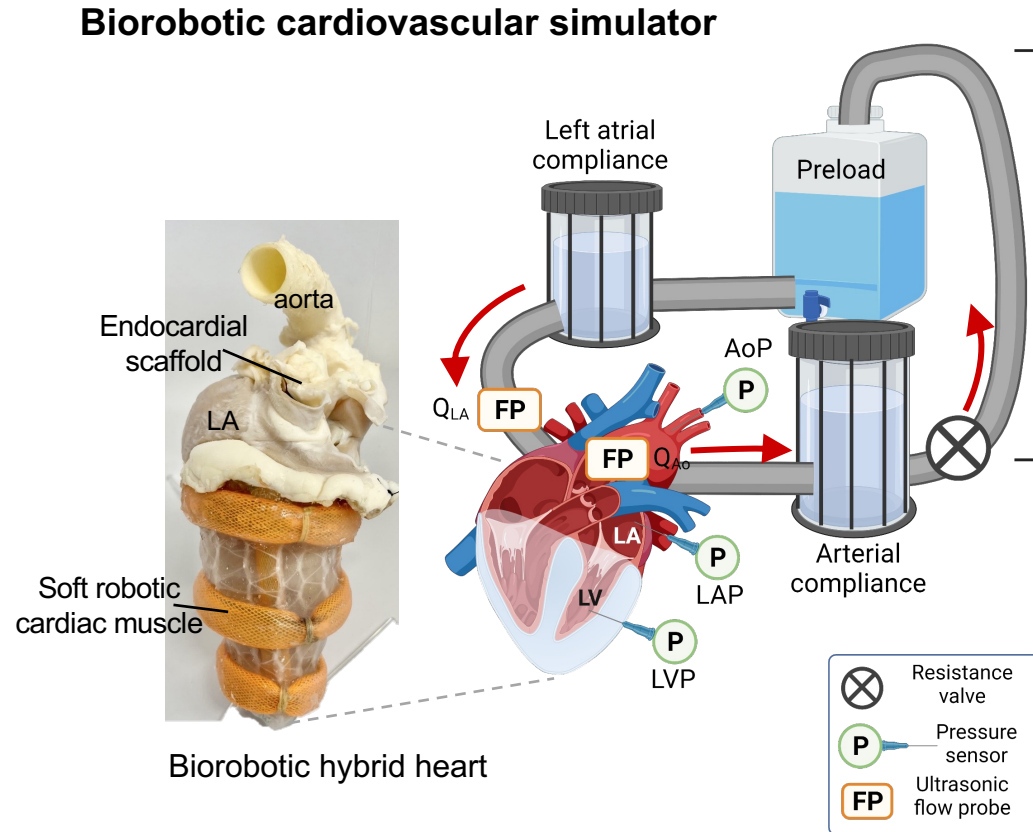
Can we use our soft robotic approaches to enable better benchtop simulators?

