

COMPUTATIONAL MANUFACTURING

Wojciech Matusik
MIT EECS



SEWBO 



Sewbo





Sonova hearing aid

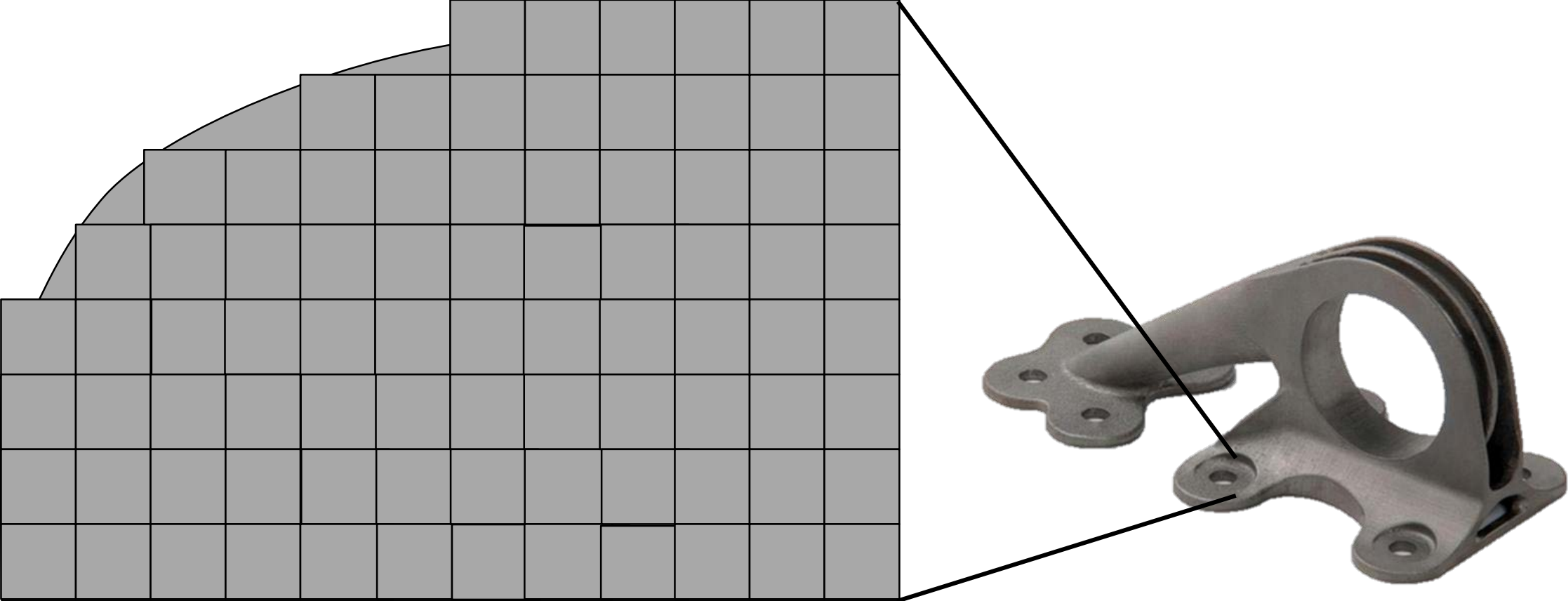


Invisalign braces

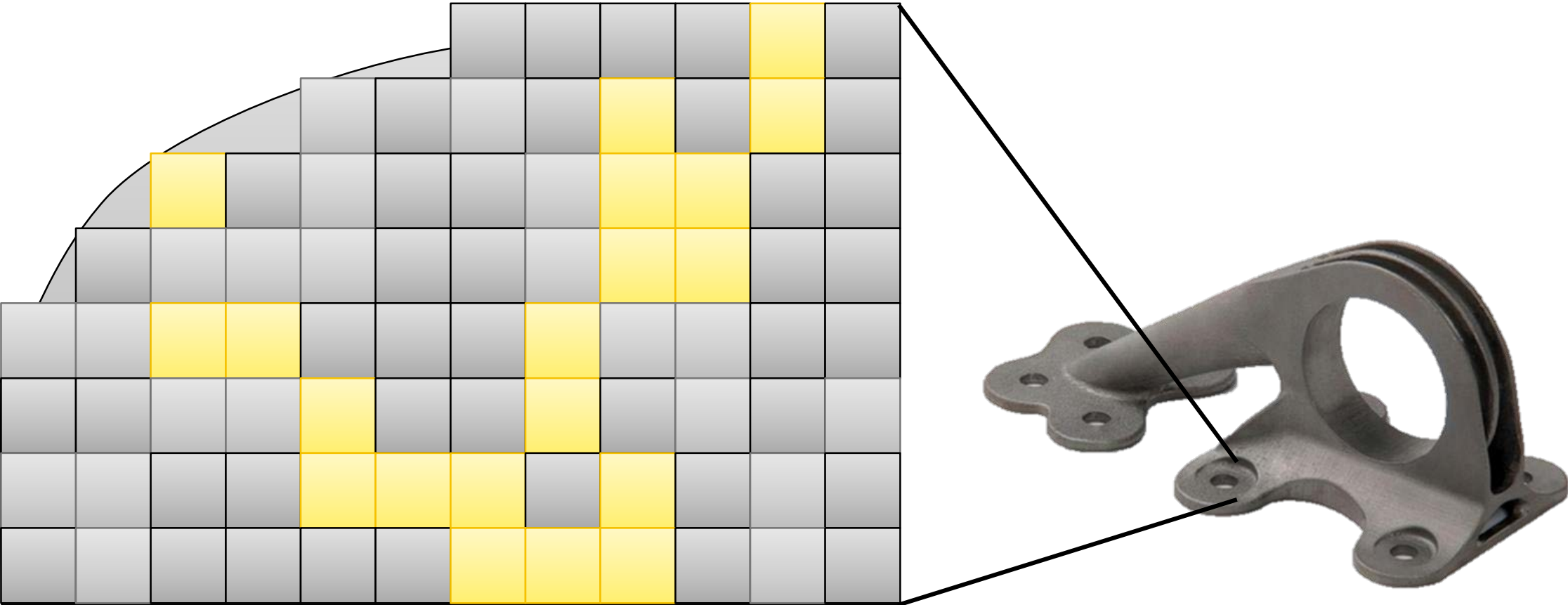


Osteoid cast

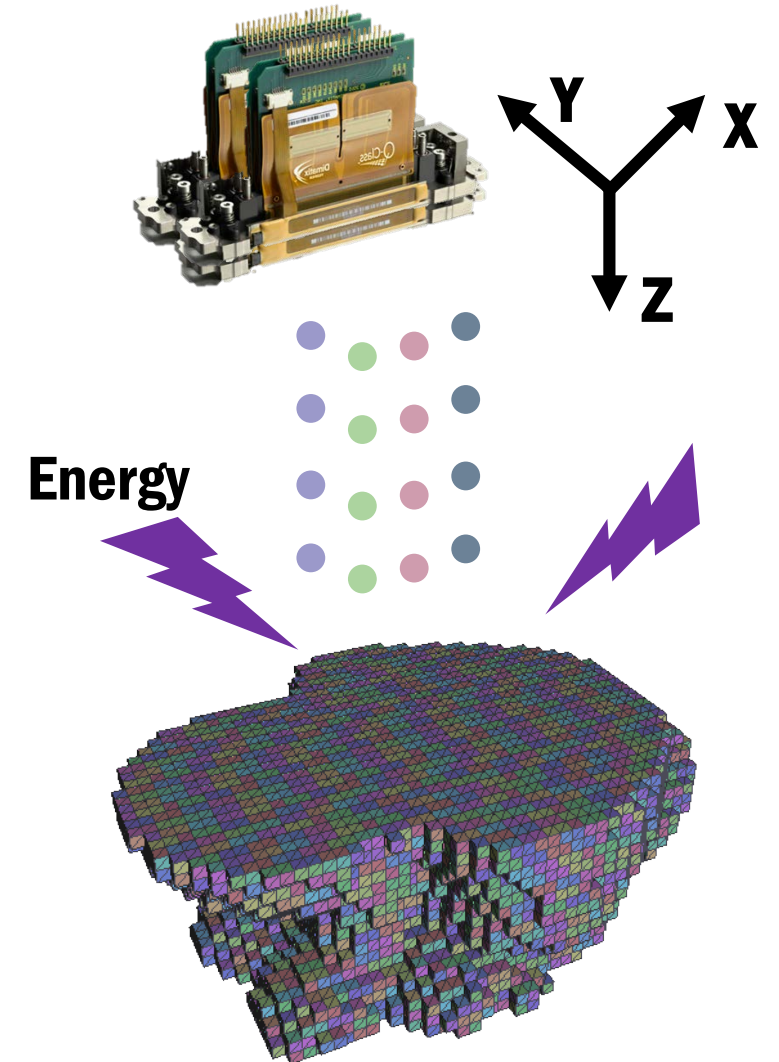
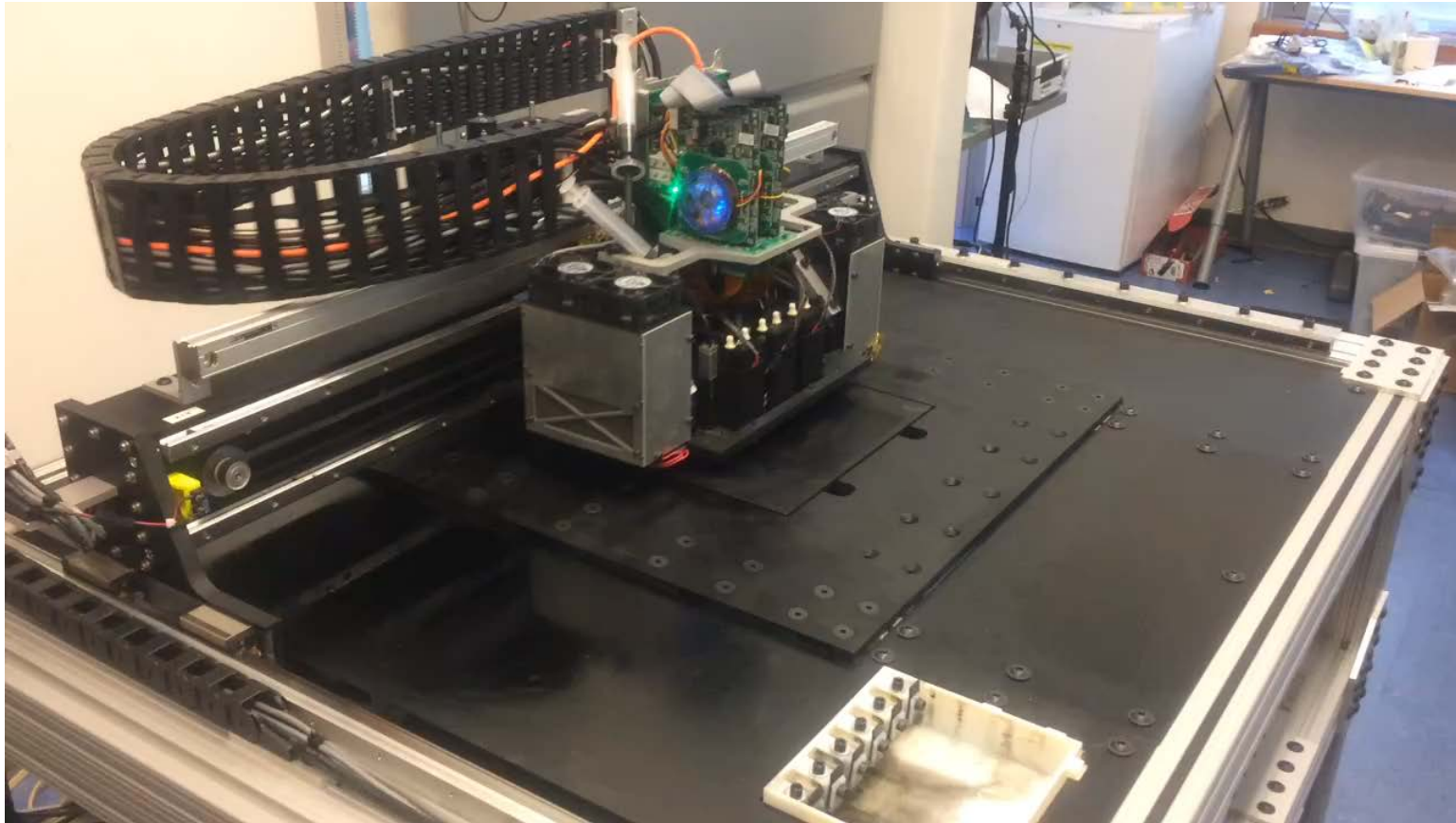
ADDITIVE MANUFACTURING



MULTI-MATERIAL ADDITIVE MANUFACTURING

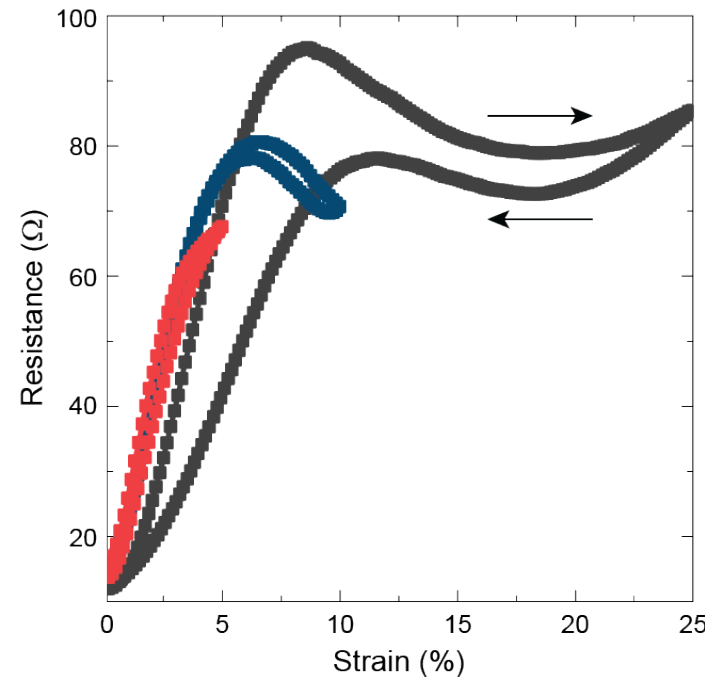
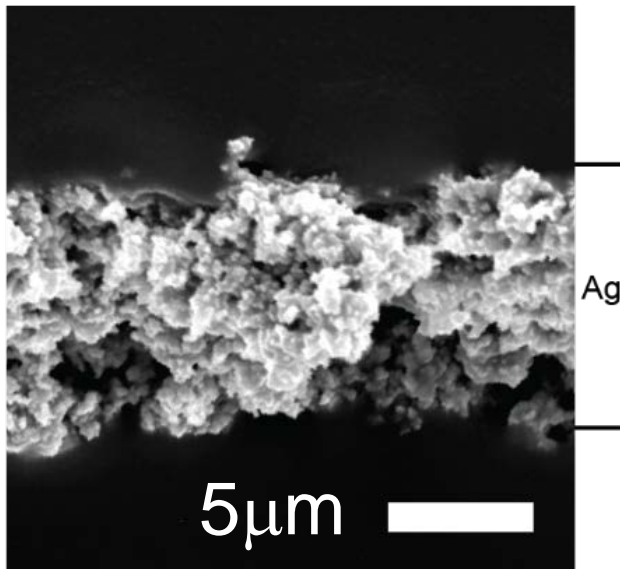
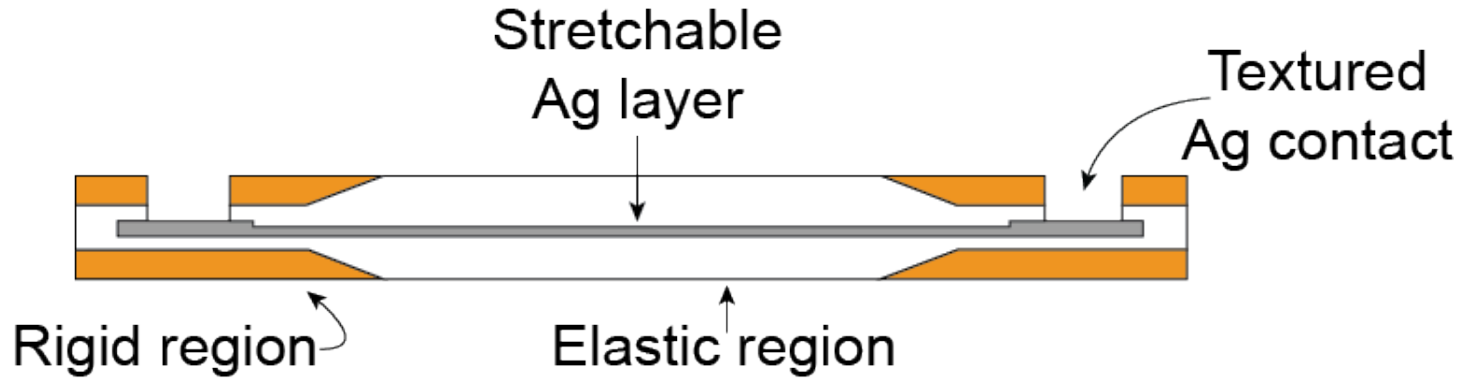


MULTI-MATERIAL ADDITIVE MANUFACTURING



ADVANCED APPLICATIONS FOR MULTI- MATERIAL ADDITIVE MANUFACTURING

STRAIN SENSORS

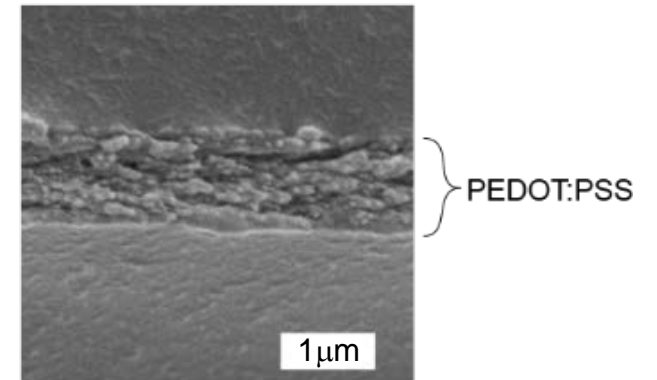
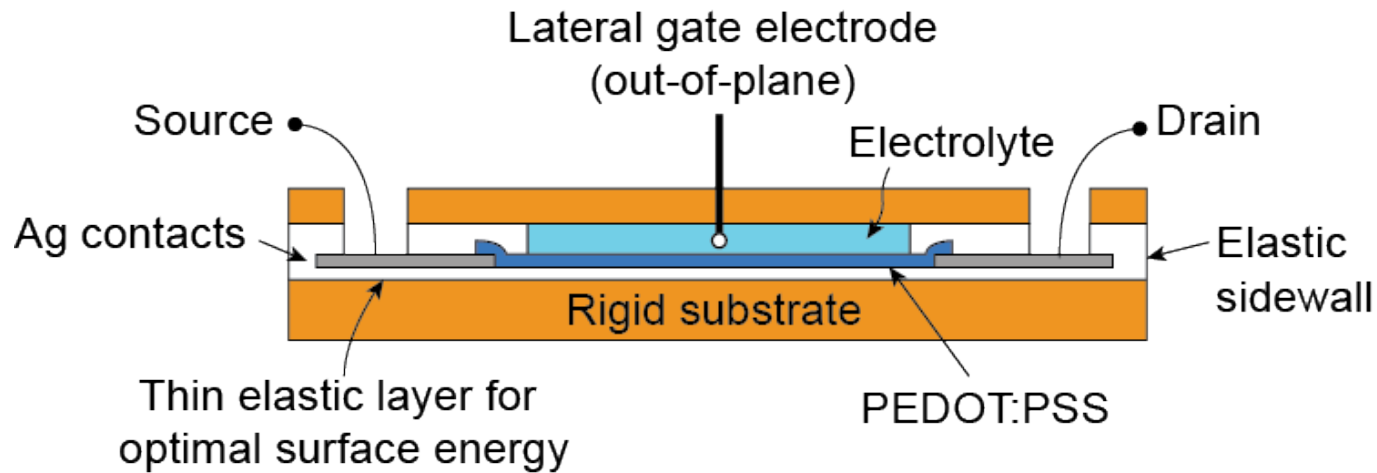


- ✓ Silver in elastic matrix
- ✓ High $\Delta R/R$
- ✓ Repeatable, no drift or offset

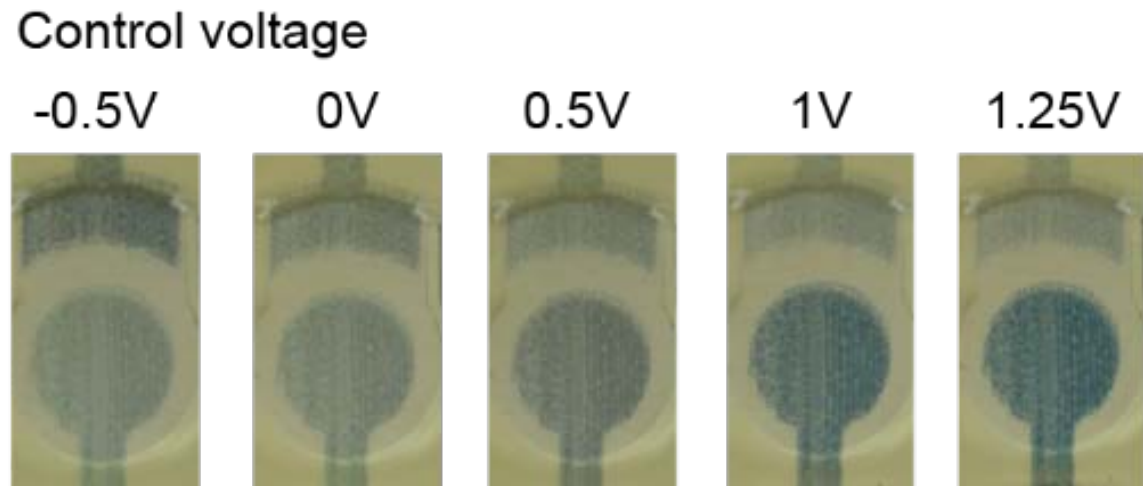
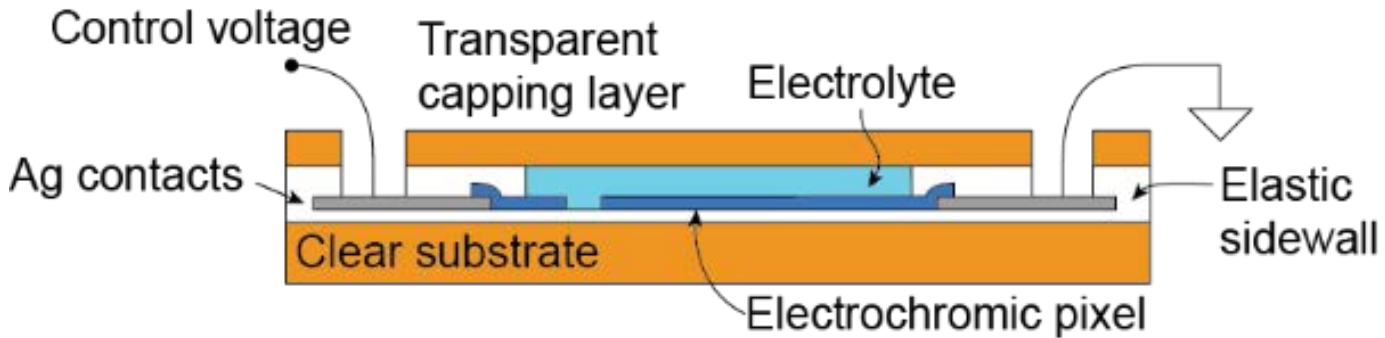
Resistance vs. strain