Biohybrid approach to replicating the heart



Biorobotic cardiovascular *in vitro* simulator

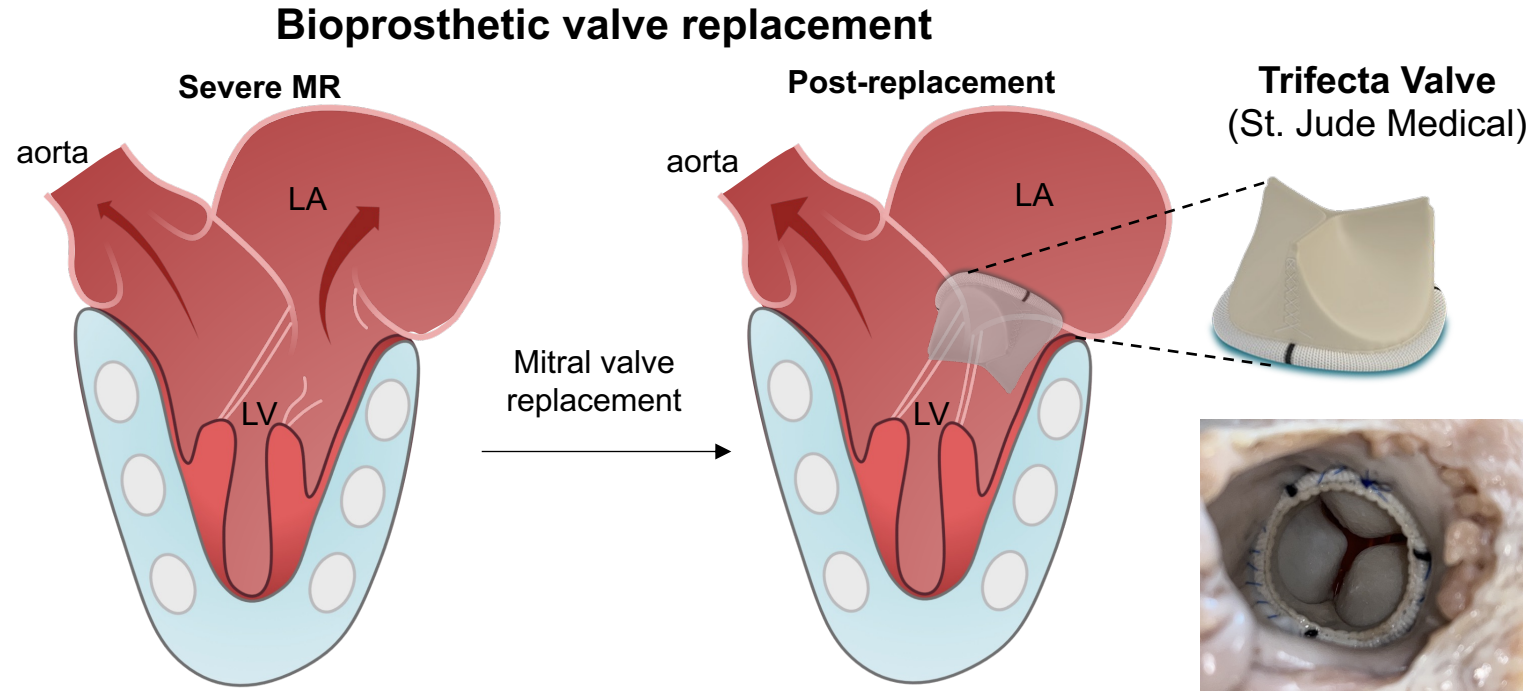
Biorobotic hybrid heart can be assembled with a left heart mock circulatory loop to drive flow



- Obtain real-time hemodynamics
- Directly observe intracardiac motion and device interaction
- Compatible with clinical imaging such as echocardiography

Demonstration of surgical valve replacement

The biorobotic cardiovascular simulator can be used to demonstrate surgical interventions



Featuring Prof. / Dr. Gio Traverso



Alexander Slocum, PhD
Professor
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Precision Machine
Design Guru



Gio Traverso, MD
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Anthony Pennes
Instructor
Electrical Engineering
Electronics Wizard



Device Engineering for Clinical Impact through the GI Tract

Giovanni Traverso

Assistant Professor

Department of Mechanical Engineering, Massachusetts Institute of Technology
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Massachusetts
Institute of
Technology