TRANSISTORS

P-TYPE DEPLETION MODE



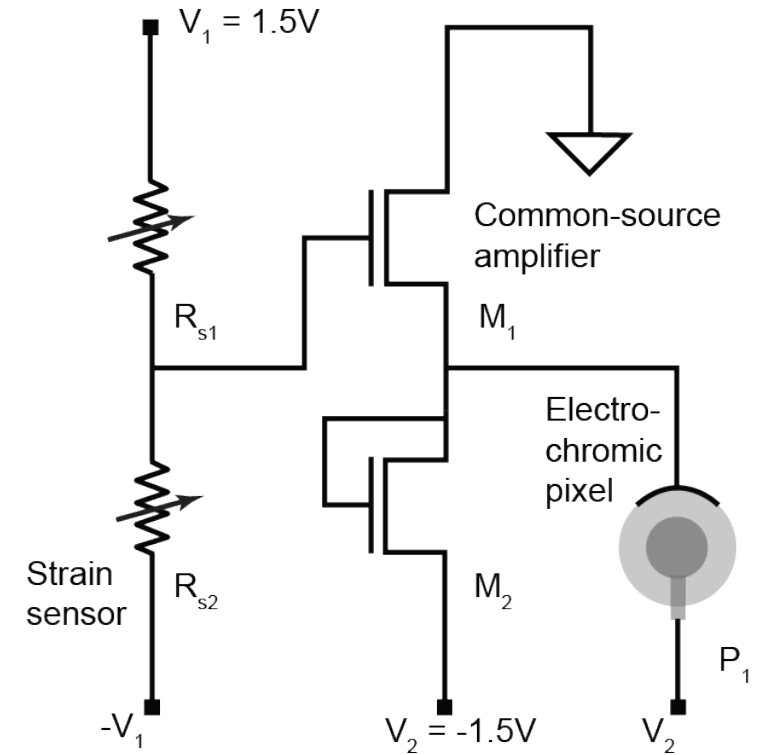
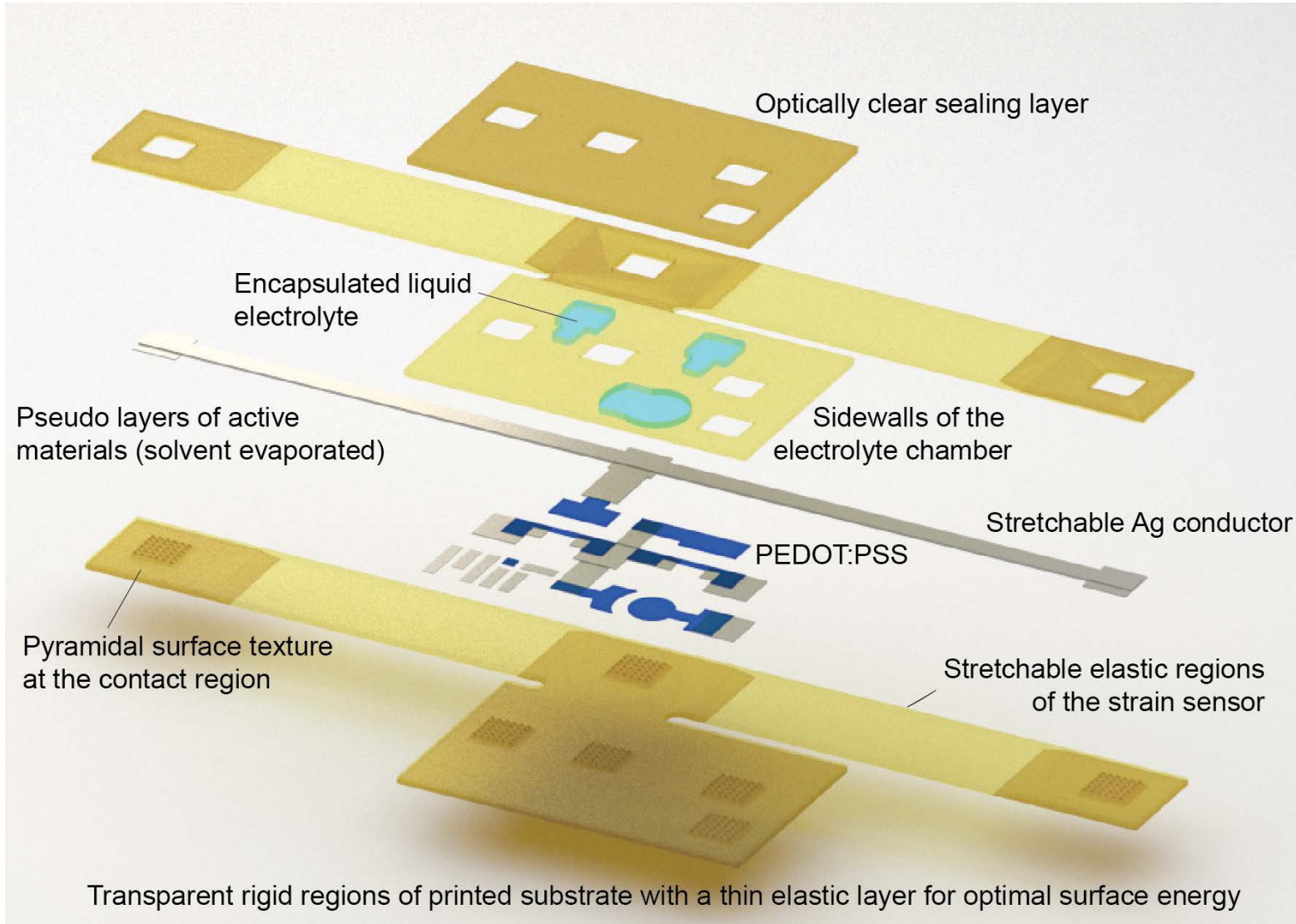
PIXELS



Pixel color - tuning applied control voltage

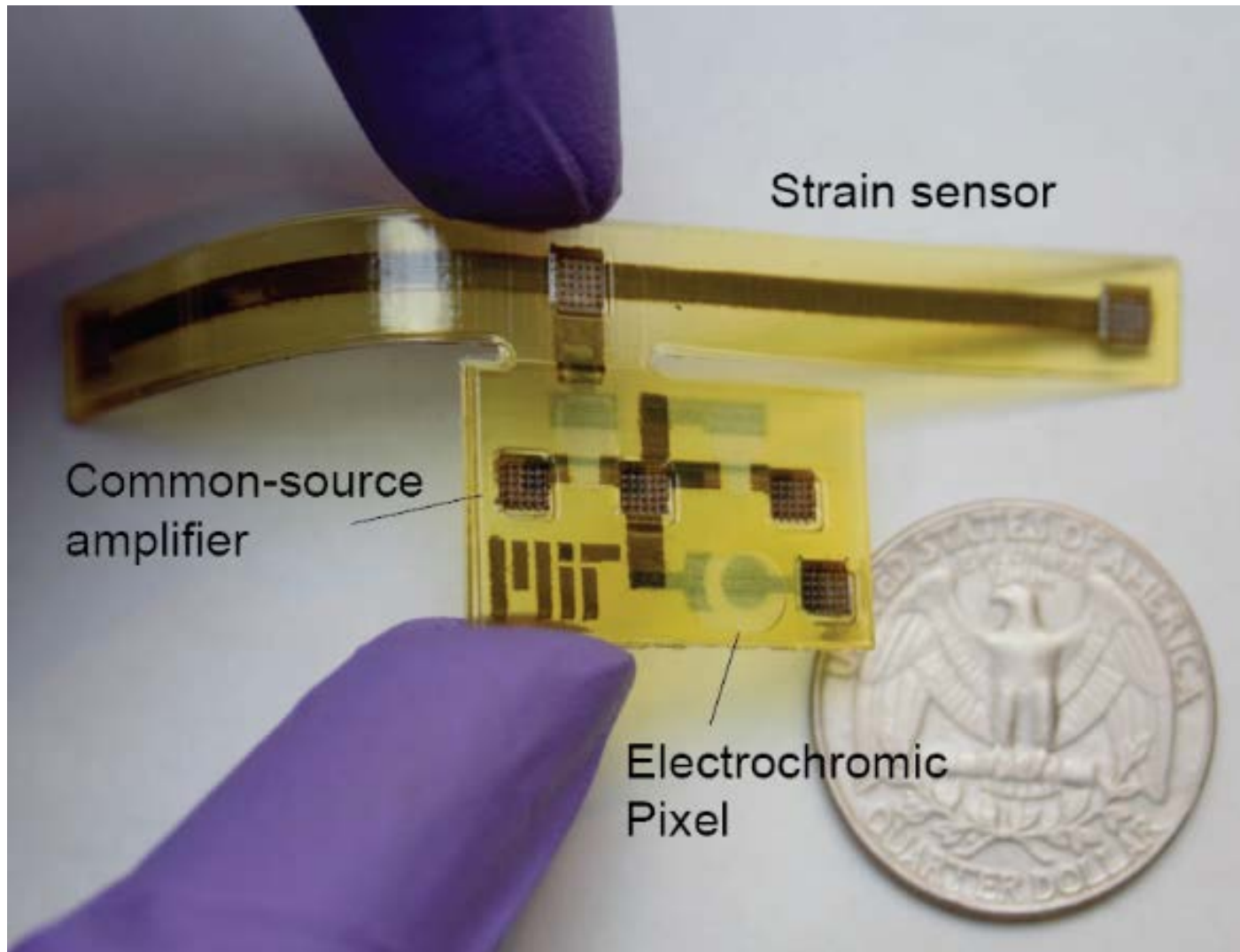
- ✓ **1.5V operation**
- ✓ **Modulate transparency**
- ✓ **Contrast – oxidized/reduced state of PEDOT**

SYSTEMS



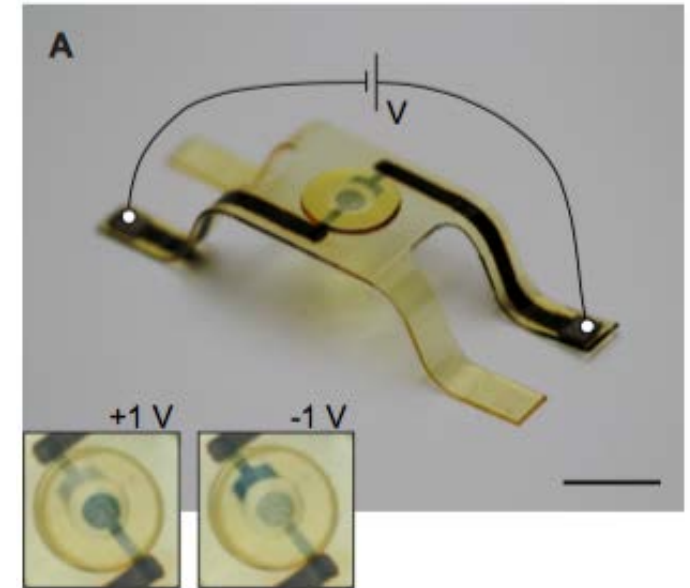
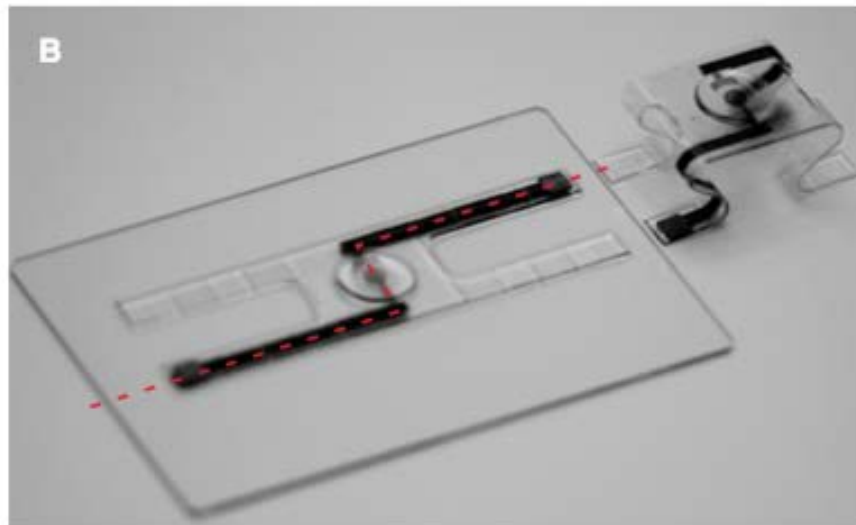
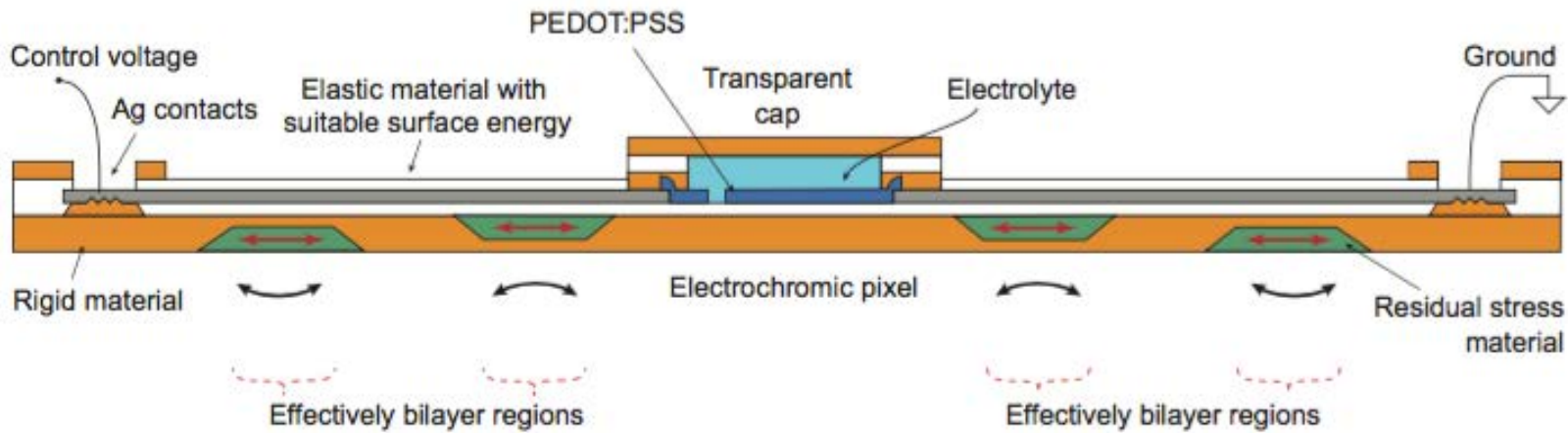
Equivalent circuit

SYSTEMS



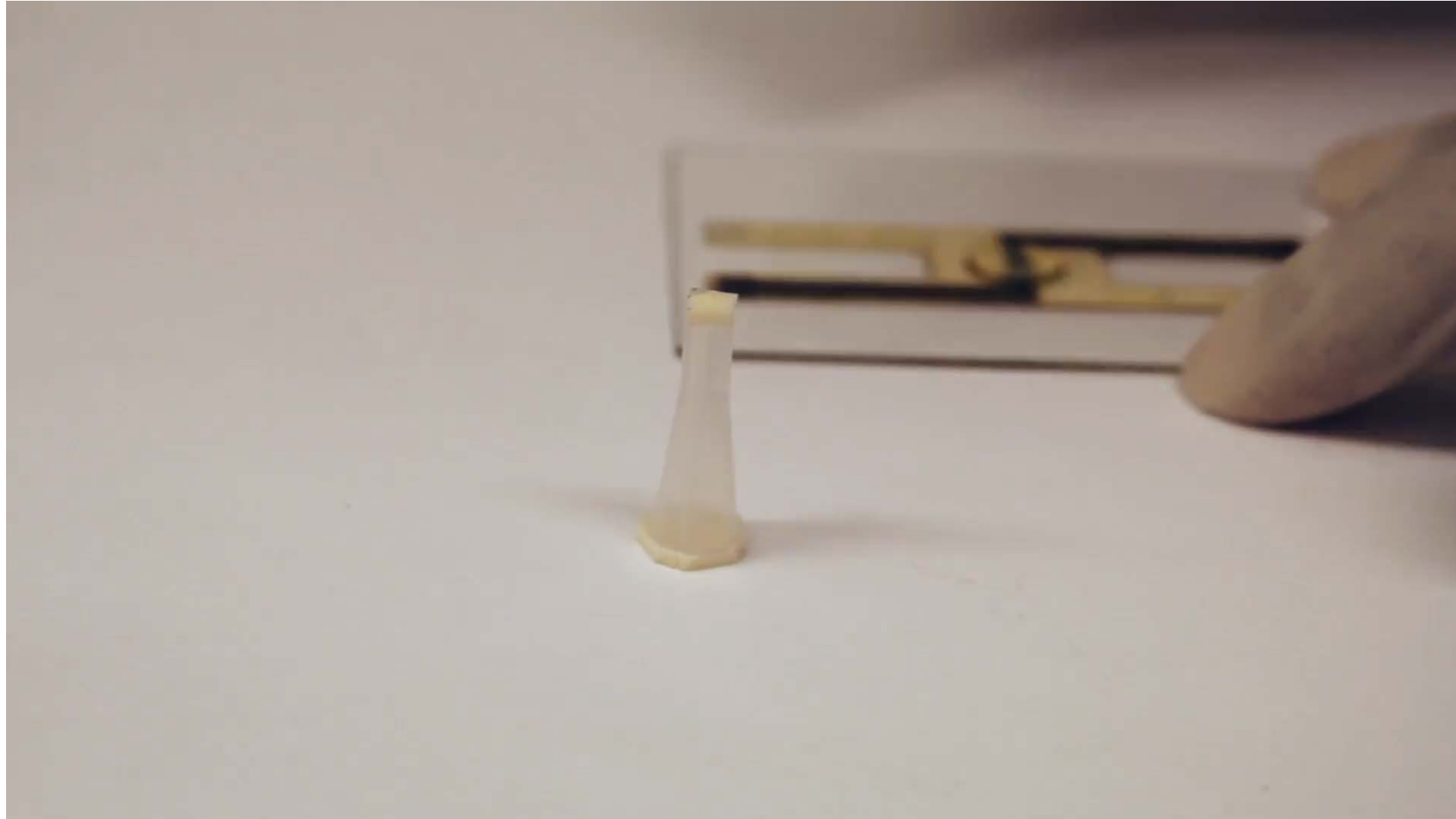
- ✓ Fully printed – 5 materials
- ✓ Low-temperature process
- ✓ No post-processing

SELF FOLDING CIRCUITS

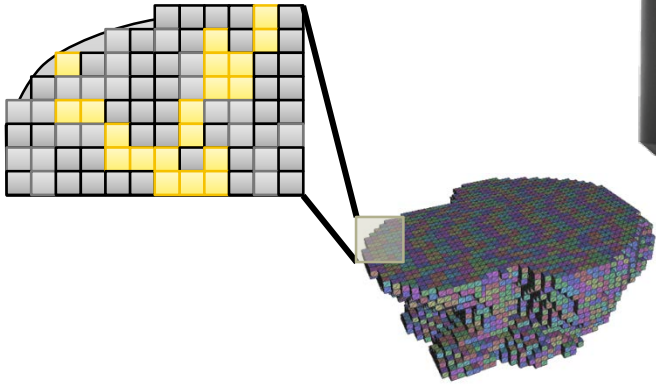


5 min after peeling

SELF FOLDING CIRCUITS

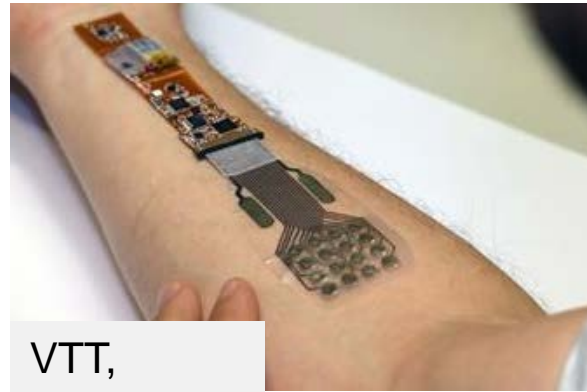


ADVANCED MANUFACTURING



Freedom of Form

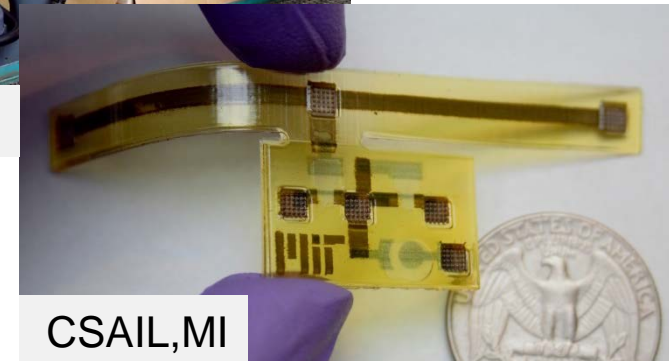
Accessibility



VTT,
Finland



Rethink
Robotics



CSAIL,MI

Integration

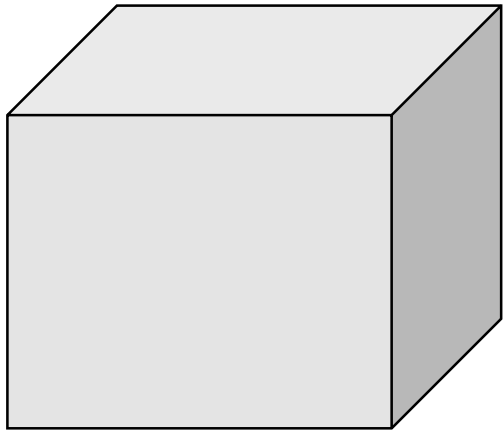
THREE FUNDAMENTAL QUESTIONS FOR COMPUTATIONAL MANUFACTURING

QUESTION #1:

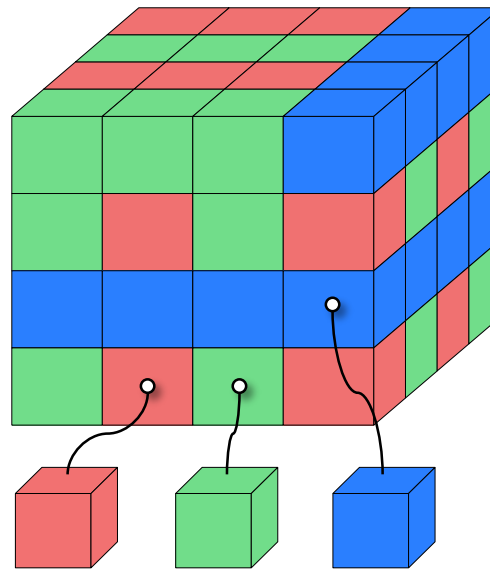
**HOW TO COMPUTE THE SPACE OF POSSIBLE
MATERIAL PROPERTIES?**

MICROSTRUCTURES

A unit microstructure cell



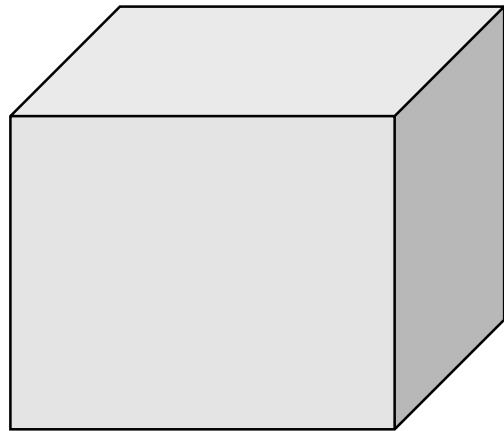
Heterogeneous material



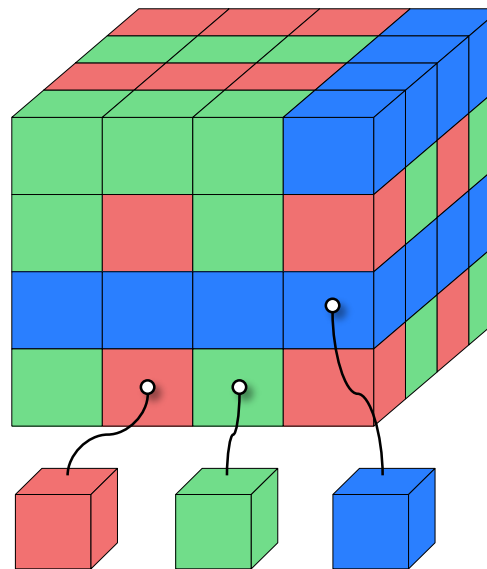
Base materials

MAPPING MICROSTRUCTURES TO MATERIAL PROPERTIES

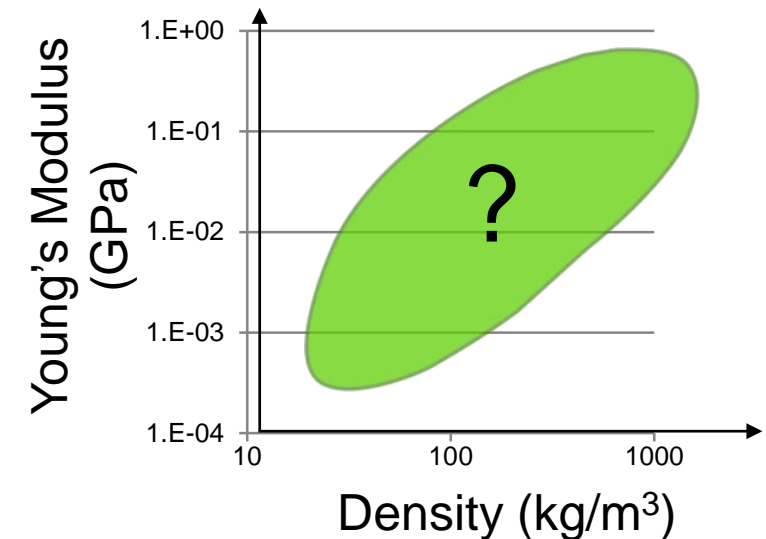
A unit microstructure cell



Heterogeneous material

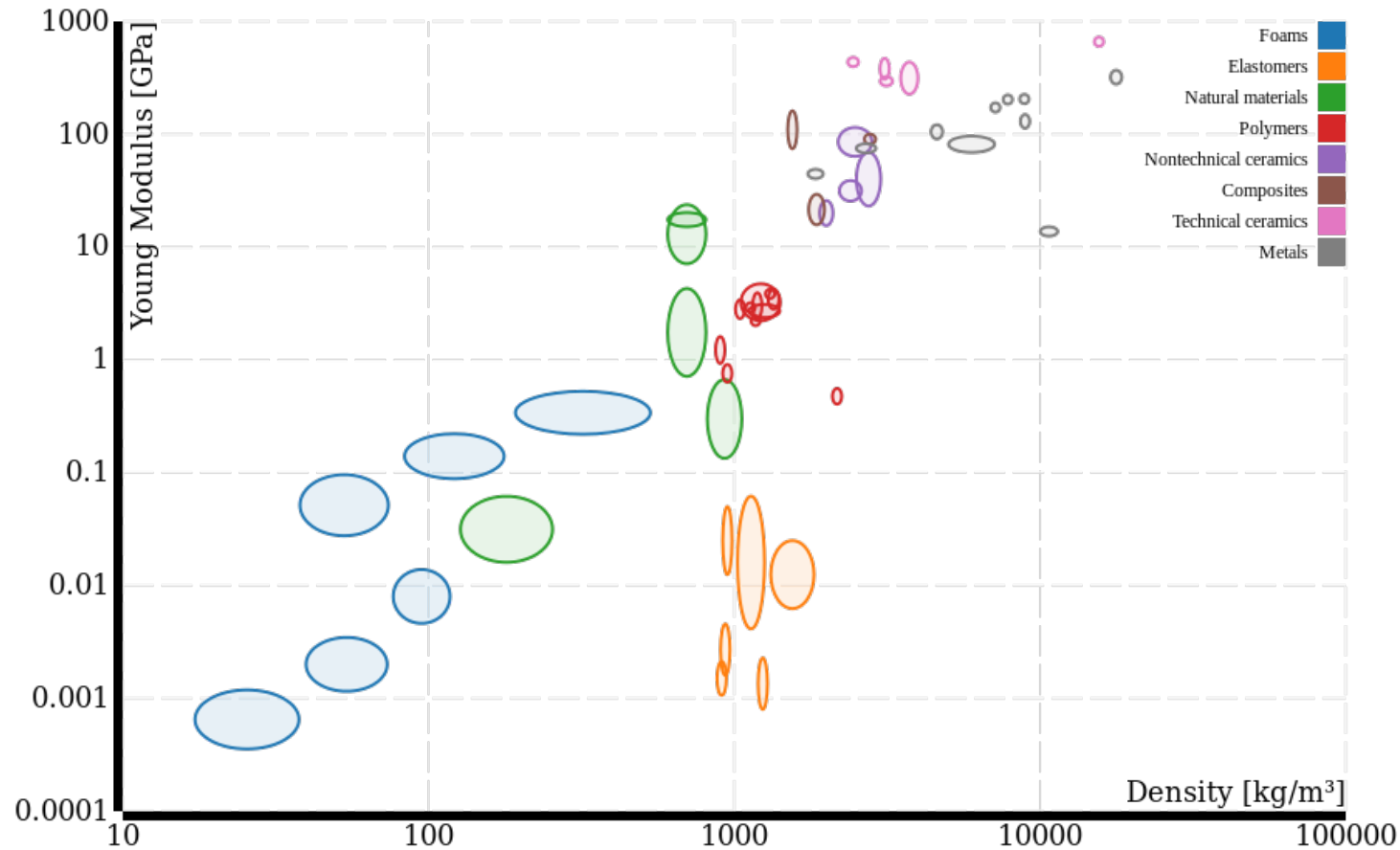


Base materials



What is the range of achievable physical properties (gamut)?

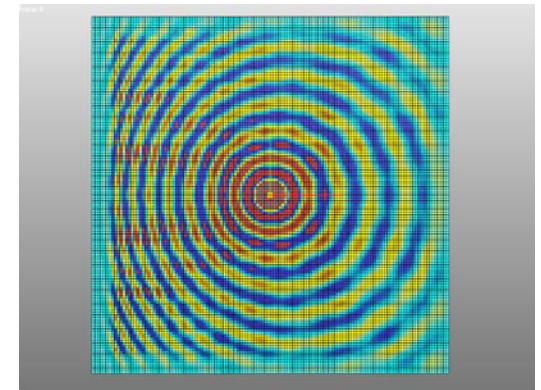
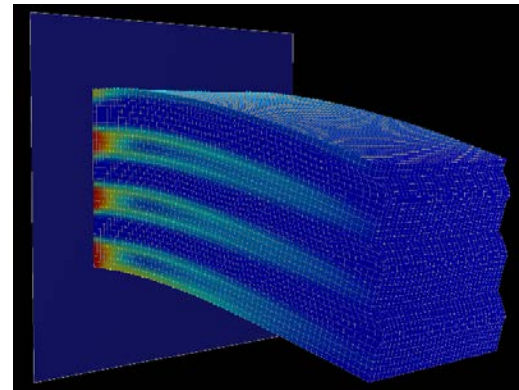
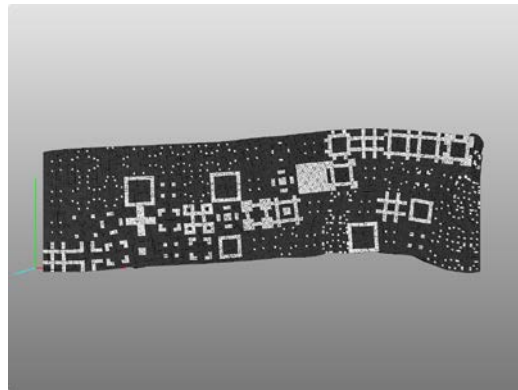
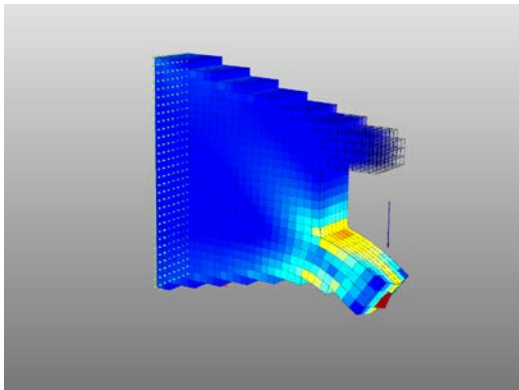
TRADITIONAL MATERIALS



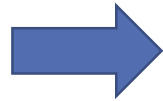
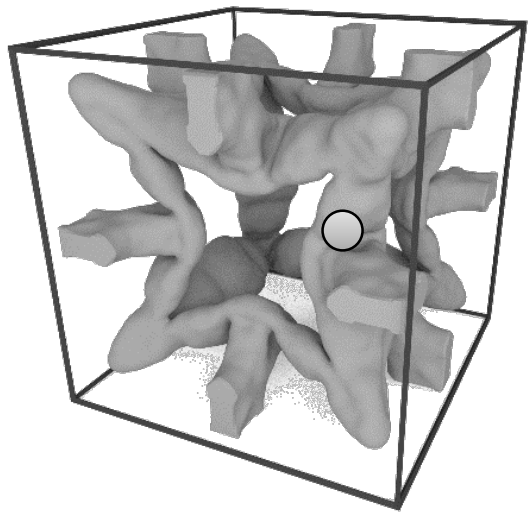
Range of mechanical material properties for traditional homogeneous materials such as foams, metals and polymers.

PHYSICS SIMULATION

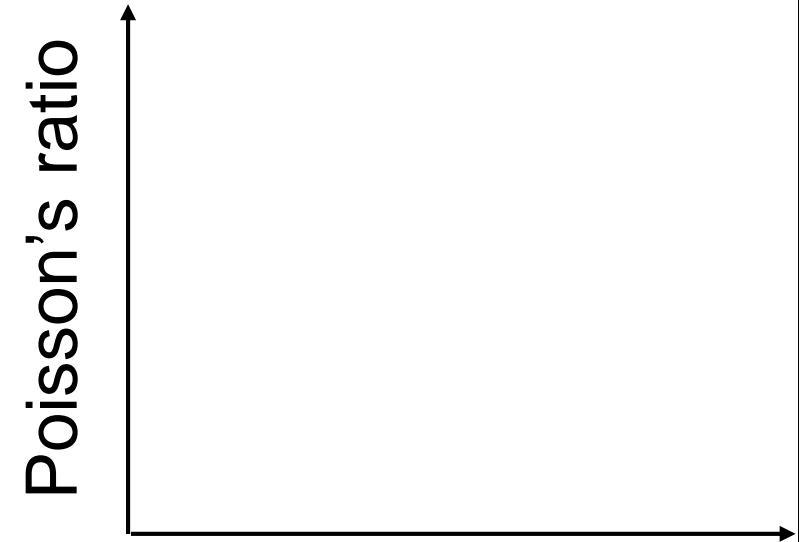
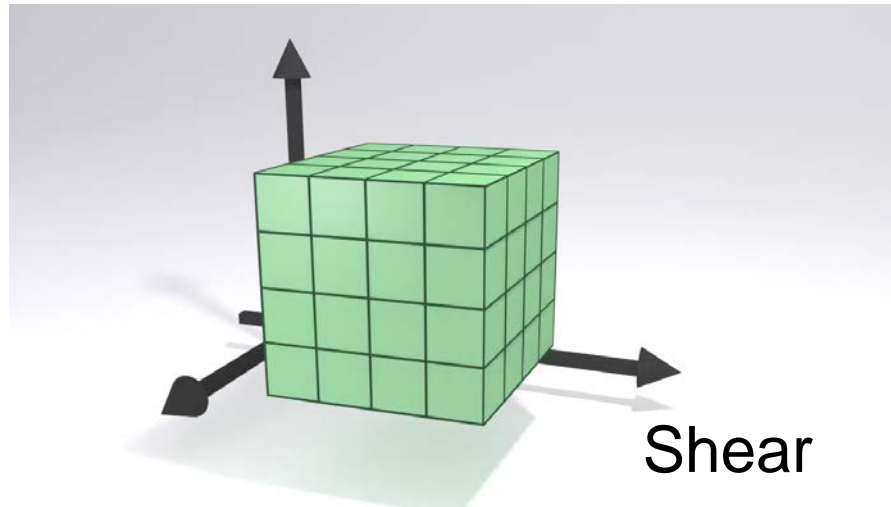
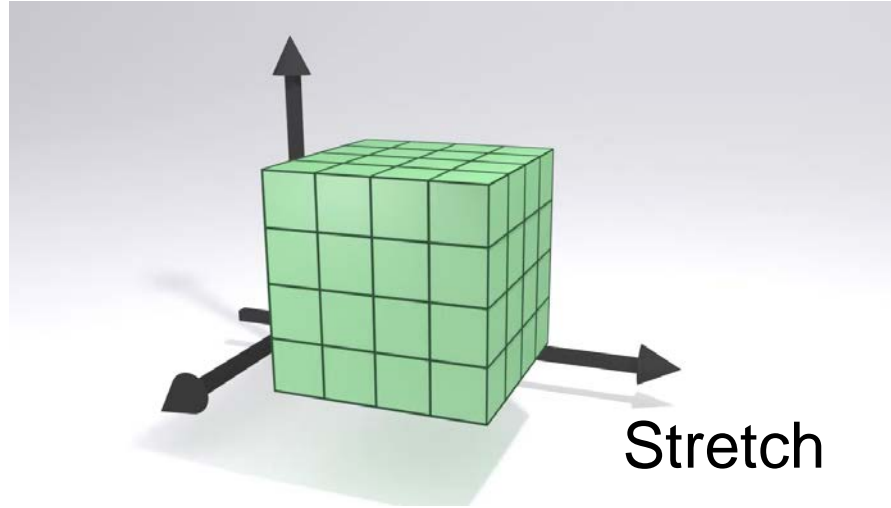
Finite element solvers with multi-grid preconditioners to simulate multi-physics problems



MAPPING MICROSTRUCTURES TO MATERIAL PROPERTIES

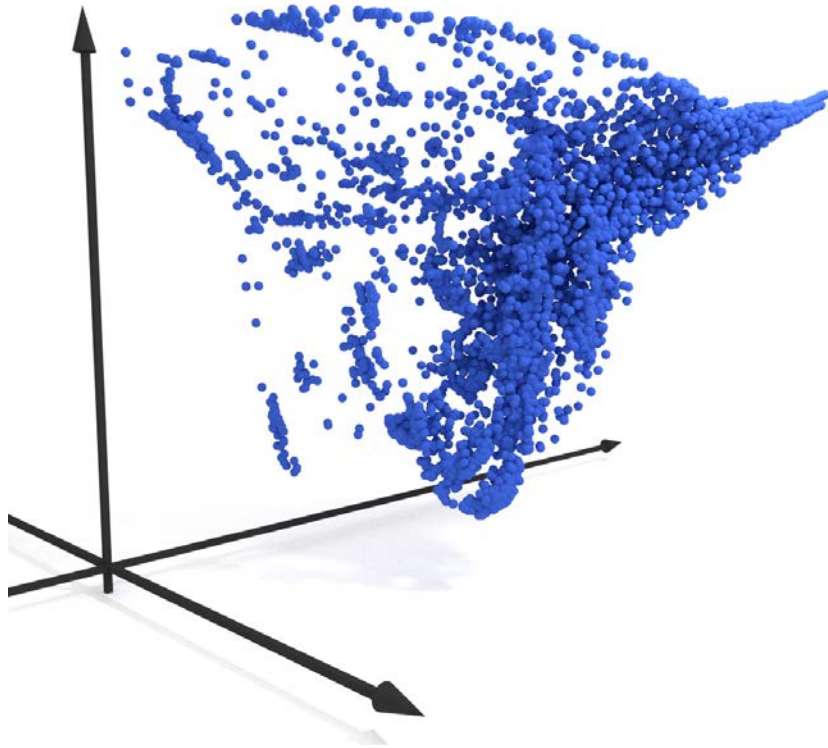


A microstructure



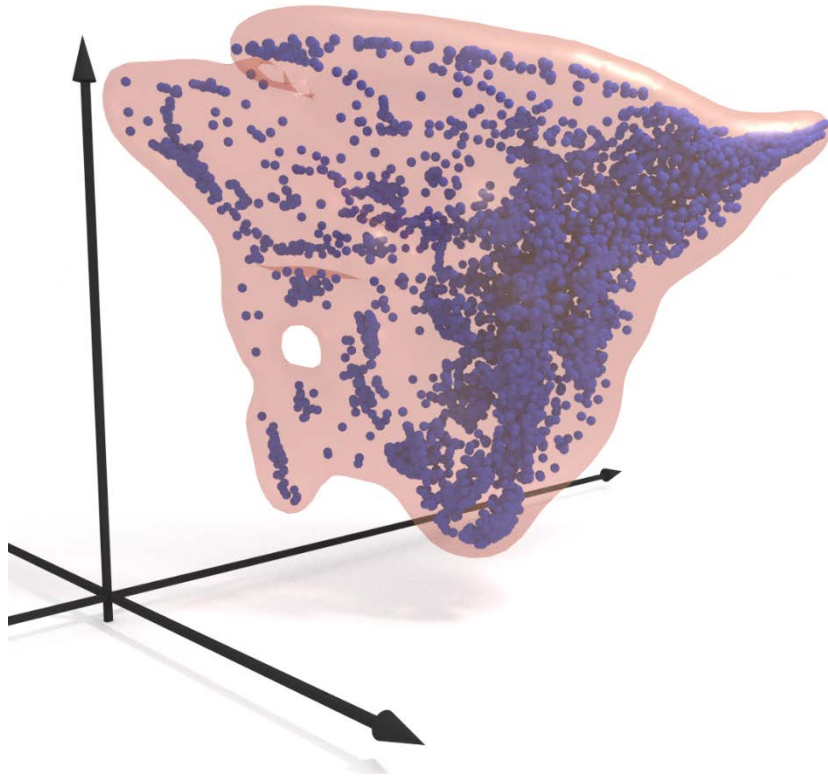
Young's Modulus

COMPUTING MICROSTRUCTURE GAMUT



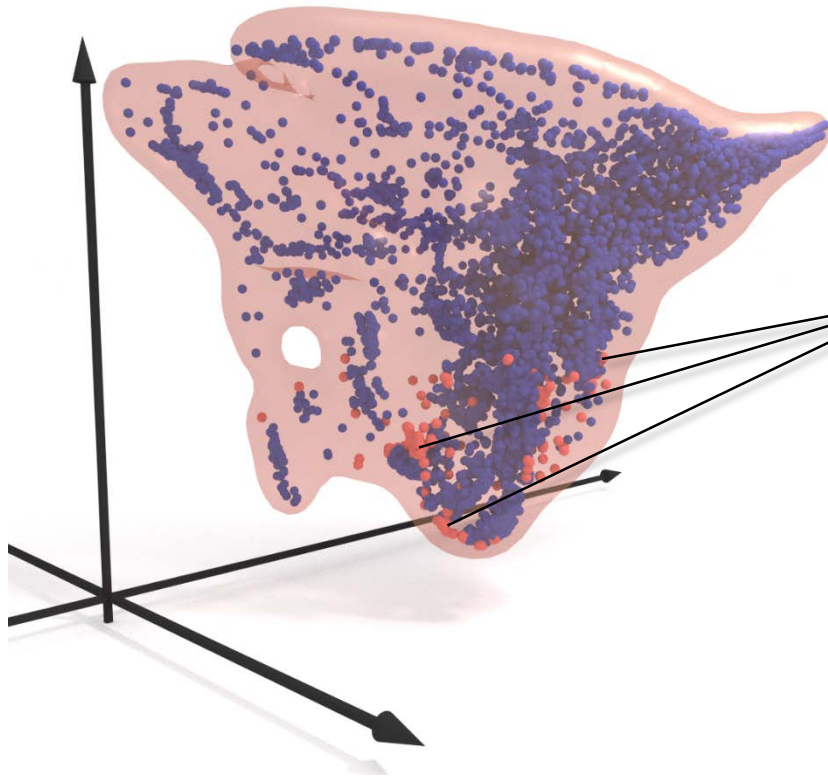
- Microstructure samples

COMPUTING MICROSTRUCTURE GAMUT



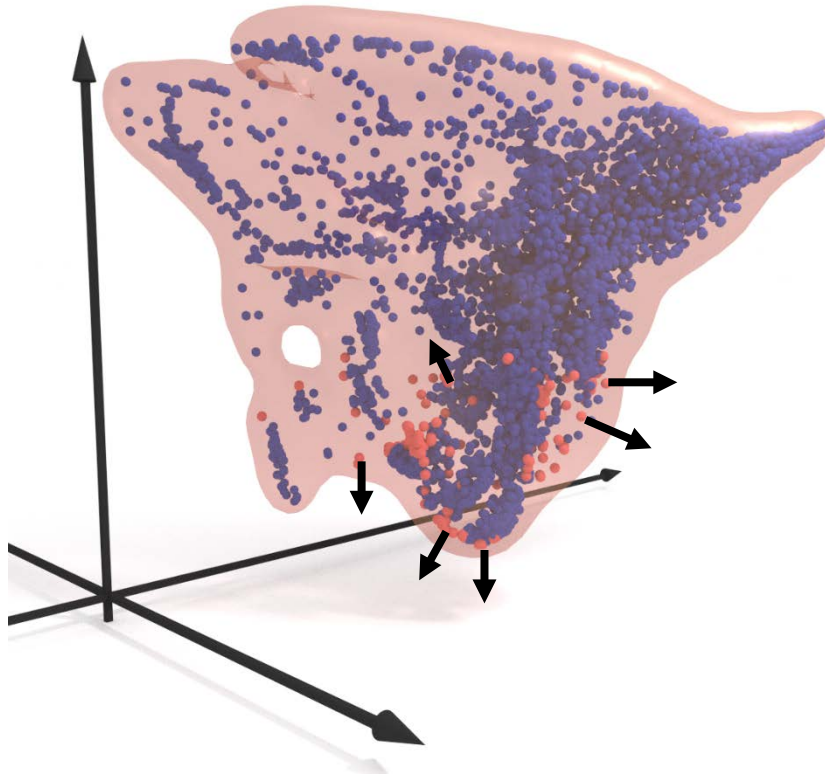
- Microstructure samples
- Compute level set