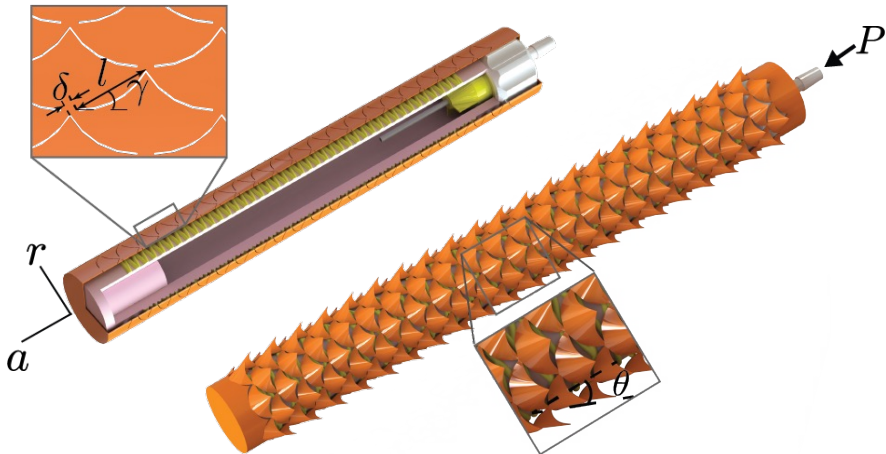
HARVARD
MEDICAL SCHOOL



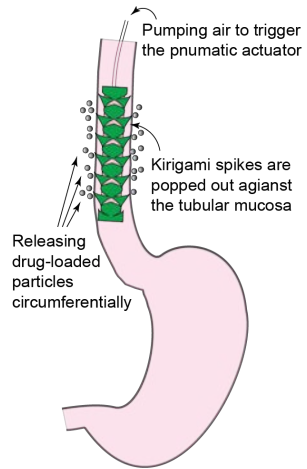
BRIGHAM AND
WOMEN'S HOSPITAL



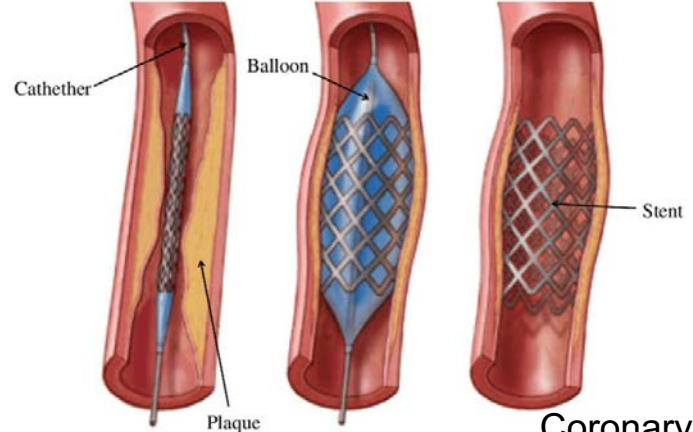
Overview: Kirigami-based stents



Kirigami surface

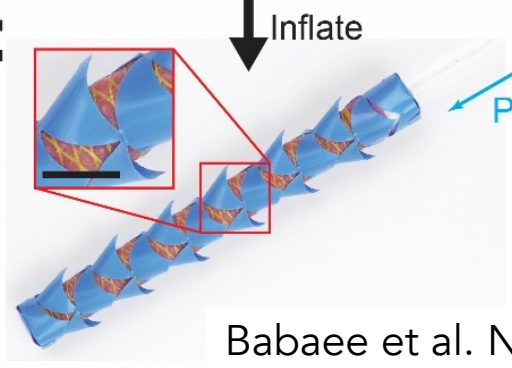
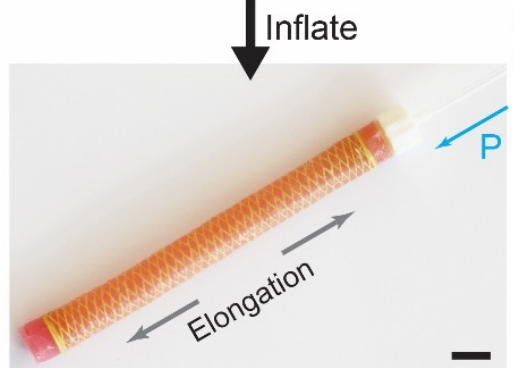
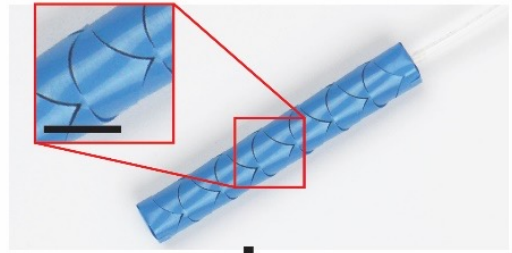
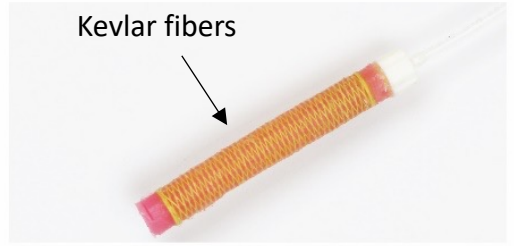
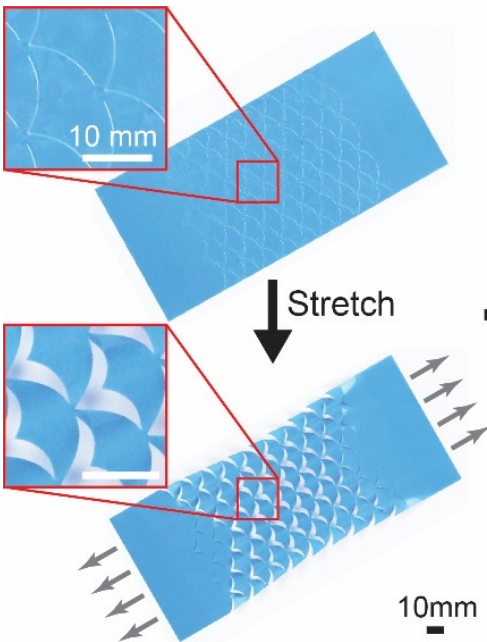


Soft linear actuator



Kirigami stent

Coronary stent



In vivo esophageal delivery

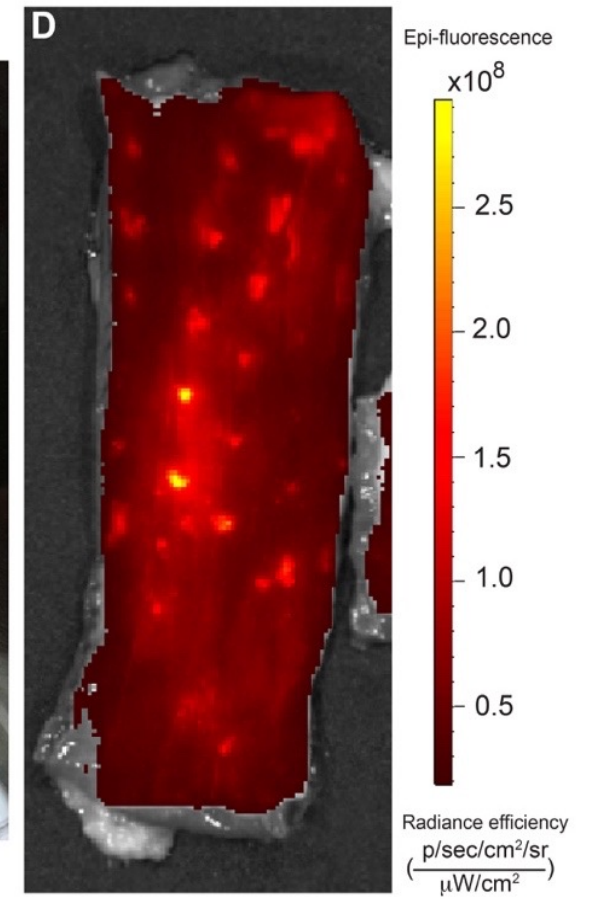
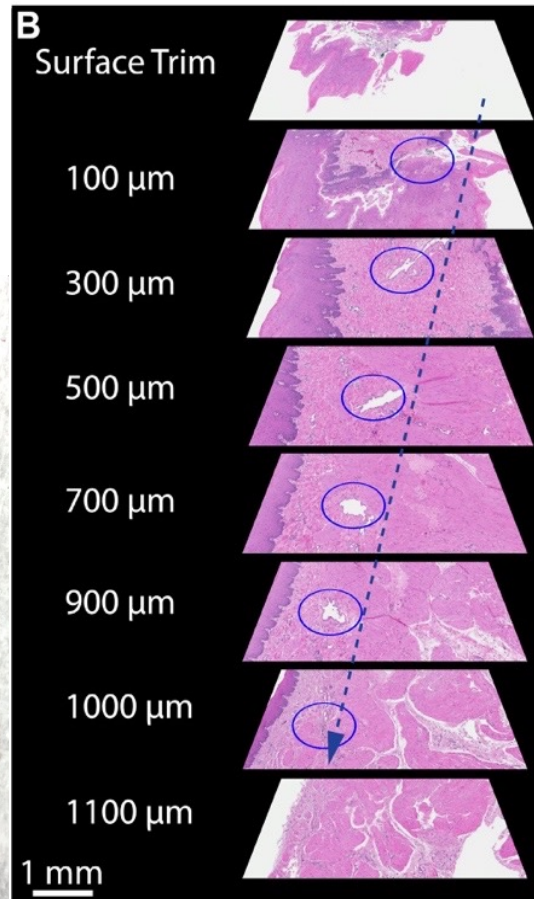
Tissue
Marking
Dye