COMPUTING MICROSTRUCTURE GAMUT



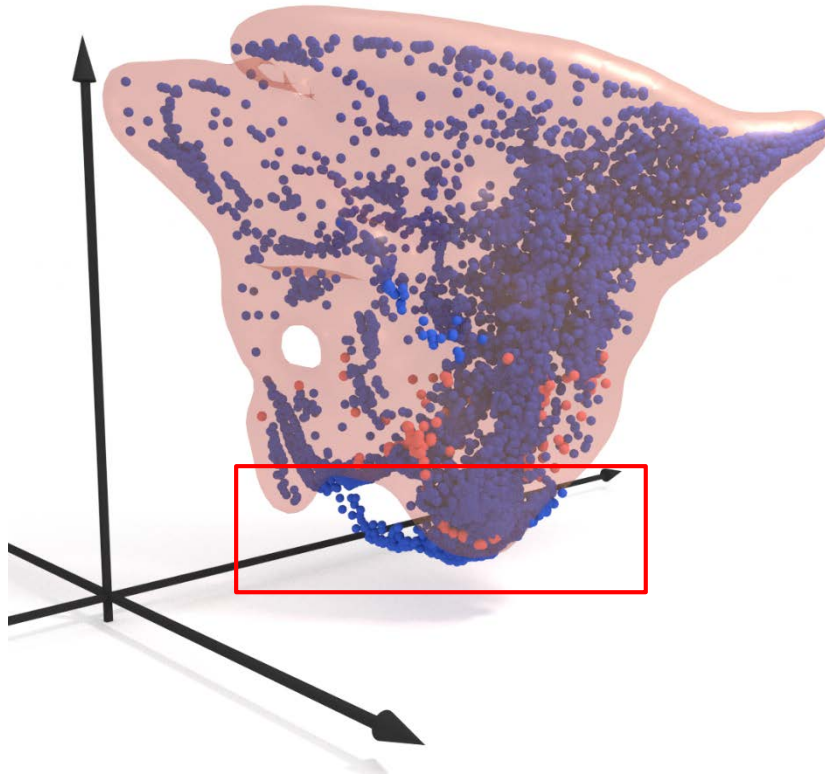
- Microstructure samples
- Compute level set
- Find random seeds near the level set boundary

COMPUTING MICROSTRUCTURE GAMUT



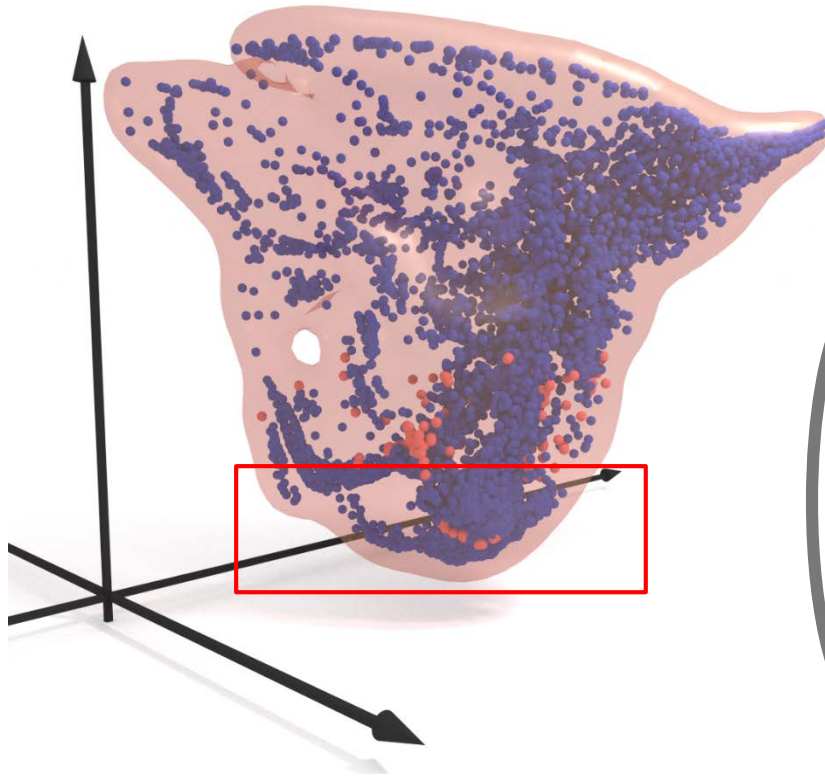
- Microstructure samples
- Compute level set
- Find random seeds near the level set boundary
- Find gradient towards outside of gamut

COMPUTING MICROSTRUCTURE GAMUT



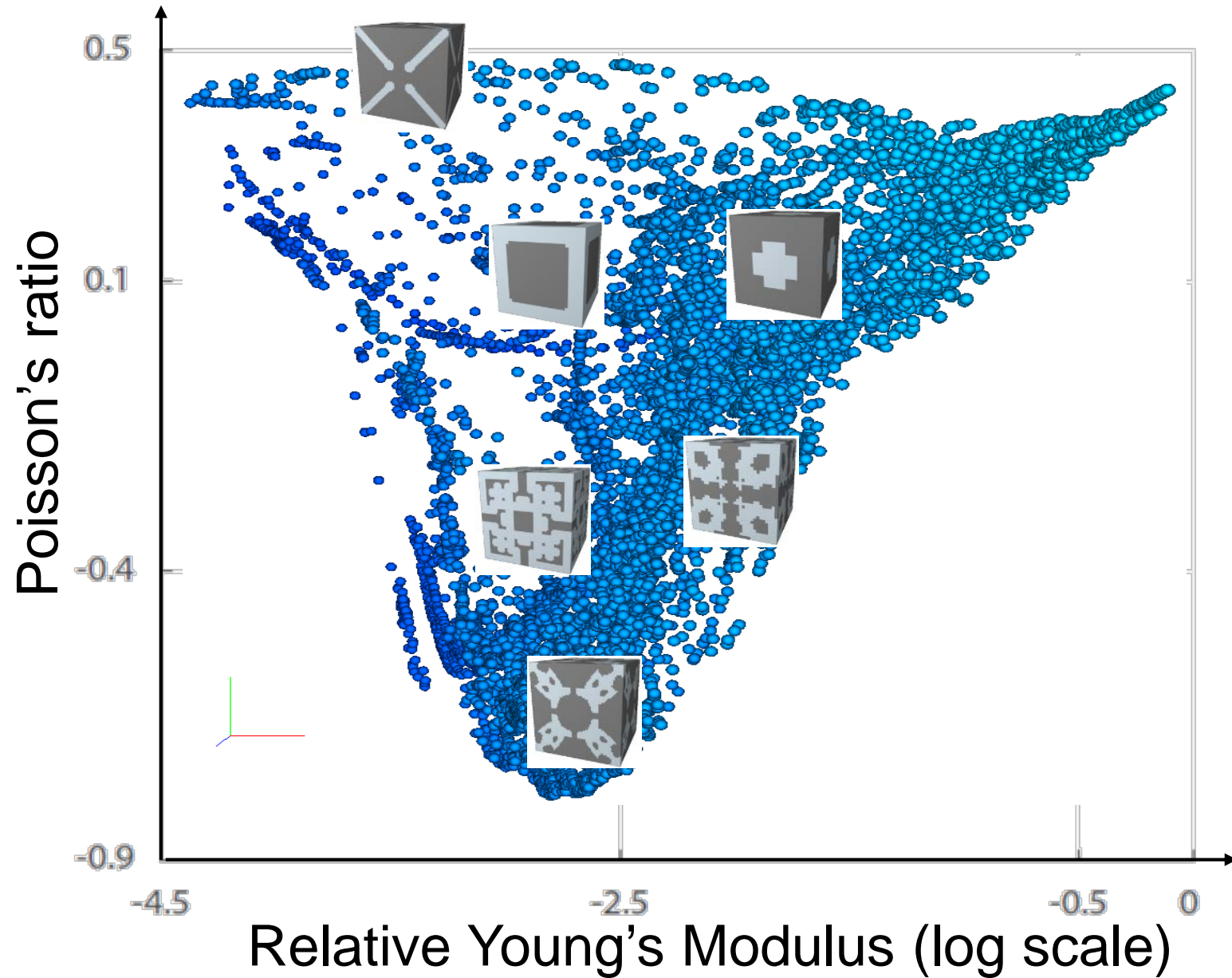
- Microstructure samples
- Compute level set
- Find random seeds near the level set boundary
- Find gradient towards outside of gamut
- Discrete and continuous sampling

COMPUTING MICROSTRUCTURE GAMUT

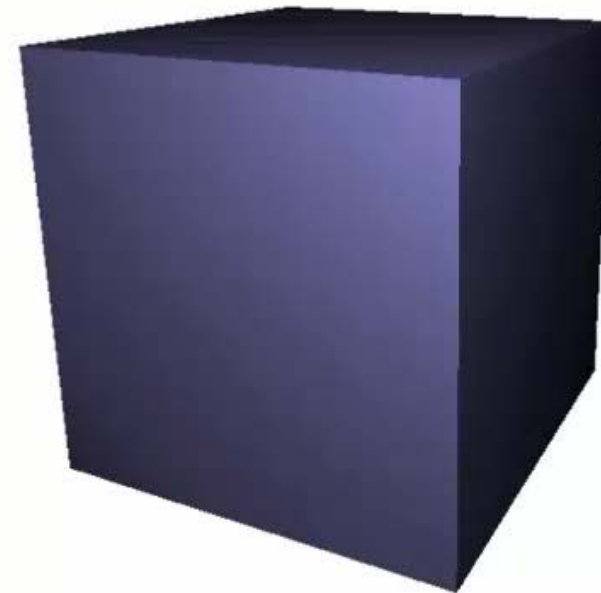
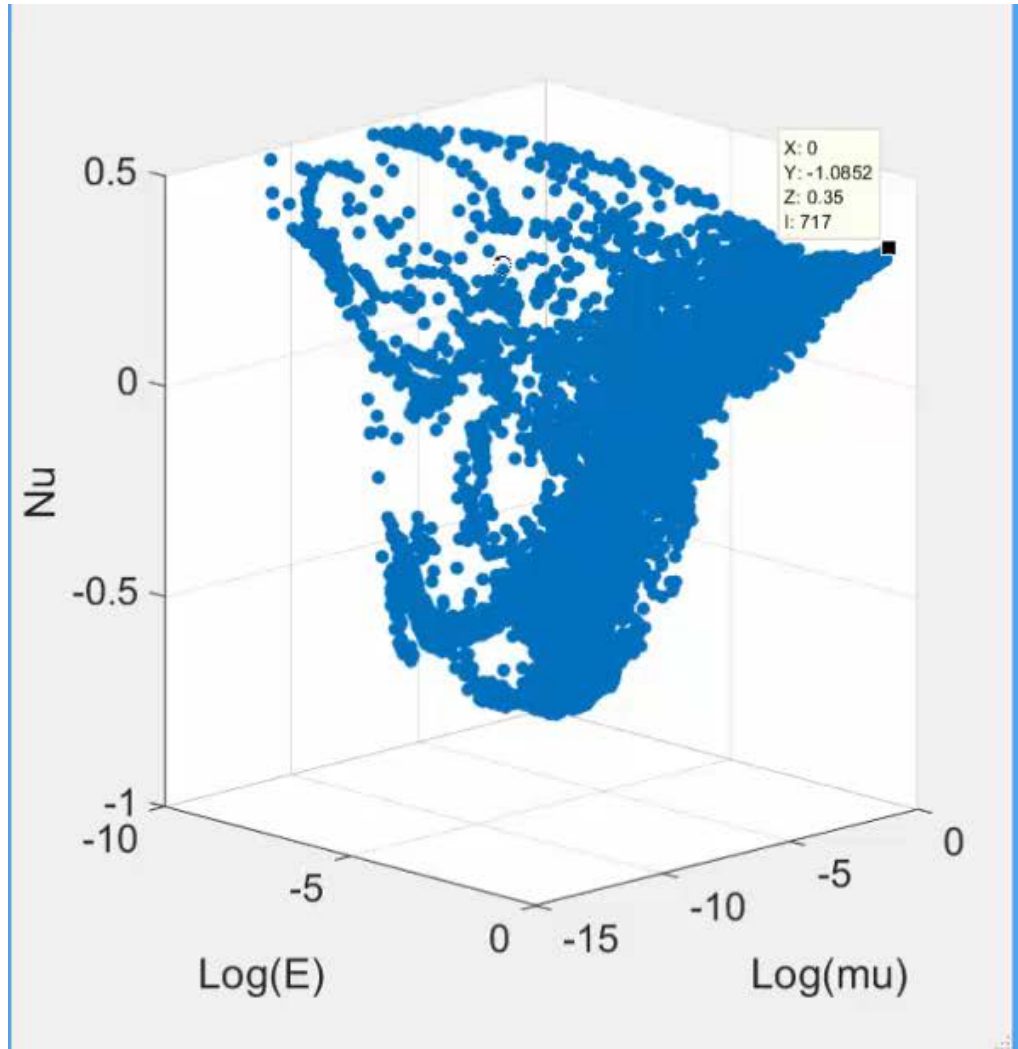


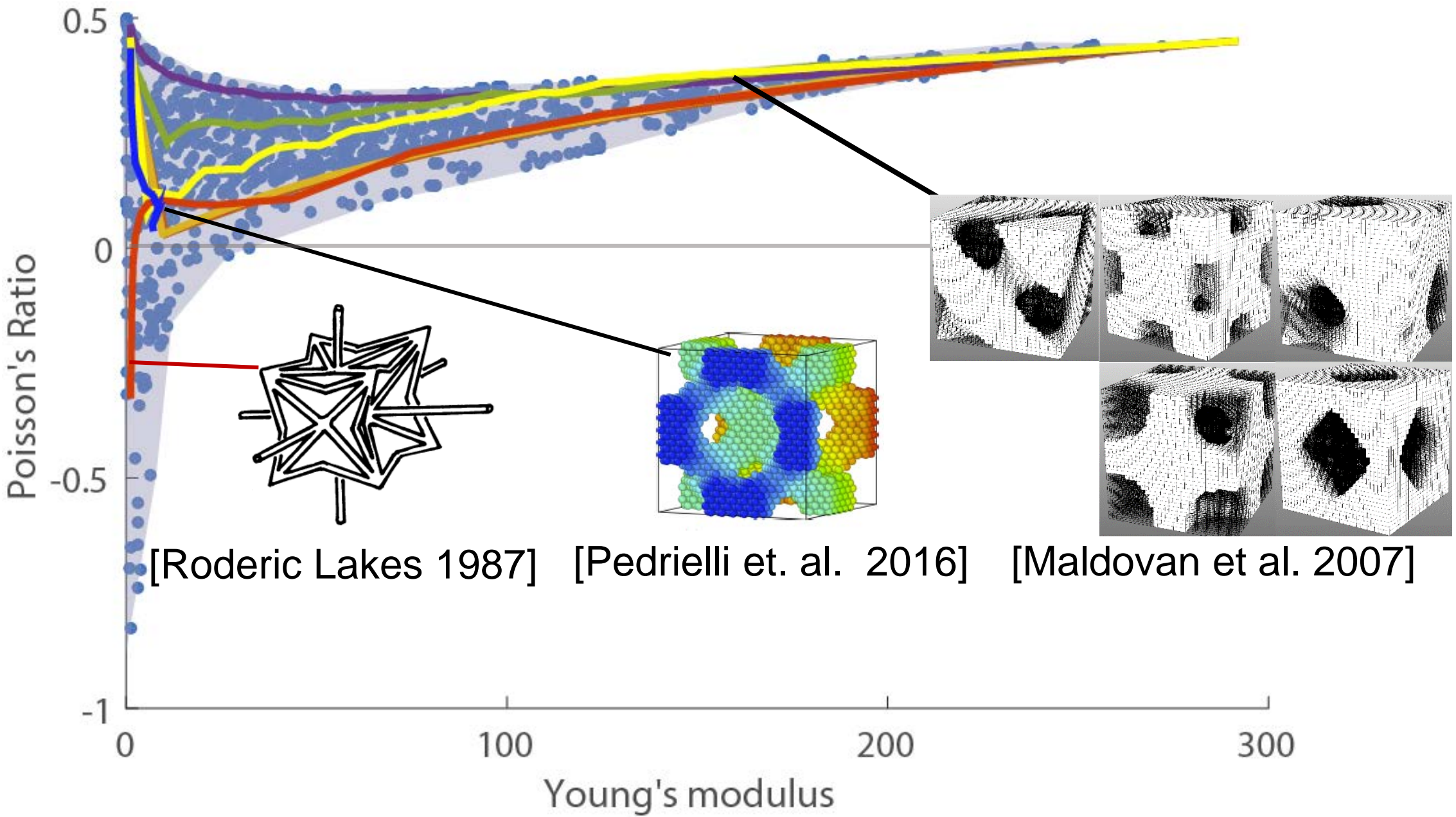
- Microstructure samples
- Compute level set
- Find random seeds near the level set boundary
- Find gradient towards outside of gamut
- Discrete and continuous sampling
- Update level set

GAMUT FOR MICROSTRUCTURES WITH CUBIC SYMMETRY



GAMUT FOR MICROSTRUCTURES WITH CUBIC SYMMETRY



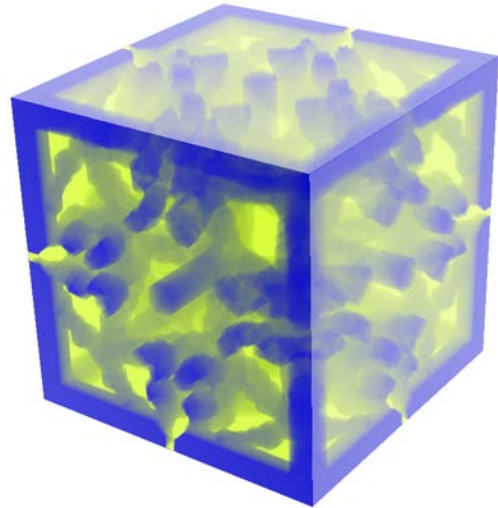


[Roderic Lakes 1987]

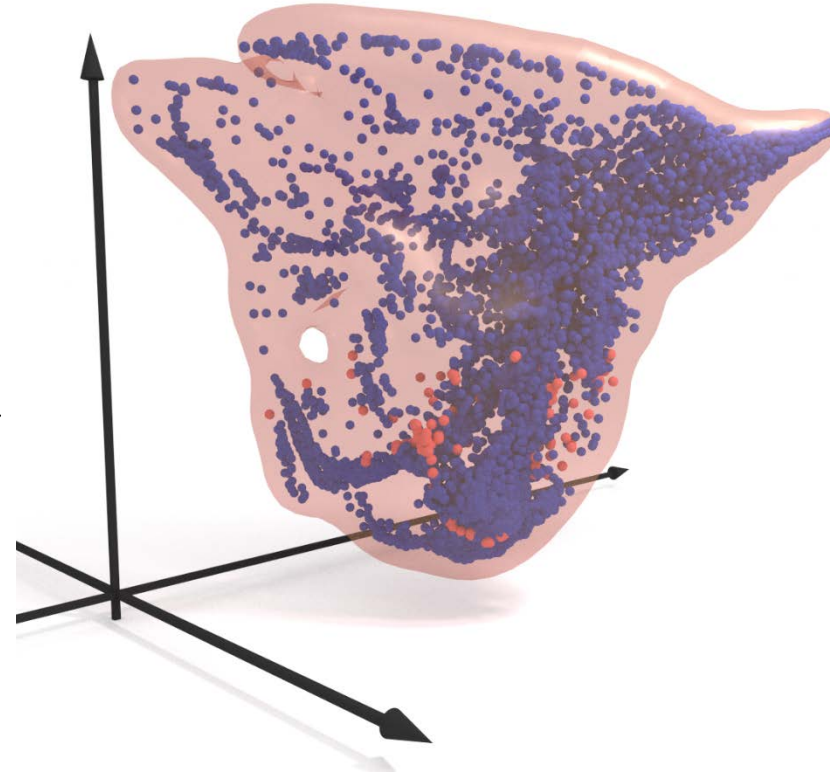
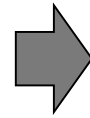
[Pedrielli et al. 2016]

[Maldovan et al. 2007]

SUMMARY: FROM DESIGN TO FUNCTION



Microstructure Design

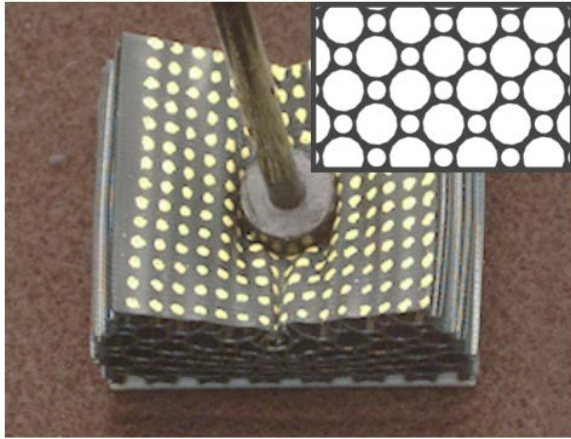


Material Gamut

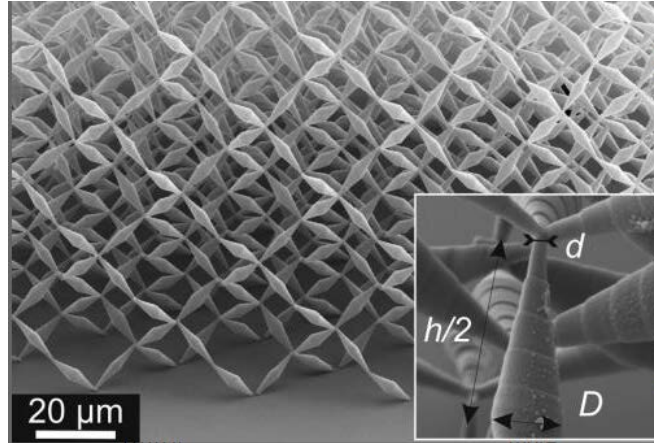
QUESTION #2:

**HOW TO DISCOVER MATERIAL FAMILIES
WITH EXTREME PROPERTIES?**

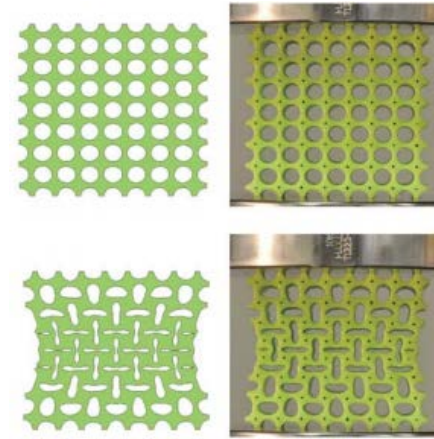
DISCOVERY OF MICROSTRUCTURES



[Bickel et al. 2010]



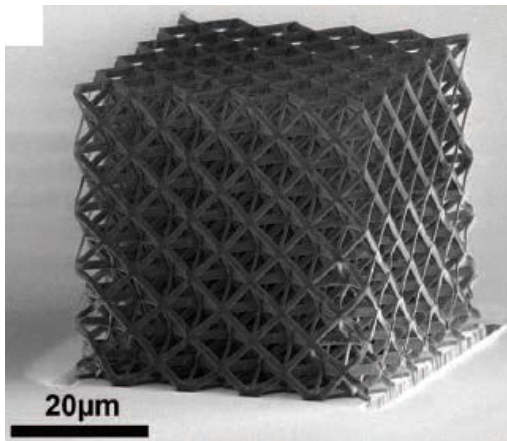
[Kadic et al. 2012]