Placement



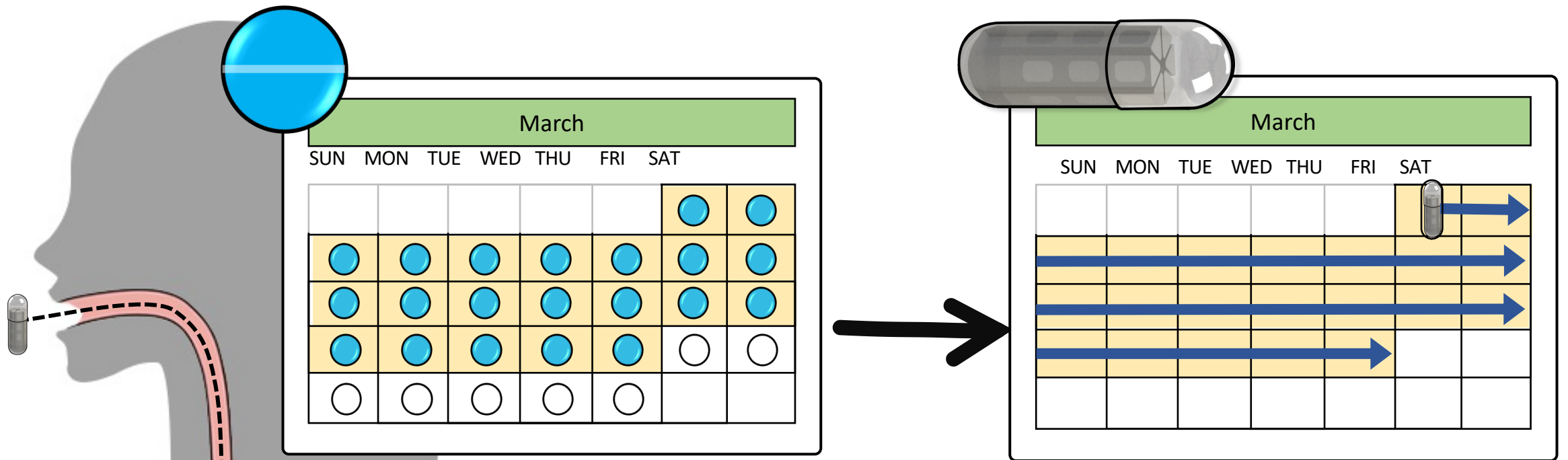
Post-Injection



Fluorescent magnetic microparticles
(1.0% w/v, 4.0-4.9 μm)

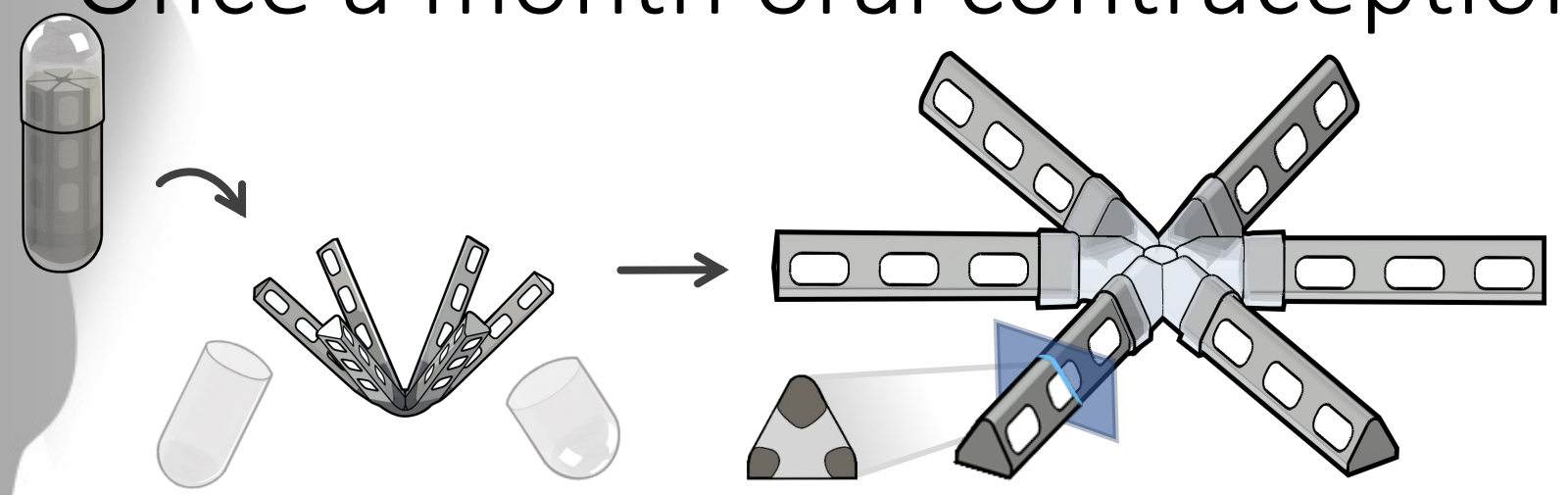
Compliance increases with more infrequent dosing regimens