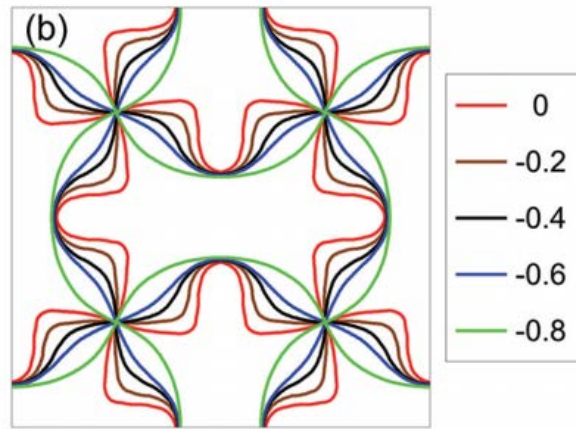
[Shim et al. 2013]



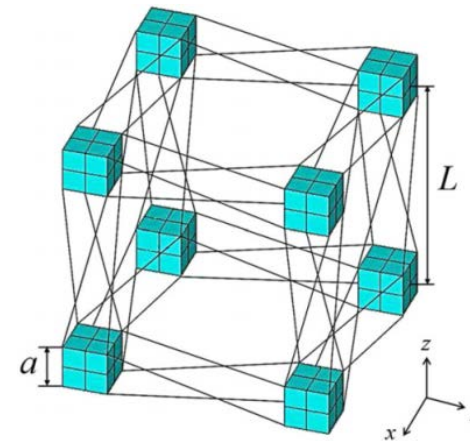
[Babaei et al. 2013]



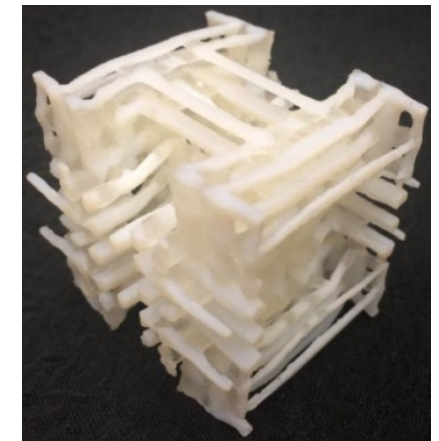
[Meza et al. 2014]



[Clausen et al. 2015]



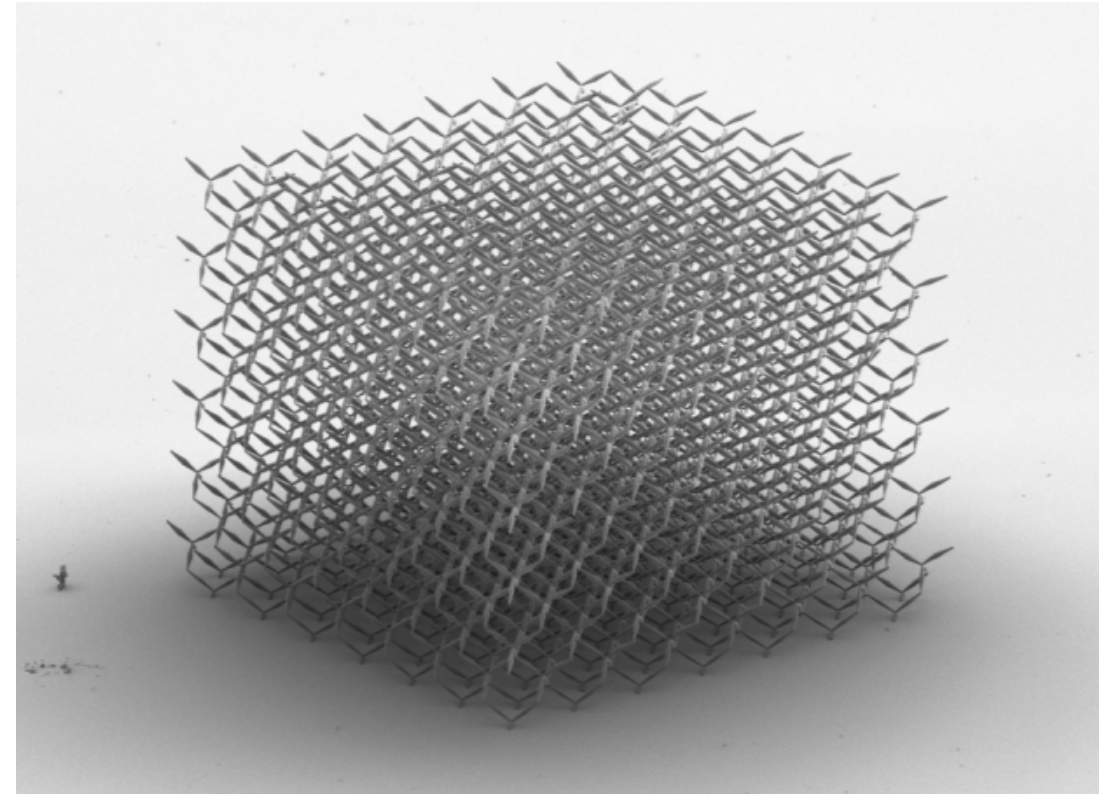
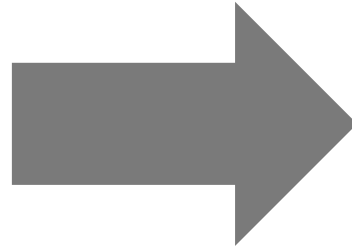
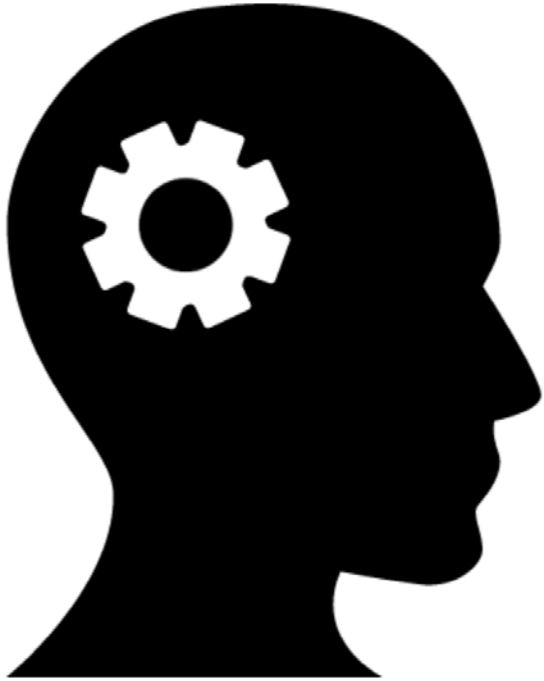
[Kadic et al. 2016]



[Volgatzis and Chen 2016]

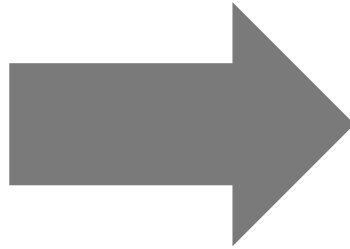
CONVENTIONAL MATERIAL DISCOVERY

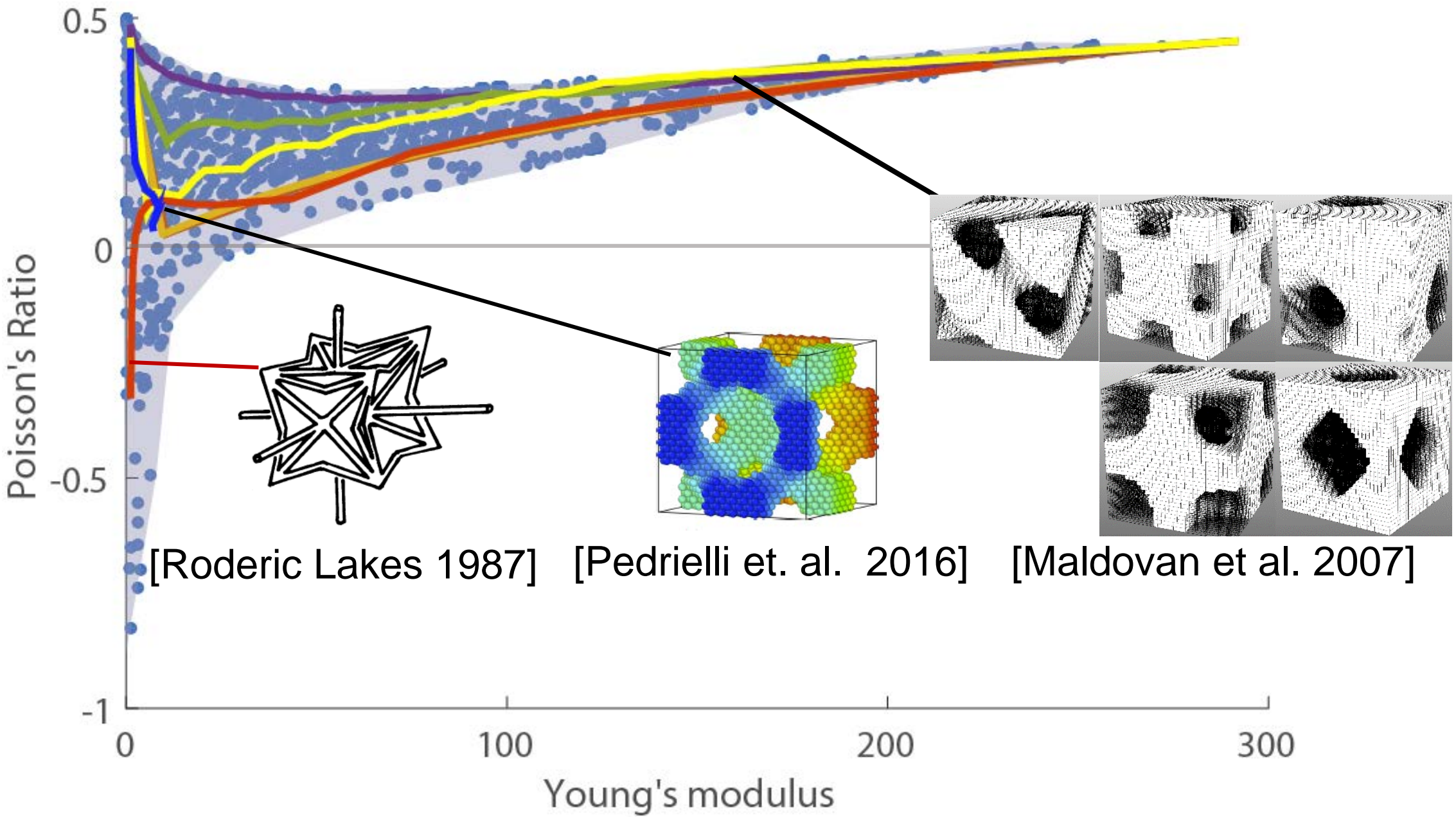
Design new materials by intuition and trial-and-error



CONVENTIONAL MATERIAL DISCOVERY

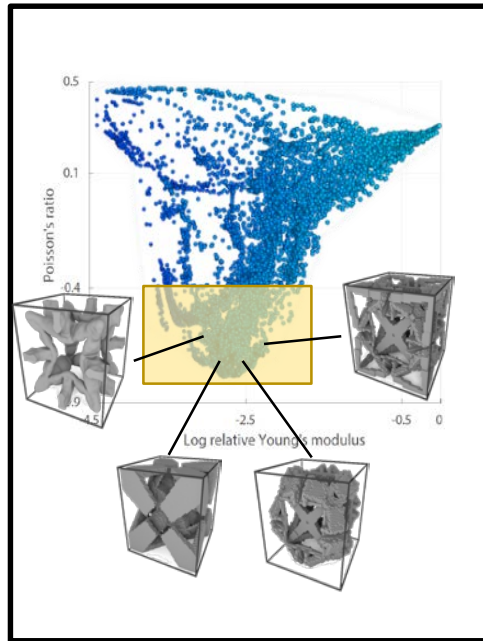
Design new materials by mimicking the nature



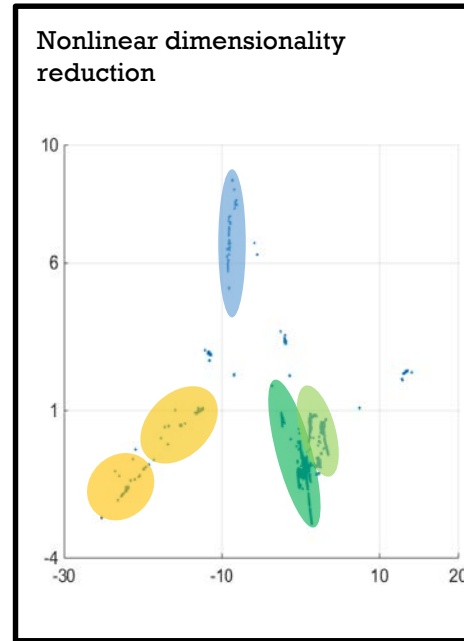


COMPUTATIONAL FRAMEWORK

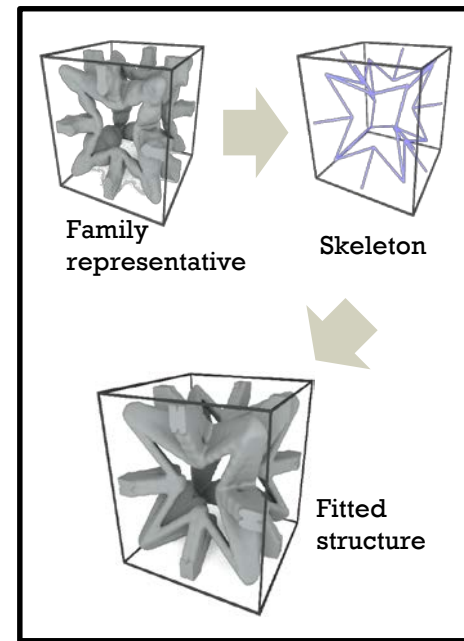
Automated discovery of new microstructural materials



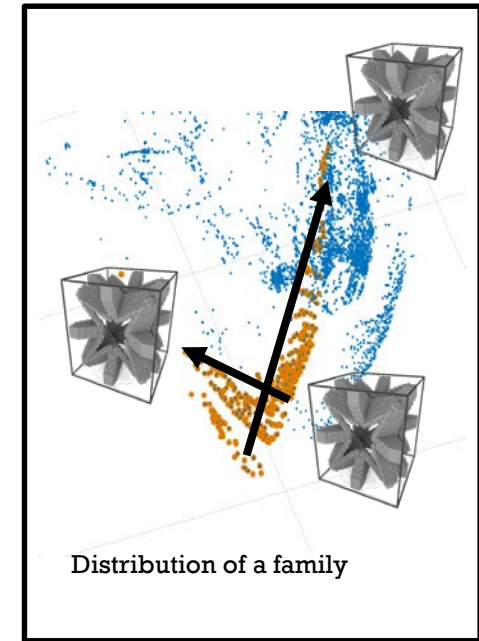
Input:
Estimate Gamut



Identify Families

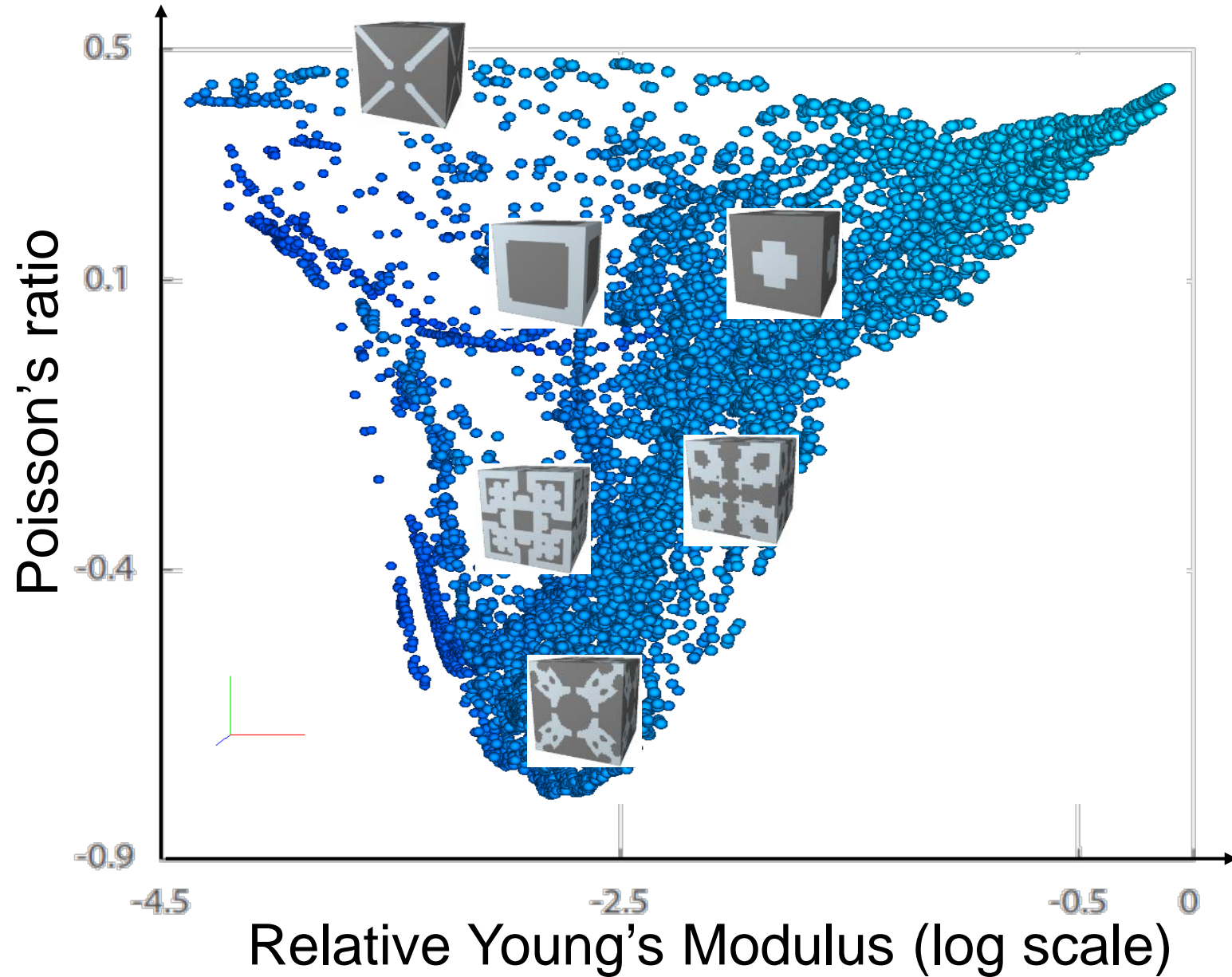


Fit Templates

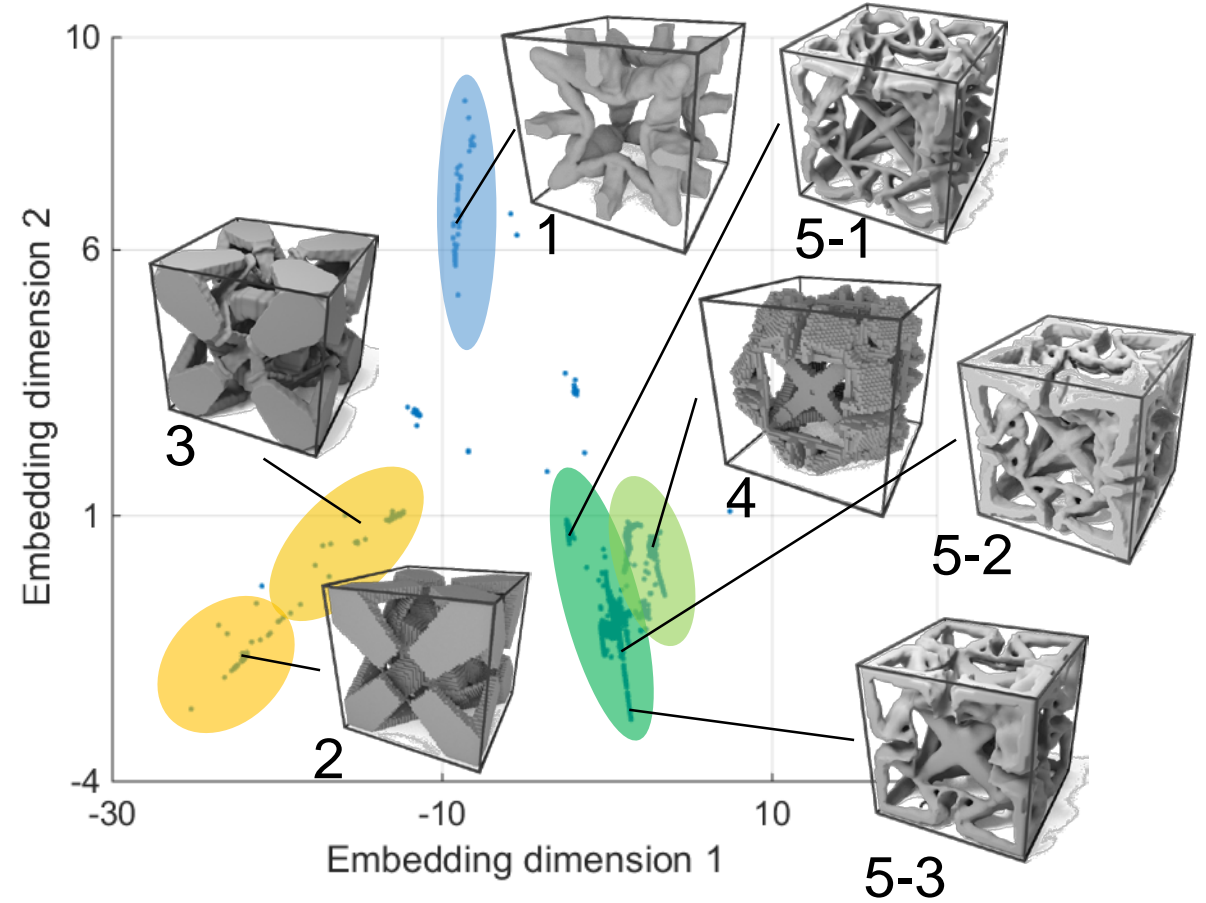
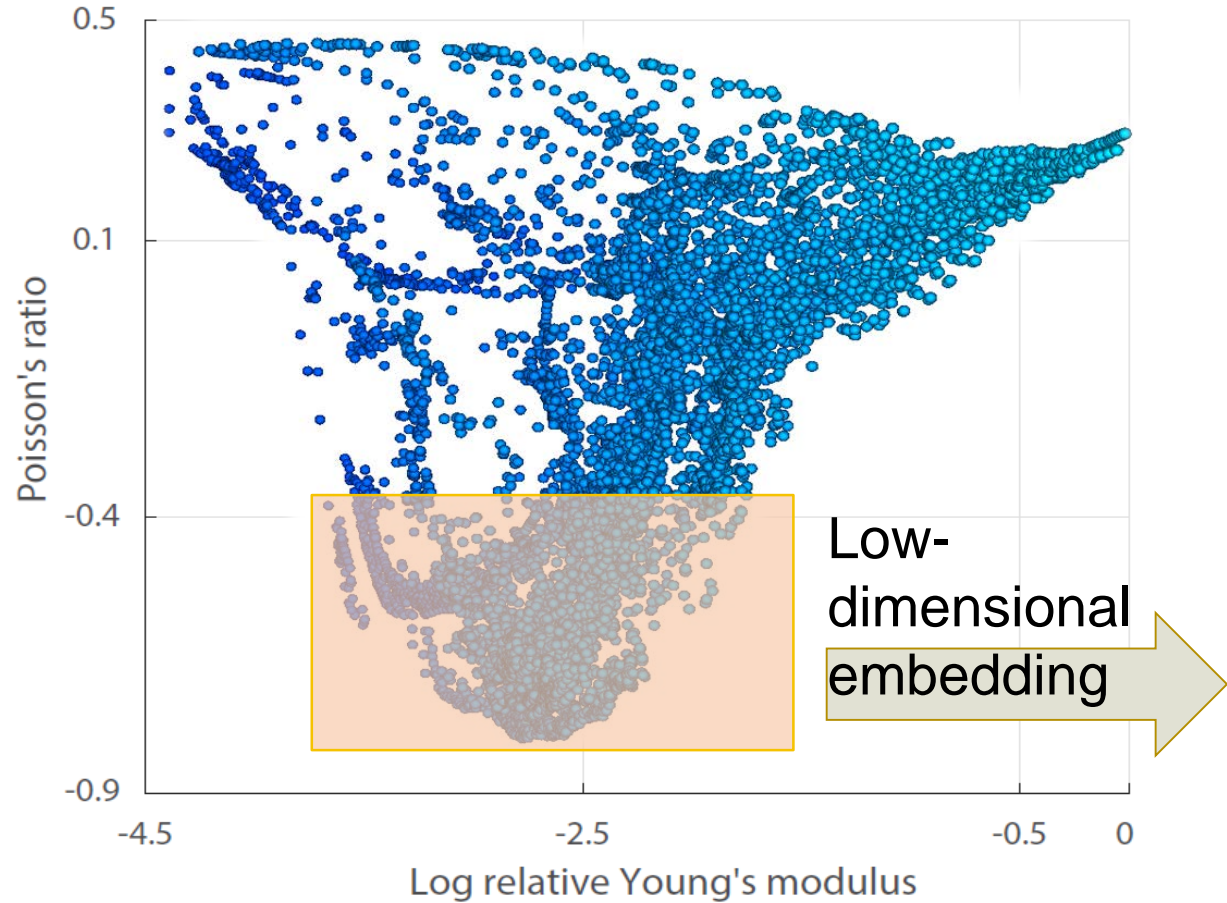