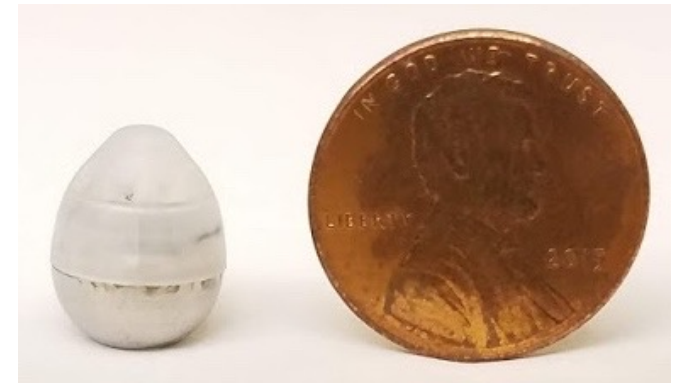
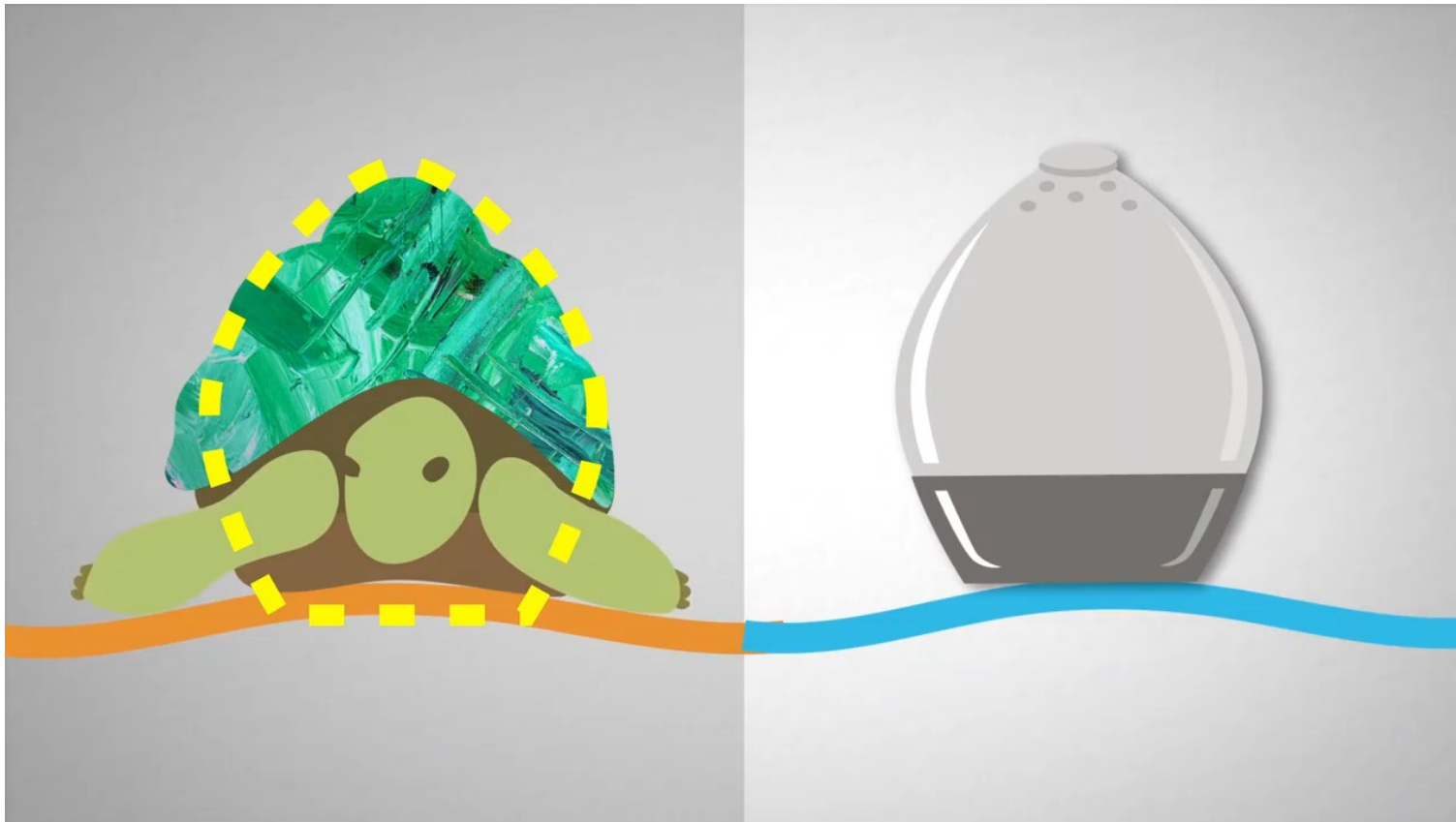
Once a month oral contraception