Reduce Parameters

INPUT: MICROSTRUCTURE GAMUT

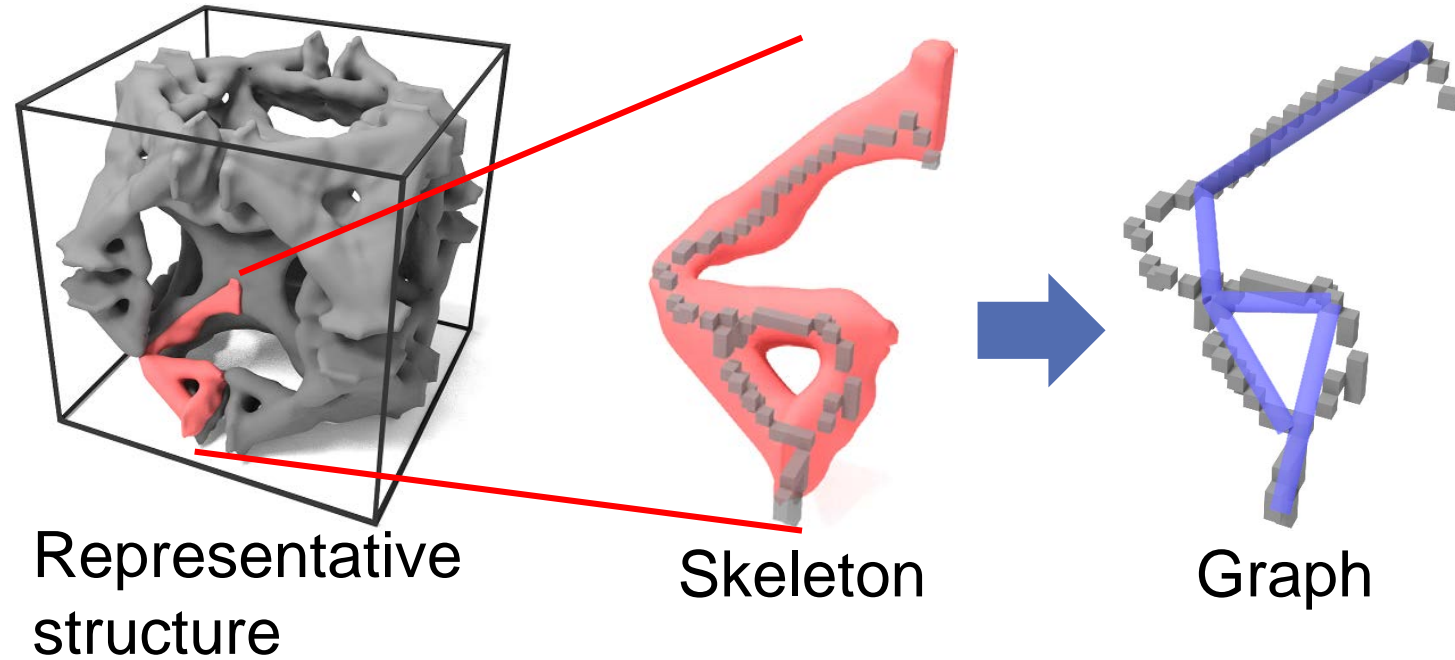


STEP 1: IDENTIFY MICROSTRUCTURE FAMILIES

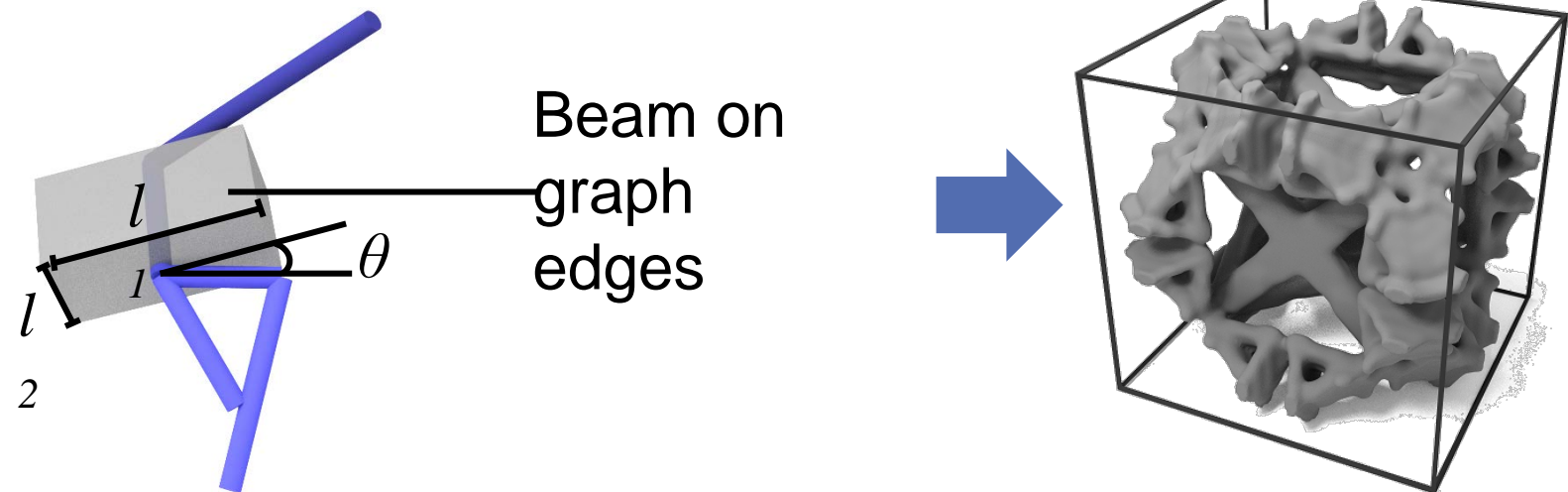


STEP 2: FIT MICROSTRUCTURE SKELETONS

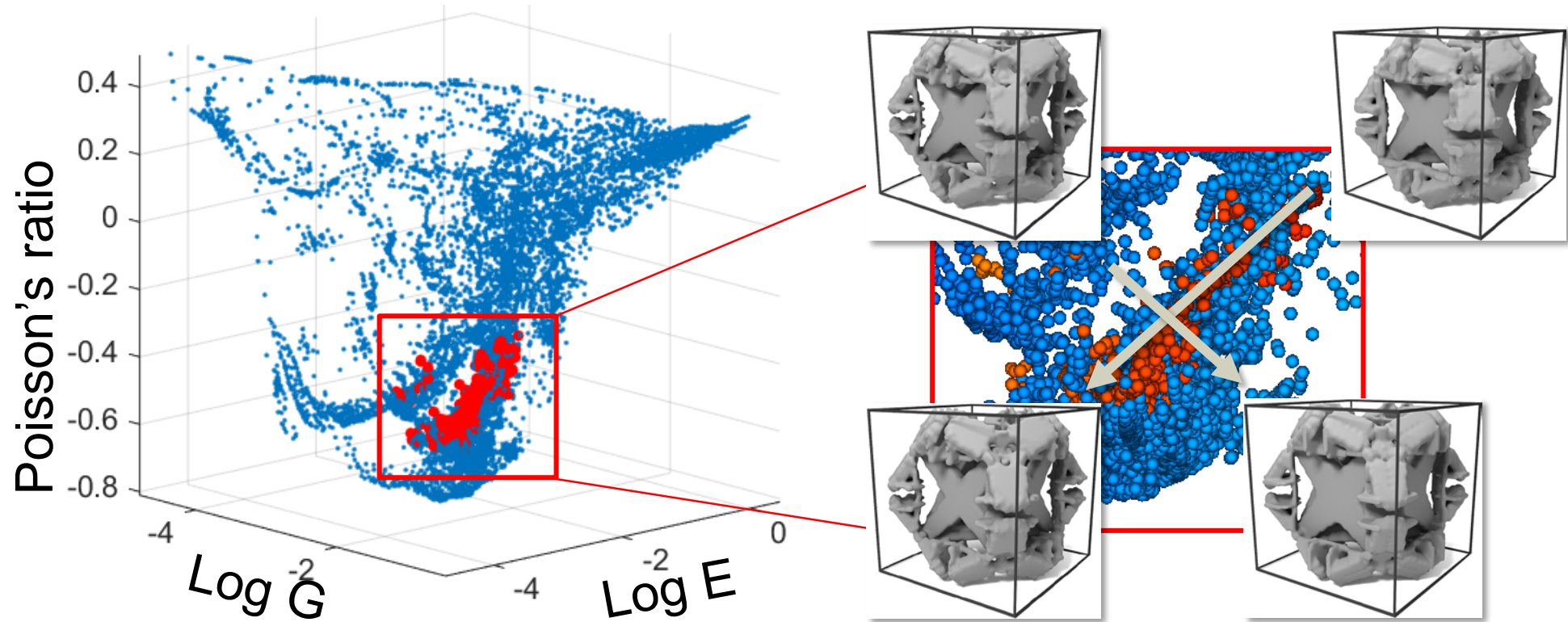
Extracting a skeleton



Template definition given a skeleton



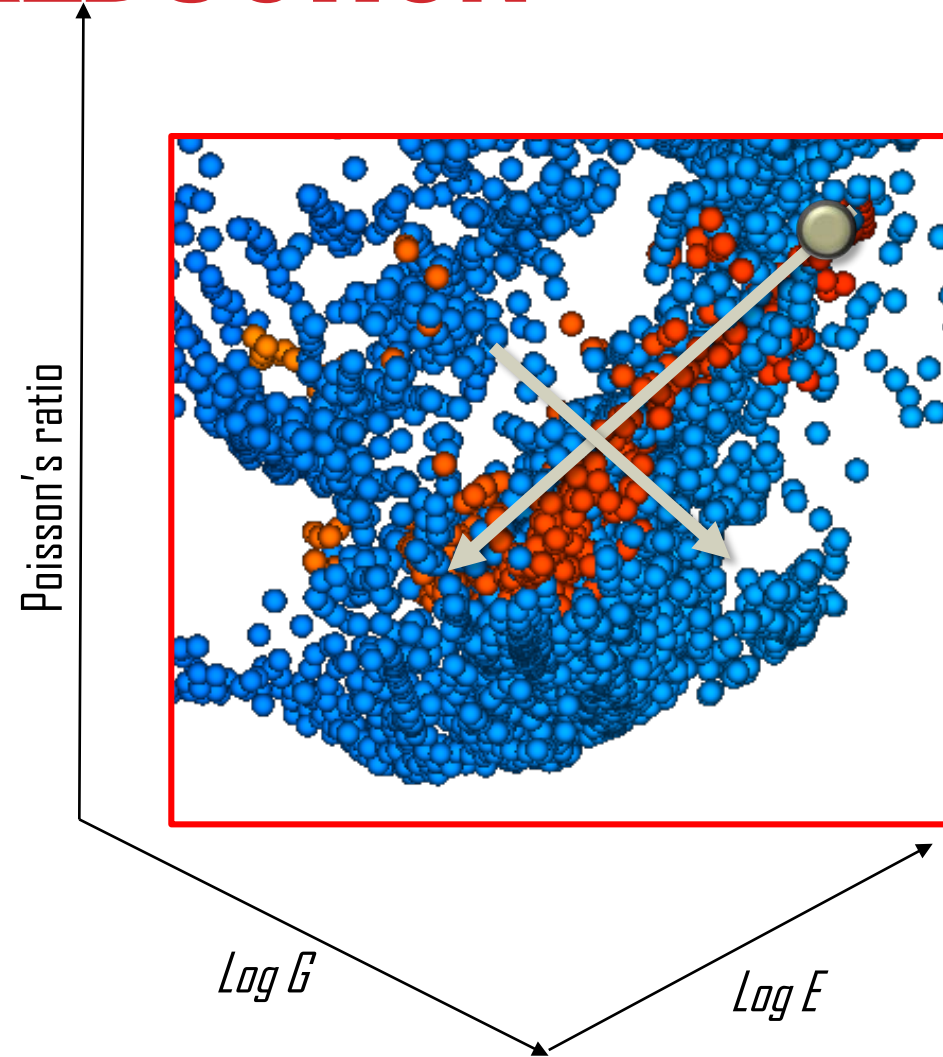
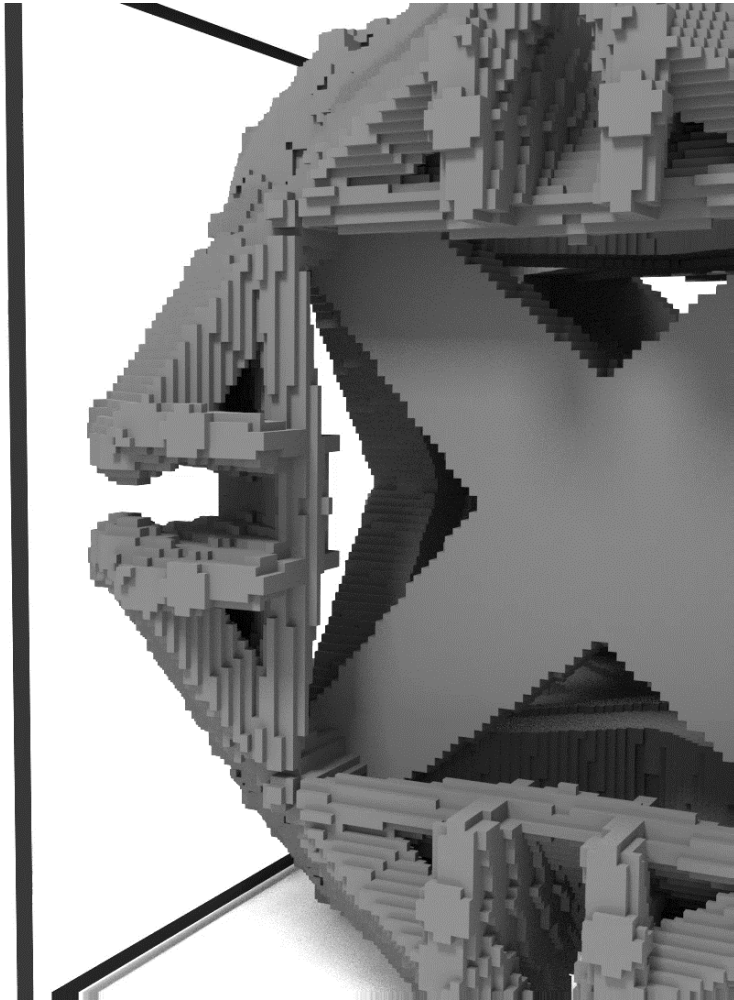
STEP 3: REDUCE TEMPLATE PARAMETERS



Range of material properties for Family 4

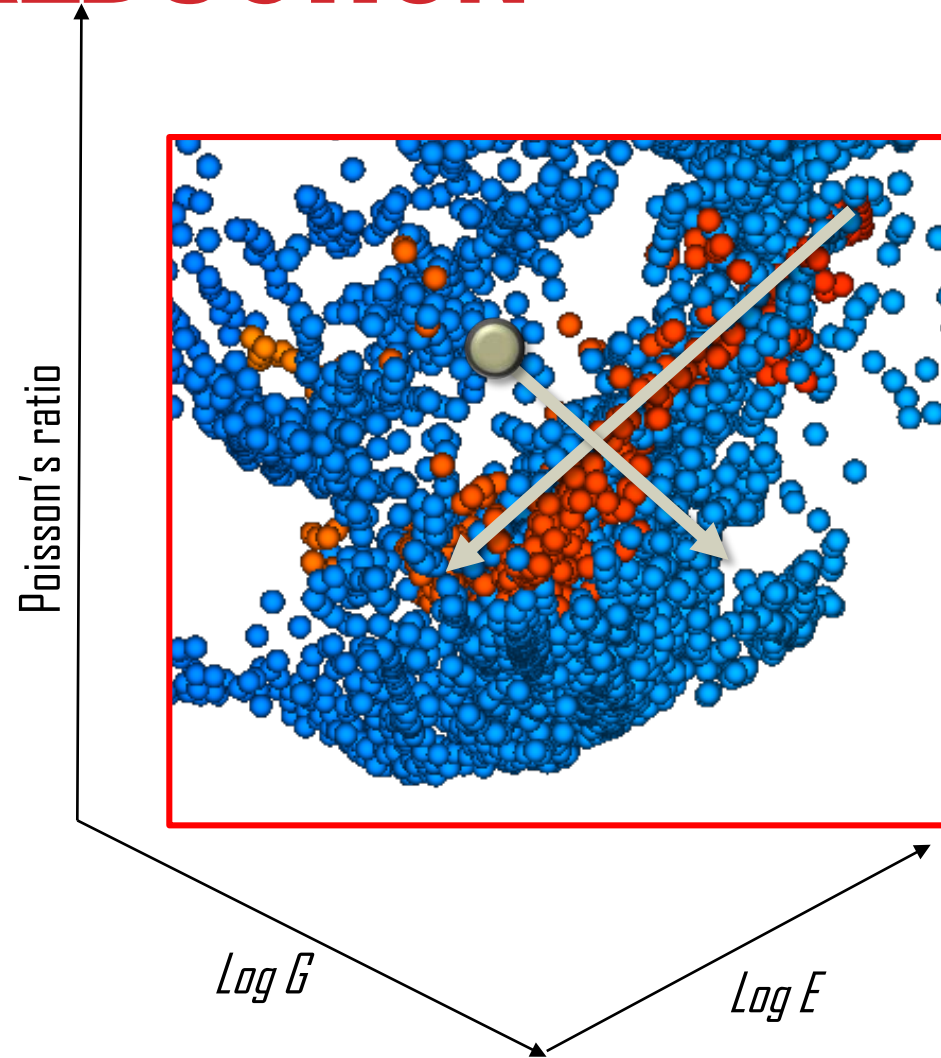
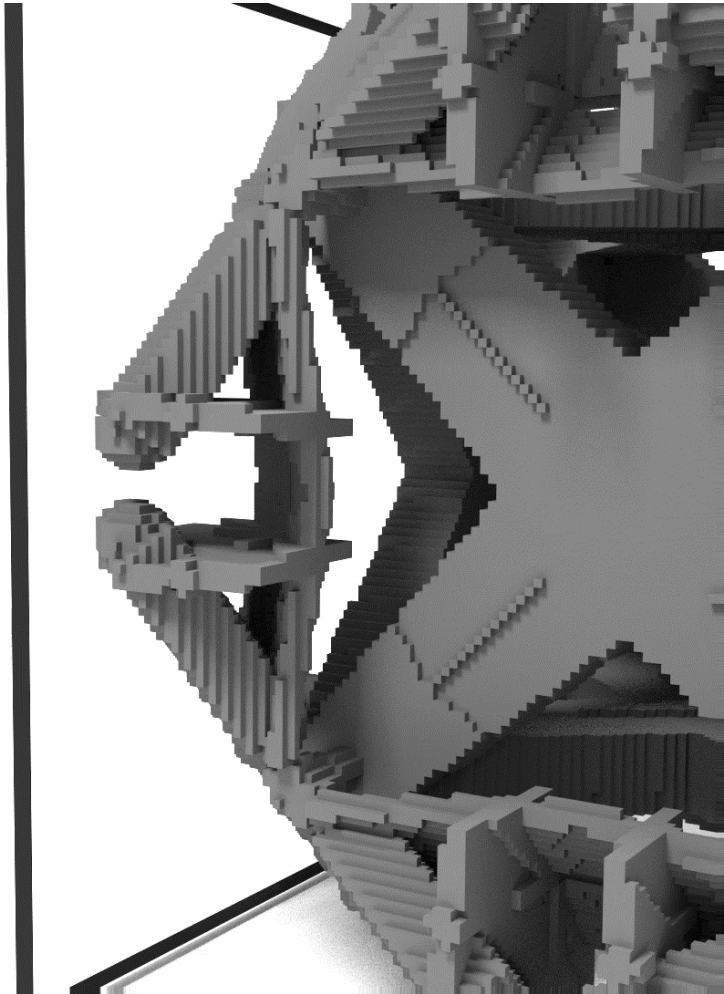
Reduced parameter directions

EXAMPLE: PARAMETER REDUCTION



Reducing joint beam thickness decreases Young's modulus E and Poisson's ratio.

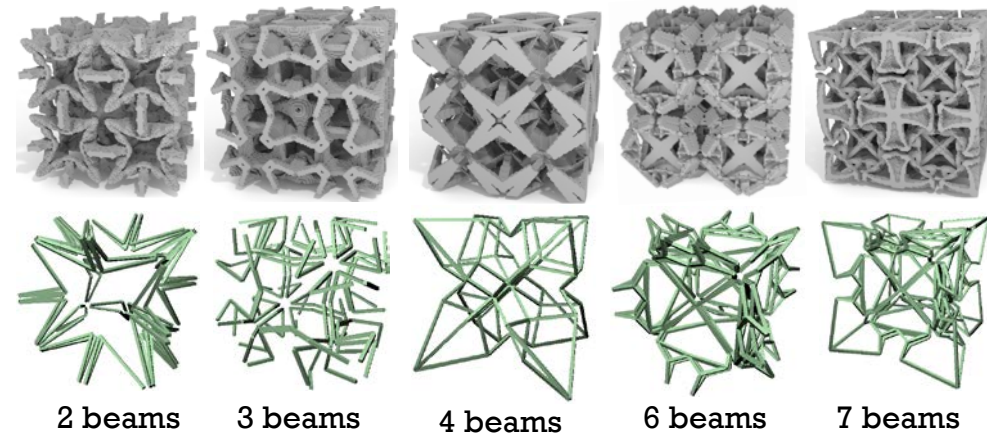
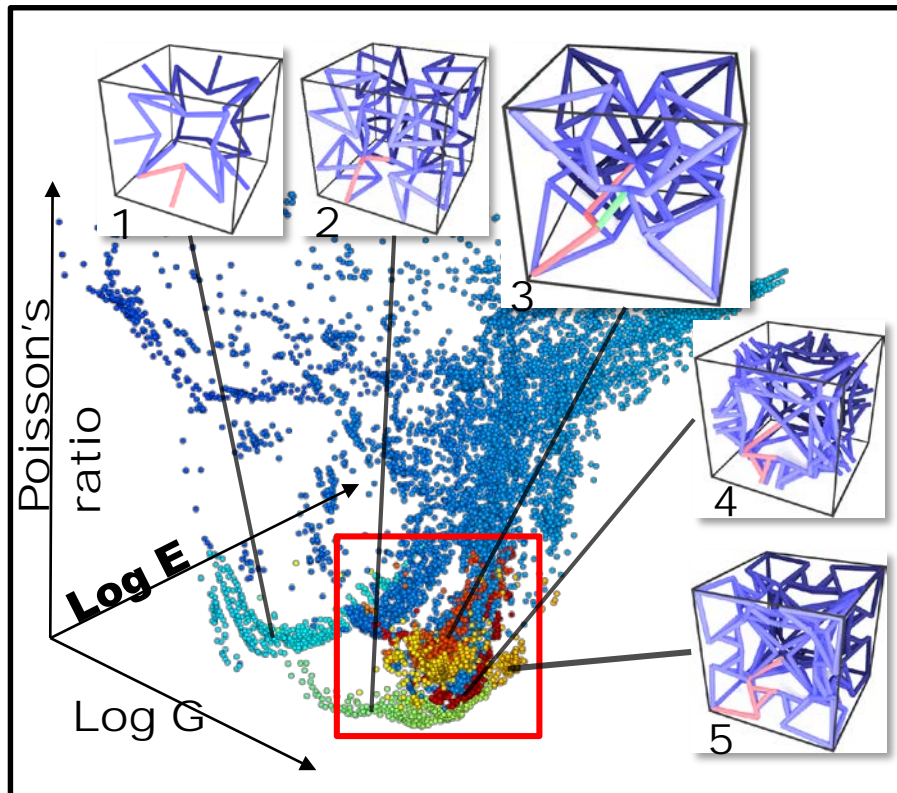
EXAMPLE: PARAMETER REDUCTION



Shifting joint location outwards increases shear modulus G and Poisson's ratio.

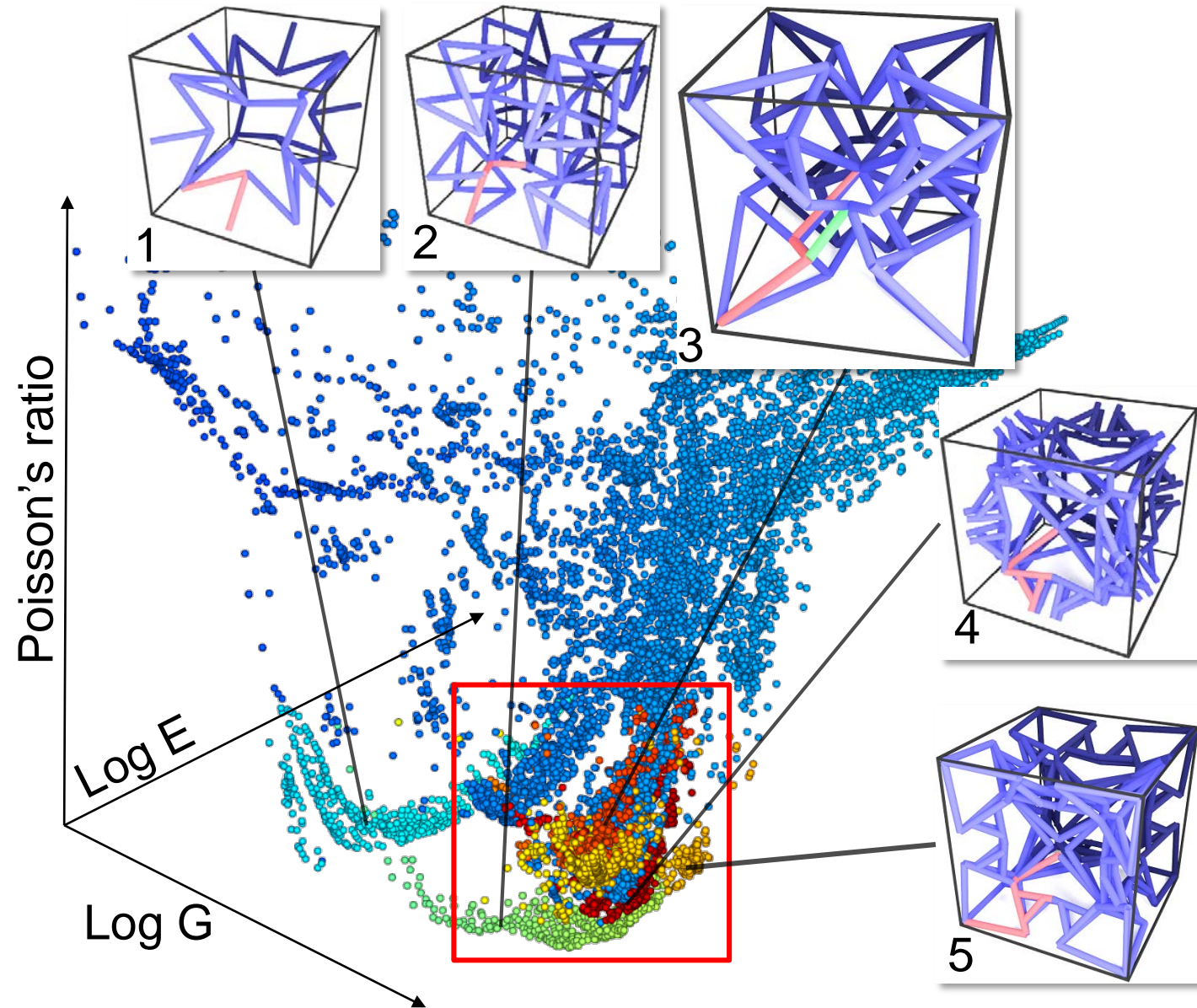
RESULT: DISCOVERY OF NEW AUXETIC MATERIALS

Five families of new microstructural materials with extremal auxetic properties



```
8 [params, withCap]= loadParams('param.txt');
9 startIdx = (family-1)*5;
10 param = params{startIdx + 1};
11 for j = 1:size(rparam,2)
12     r = rparam(j);
13     if(r>0)
14         param = (1-r)*param + r*params{startIdx+2*j};
15     else
16         param = (1+r)*param - r*params{startIdx+2*j+1};
17     end
18 end
19 nParam = size(param,2);
20 paramPerBeam=9;
21 nBeam = nParam/paramPerBeam;
22 for i = 1:nBeam
23     beamParam = [param(1+6*(i-1) : 6*i) param(nBeam*6 + 1 + (i-1)*3 : nBeam*6+i*3)];
24     st = drawCuboid(st, beamParam, withCap(family));
25 end
```

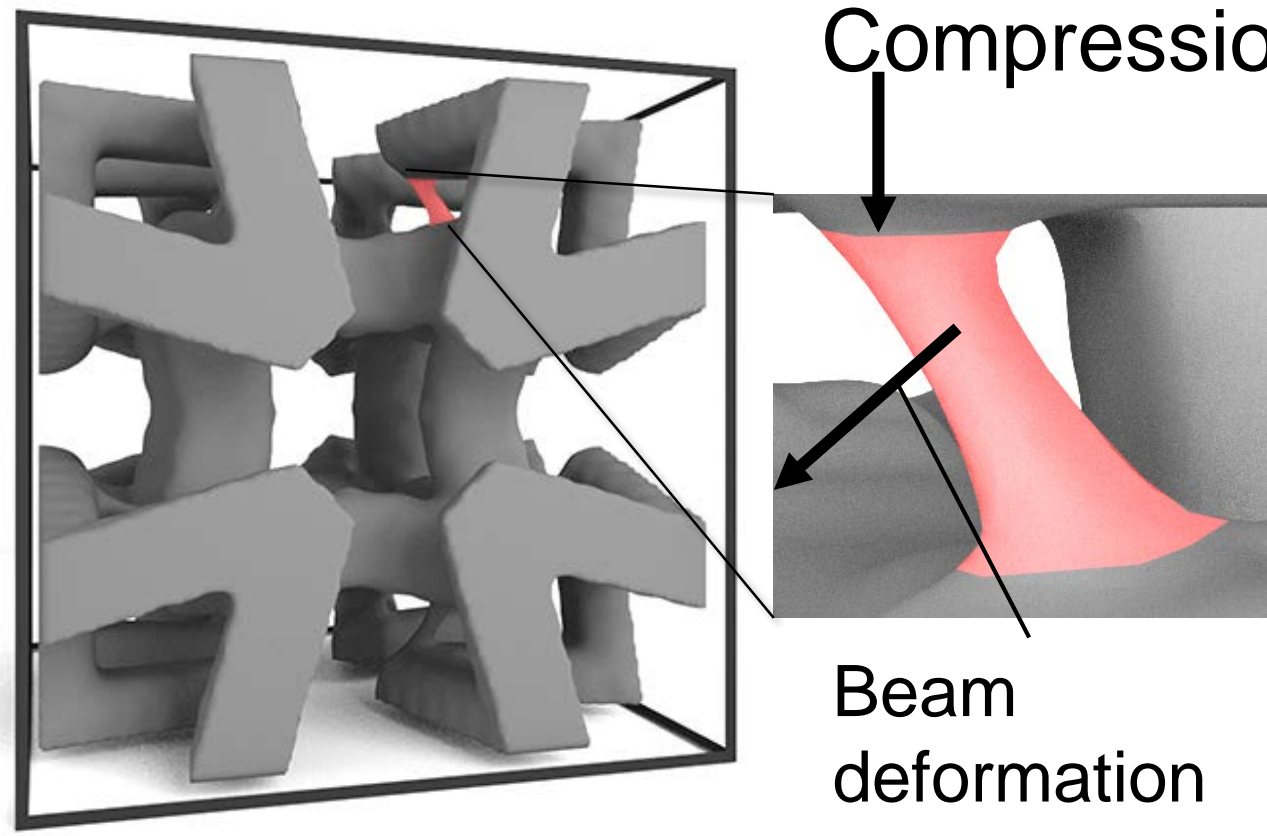
MICROSTRUCTURE SAMPLING USING TEMPLATES



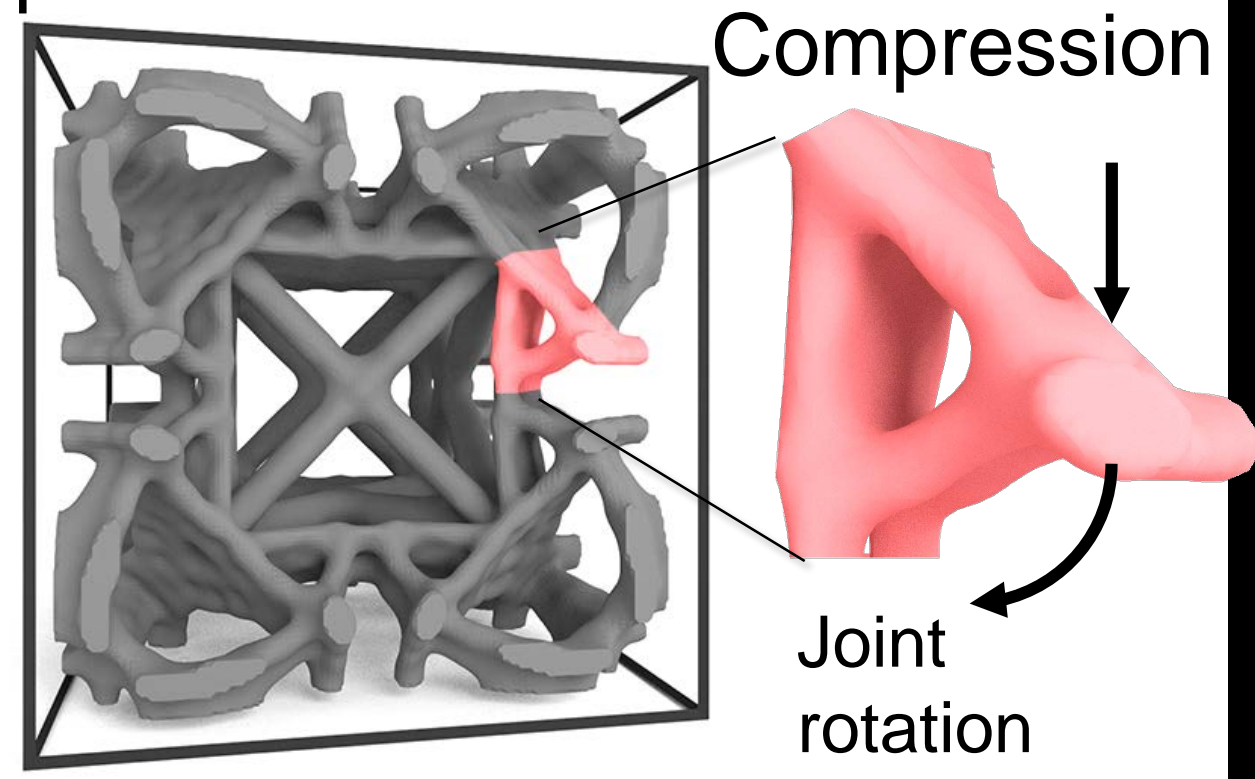
OUTPUT – PARAMETRIC MICROSTRUCTURES

```
1   %\param rparam row vector of 2 reduced parameters in the range [-1,1].
2   %\param family integer family index
3   %\param res integer of 3D grid resolution
4   %e.g. st = struct_template([0.1 0.2], 1, 64);
5   function st = struct_template(rparam, family, res)
6       st = zeros(res, res, res);
7       %full parameter
8       [params, withCap]= loadParams('param.txt');
9       startIdx = (family-1)*5;
10      param = params{startIdx + 1};
11      for j = 1:size(rparam,2)
12          r = rparam(j);
13          if(r>0)
14              param = (1-r)*param + r*params{startIdx+2*j};
15          else
16              param = (1+r)*param - r*params{startIdx+2*j+1};
17          end
18      end
19      nParam = size(param,2);
20      paramPerBeam=9;
21      nBeam = nParam/paramPerBeam;
22      for i = 1:nBeam
23          beamParam = [param(1+6*(i-1) : 6*i) param(nBeam*6 + 1 + (i-1)*3 : nBeam*6+i*3)];
24          st = drawCuboid(st, beamParam, withCap(family));
25      end
26      st = mirrorCubicStructure(st);
27  end
```

DISCOVERED AUXETIC MECHANISMS

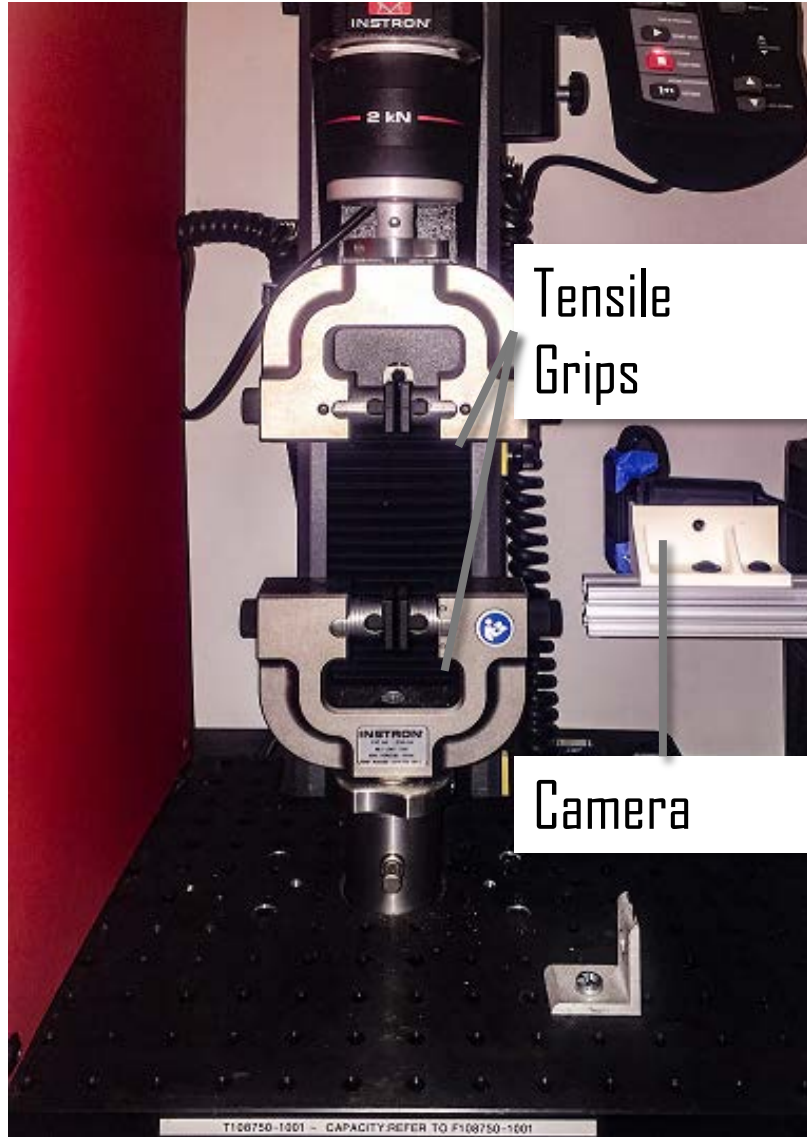


Slanted column



Rotating triangle

EXPERIMENTAL VALIDATION



Test Machine



Tensile Test

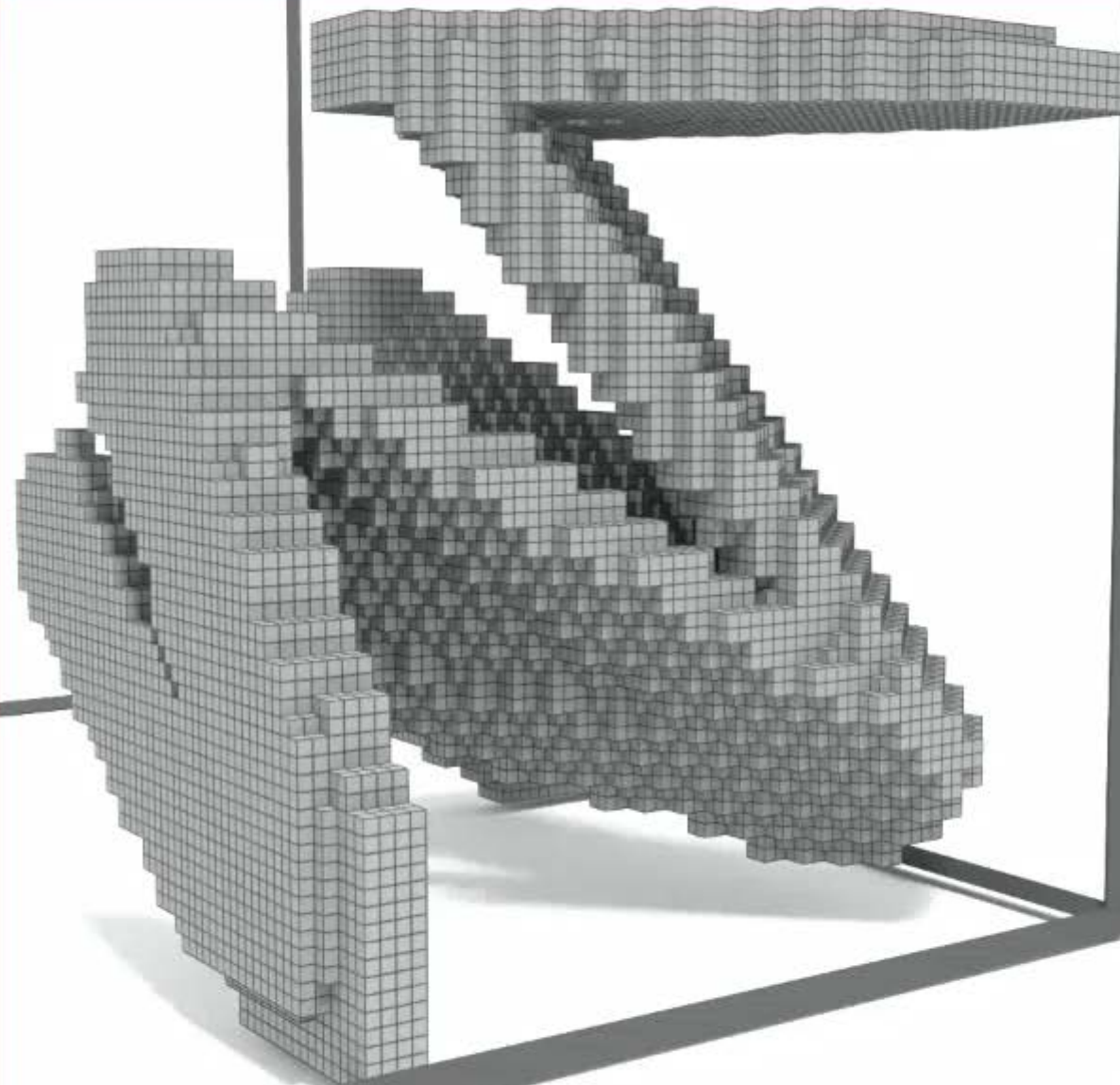


Compression
Test

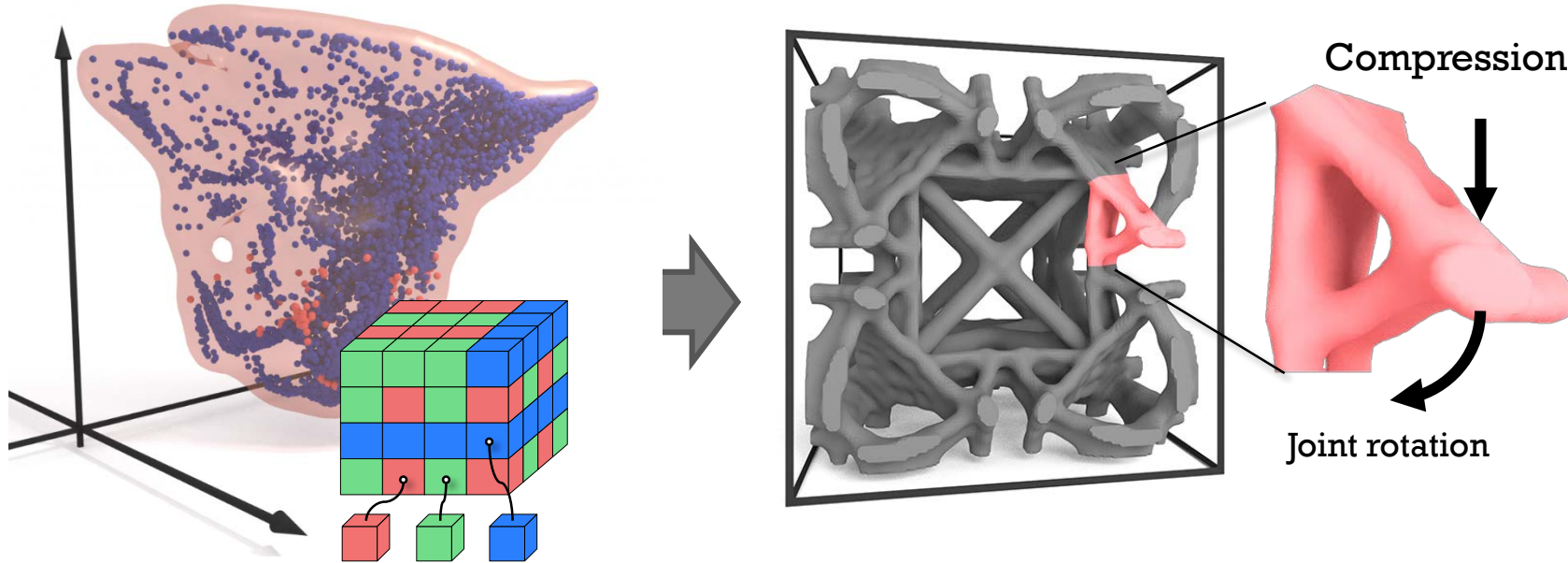
Measurement (20x)