21 Days



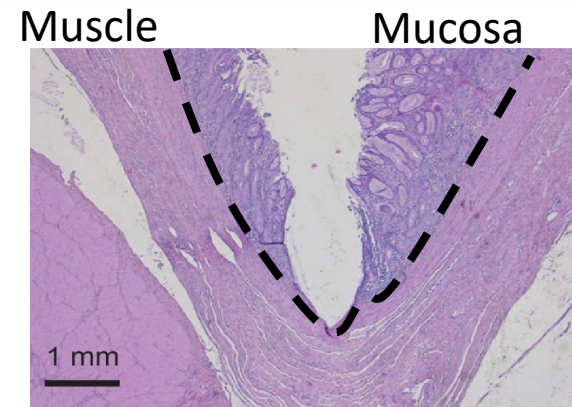
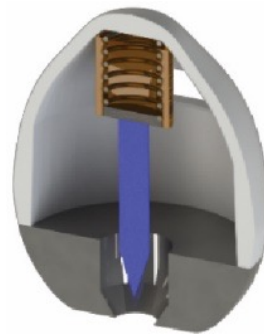
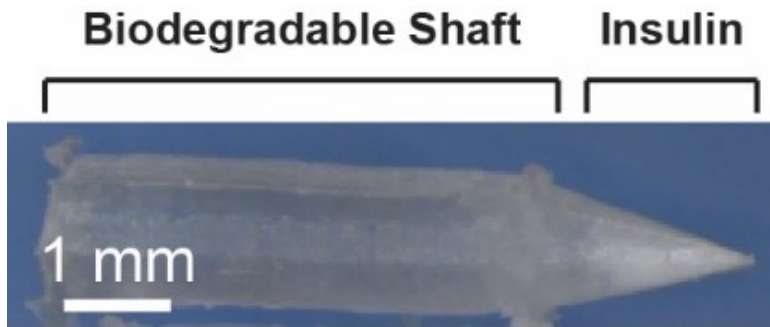
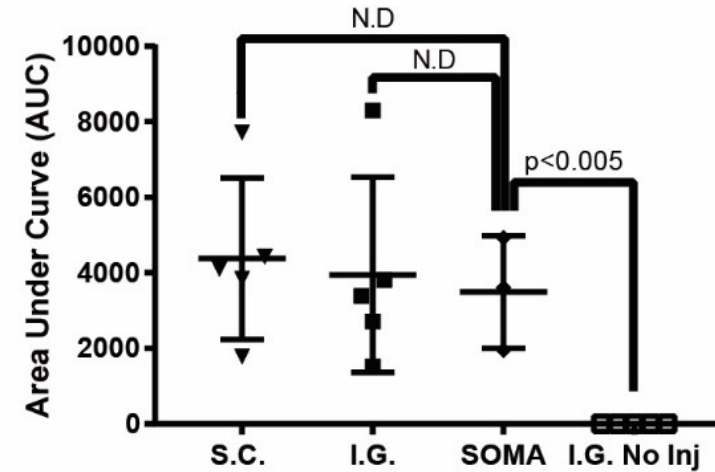
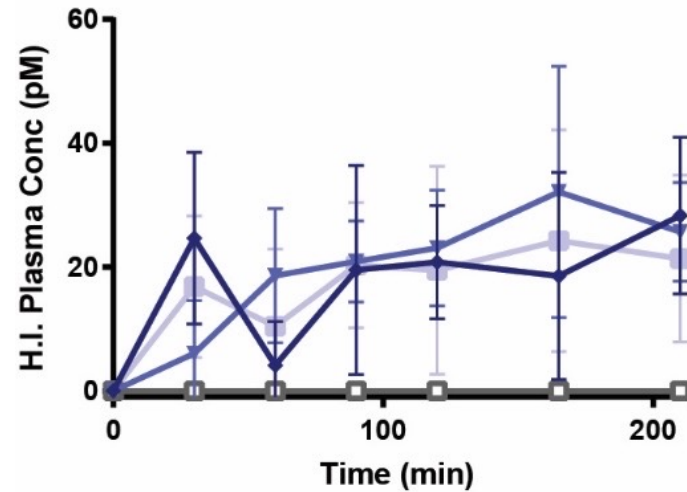
Self-Orienting Millimeter-Scale Injector

Inspired by a tortoise, the Self-Orienting Millimeter-Scale Actuator (SOMA) passively orients an injector towards the stomach wall after ingestion



Actuation and Delivery

A compressed spring encapsulated in sugar drives a needle into tissue once released



Because sugar is brittle, it releases the spring in 1 ms

Abramson et al, Science (2019)

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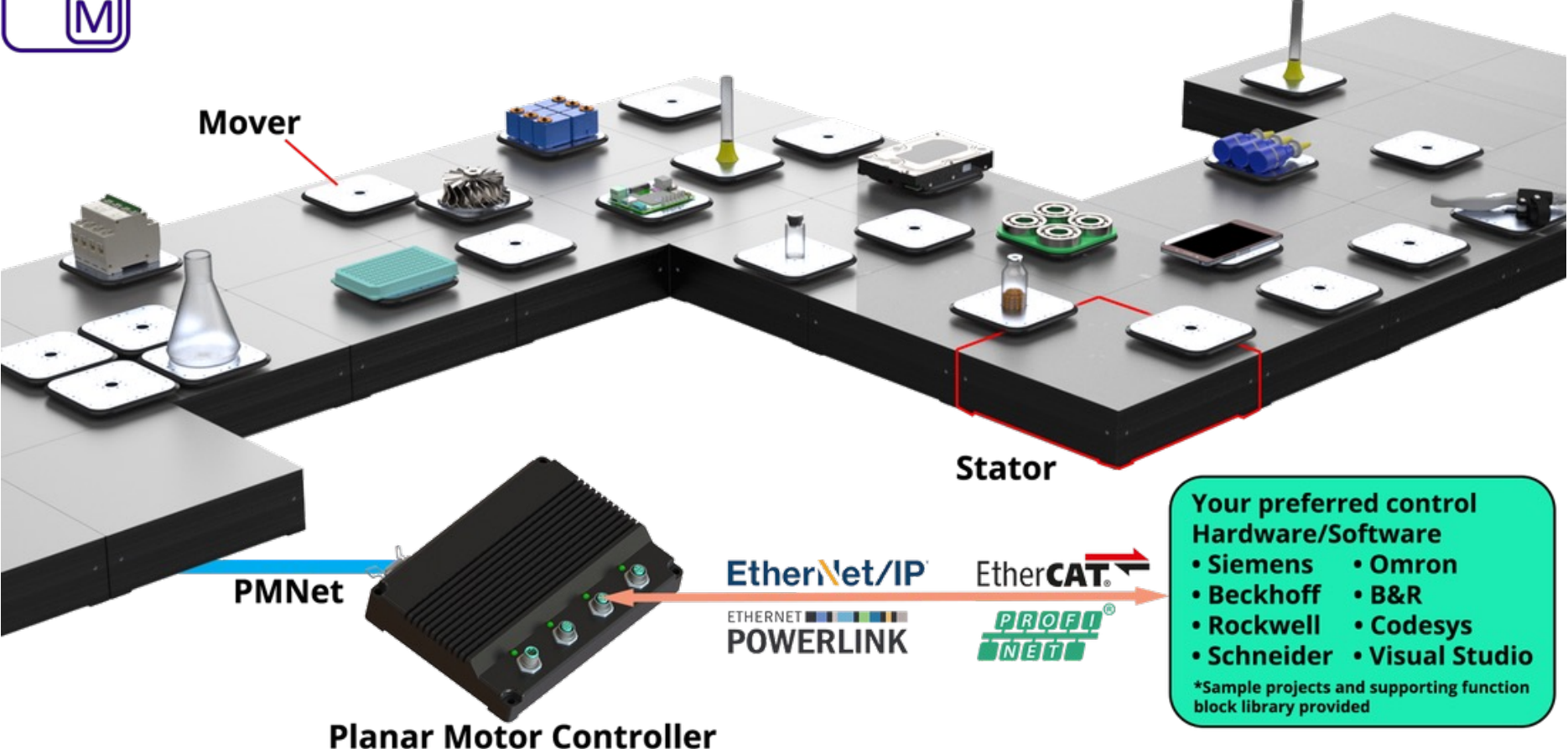
Example: Student research spun off to form enabling technology company

www.planarmotor.com

XBot[®] enables smart manufacturing, with unprecedented flexibility, reliability, agility, and efficiency to enable ultra clean (non-contact motion) fast flexible manufacturing, e.g., pharma manufacturing



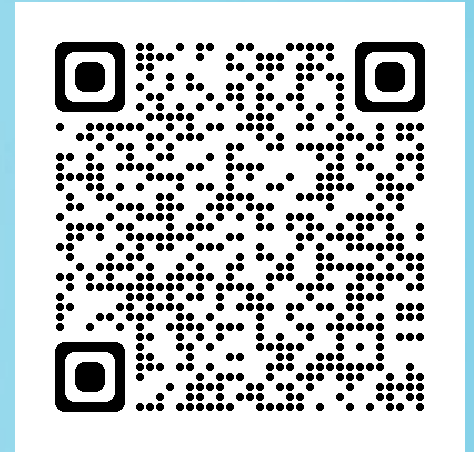
XBot[®]



Example: “LeHit” Ortho medical tool Development

(will be announced mid 2023, sorry cannot say more now)





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