Simulation



SUMMARY: FROM FUNCTIONS TO MECHANISMS



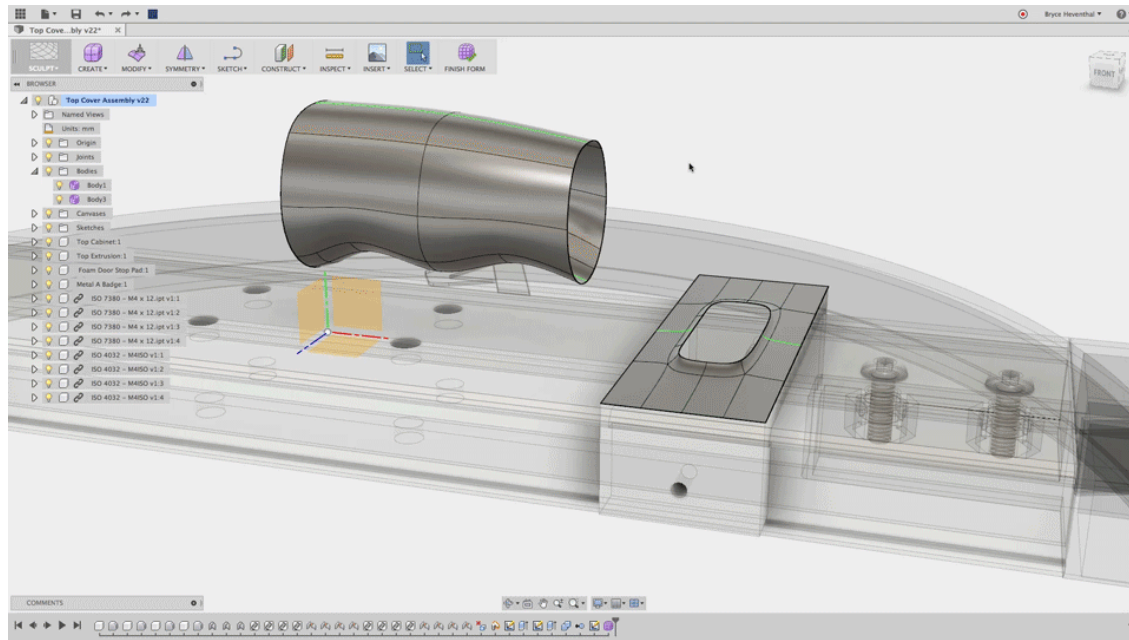
Microstructure Gamut

Mechanism

QUESTION #3:

**HOW TO SYNTHESIZE DESIGNS WITH
DESIRED FUNCTION?**

DIRECT DESIGN VS. GENERATIVE DESIGN

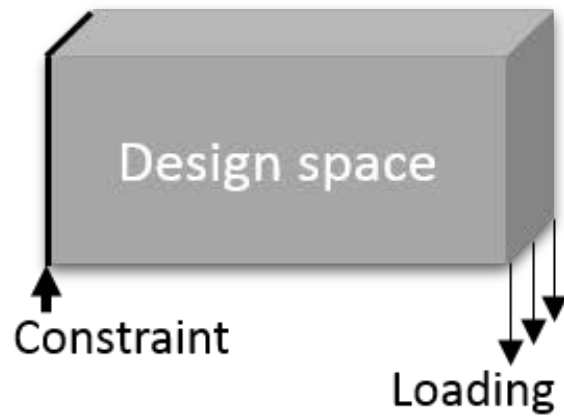


Direct Design

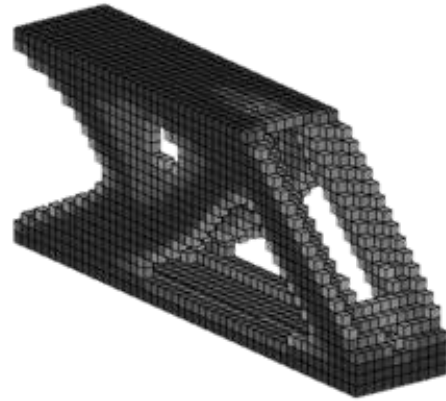


Generative Design

TOPOLOGY OPTIMIZATION



Problem definition

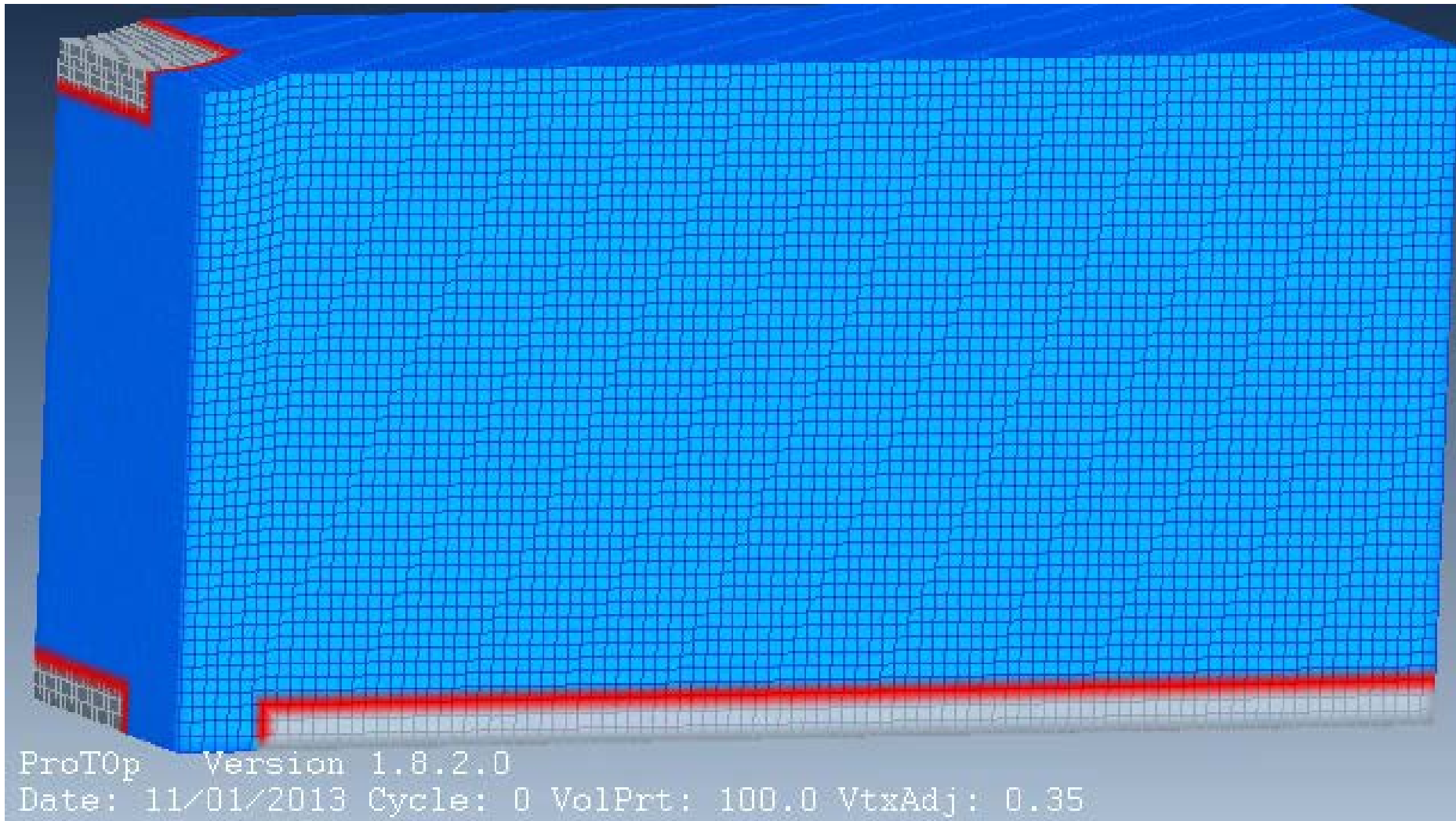


Topology optimization
output

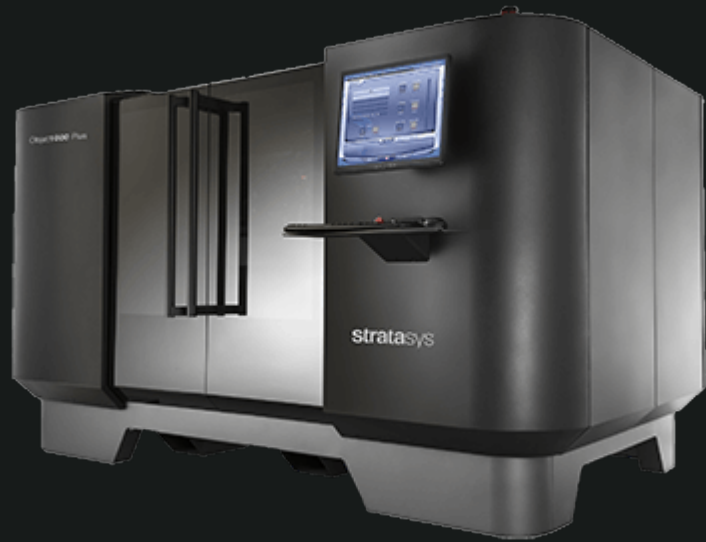


Topology optimized
part

TOPOLOGY OPTIMIZATION

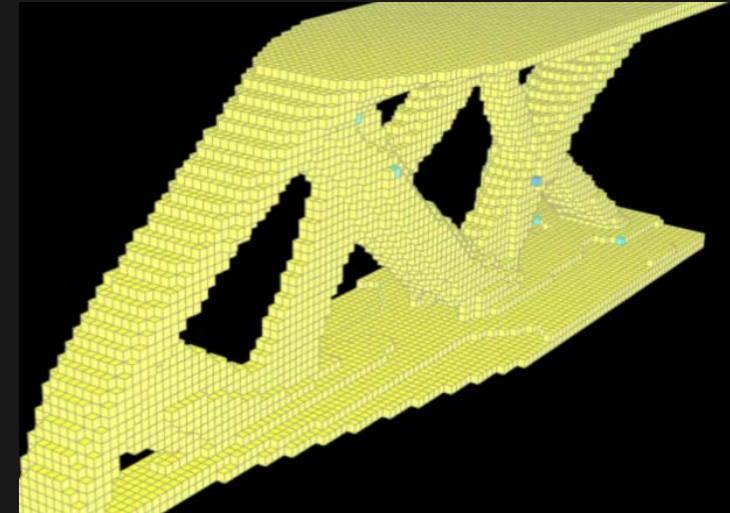


CHALLENGES



Hardware: Object-1000 Plus

- Up to 39.3 x 31.4 x 19.6 in.
- 600dpi (~40 microns)
- 5 trillion voxels

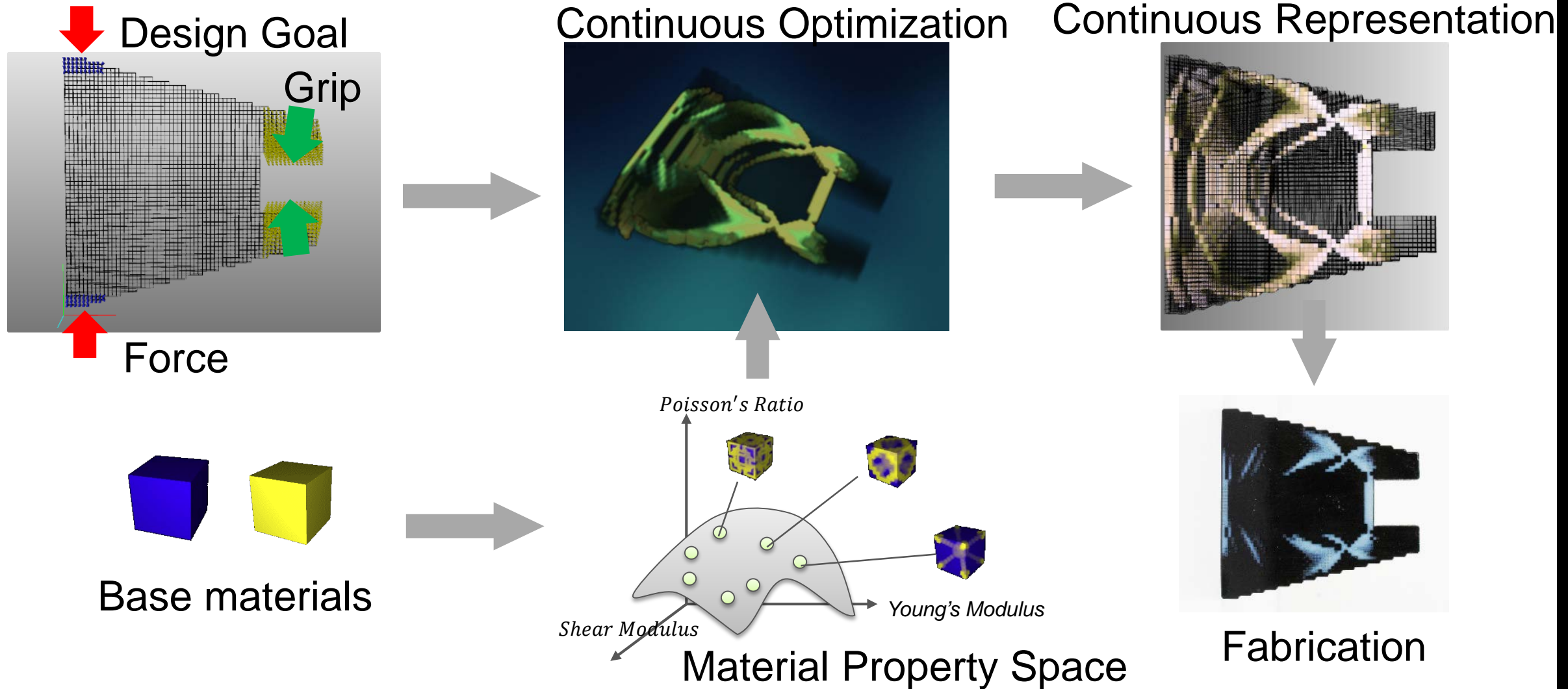


Software: SIMP Topology Optimization

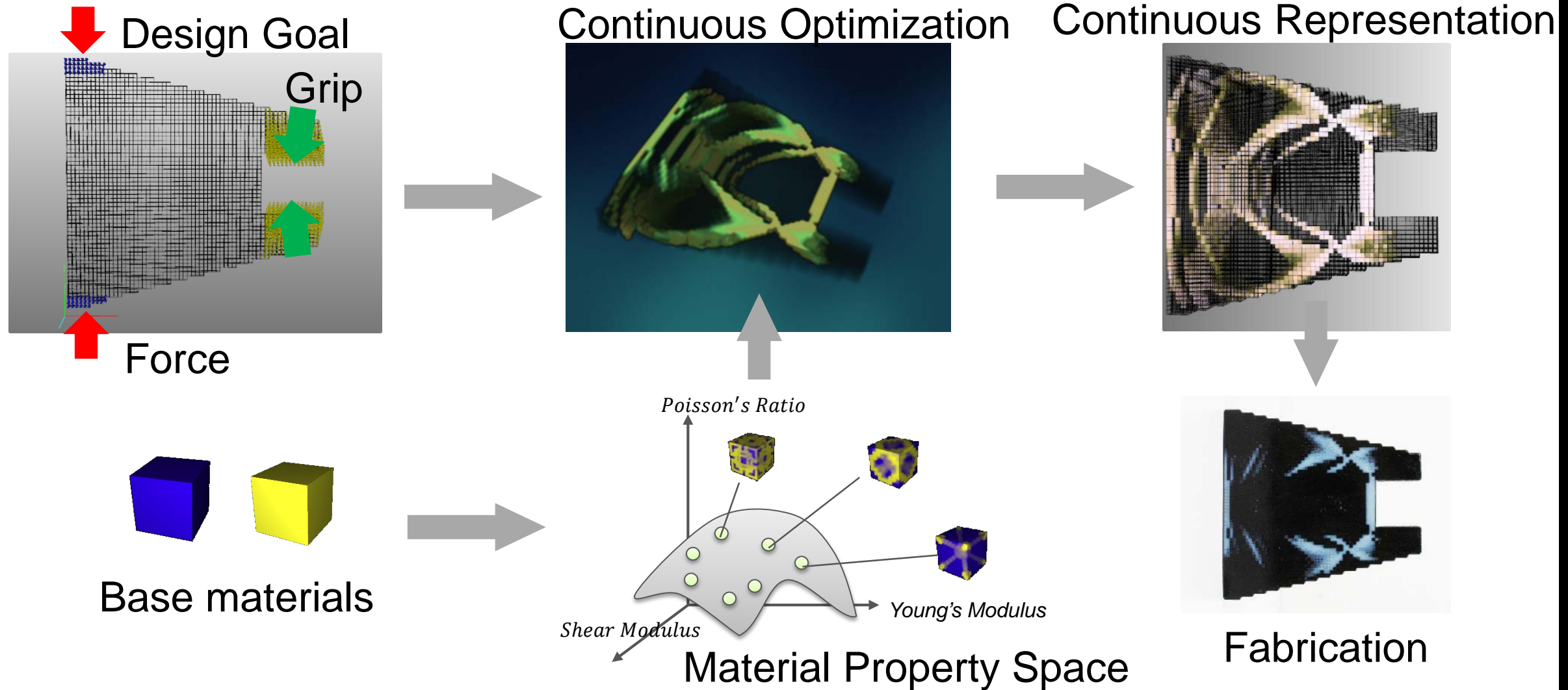
Up to millions of elements

Difficult to handle multiple materials

TWO-SCALE TOPOLOGY OPTIMIZATION



TWO-SCALE TOPOLOGY OPTIMIZATION



TOPOLOGY OPTIMIZATION - FABRICATION

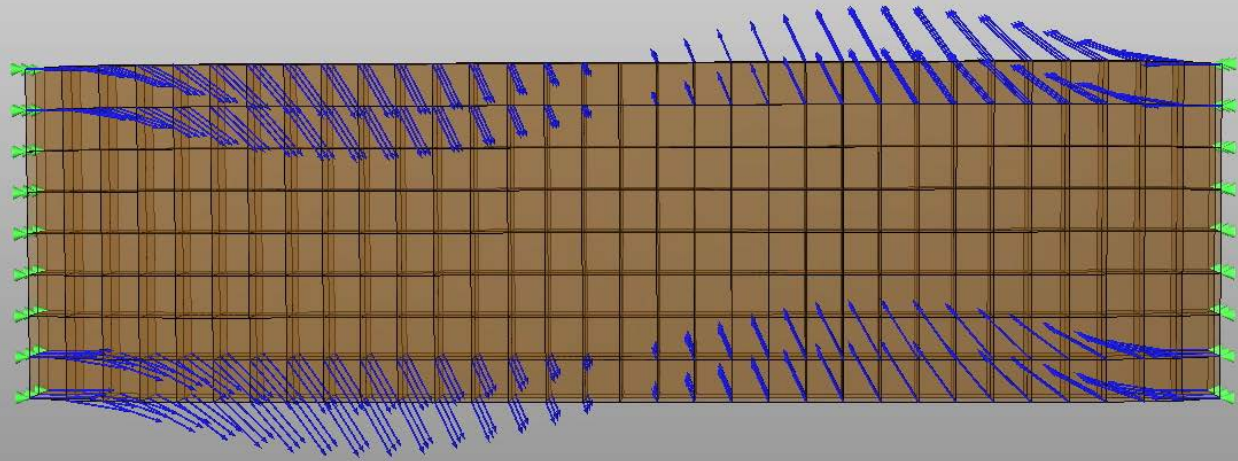


A 3D-printed gripper



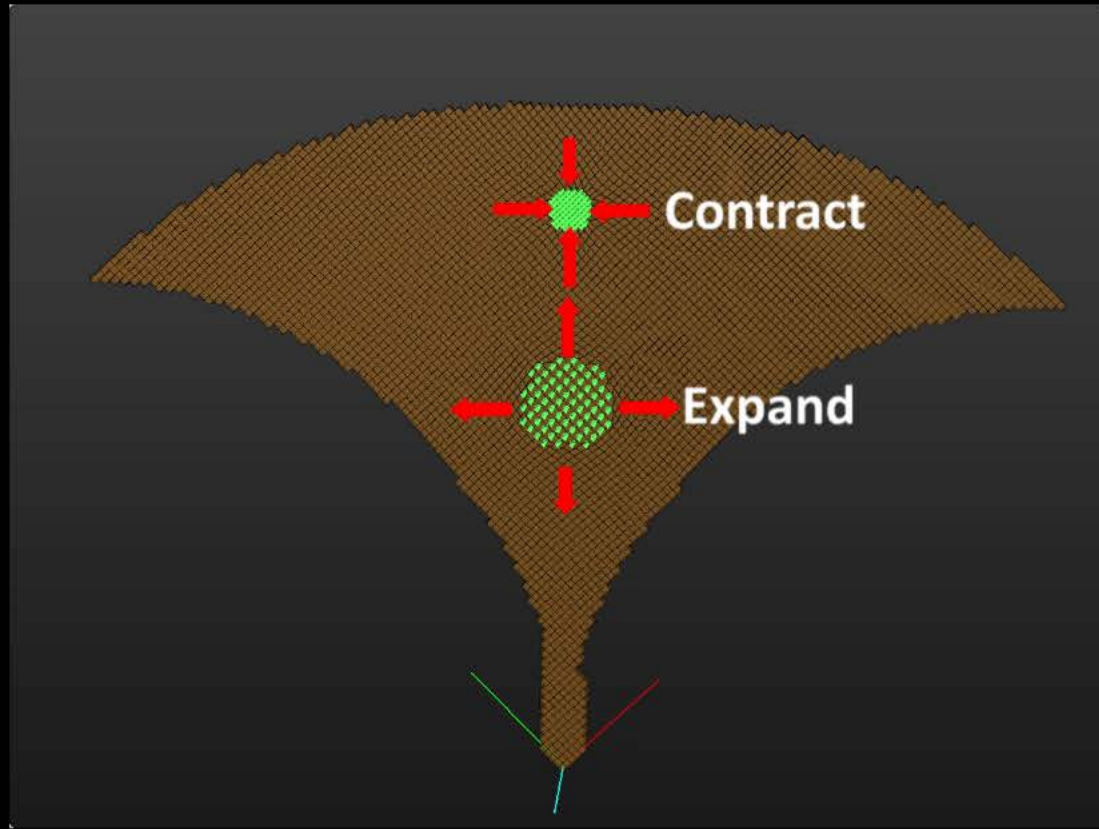
Gripper in action

EXAMPLE: TARGET DEFORMATION

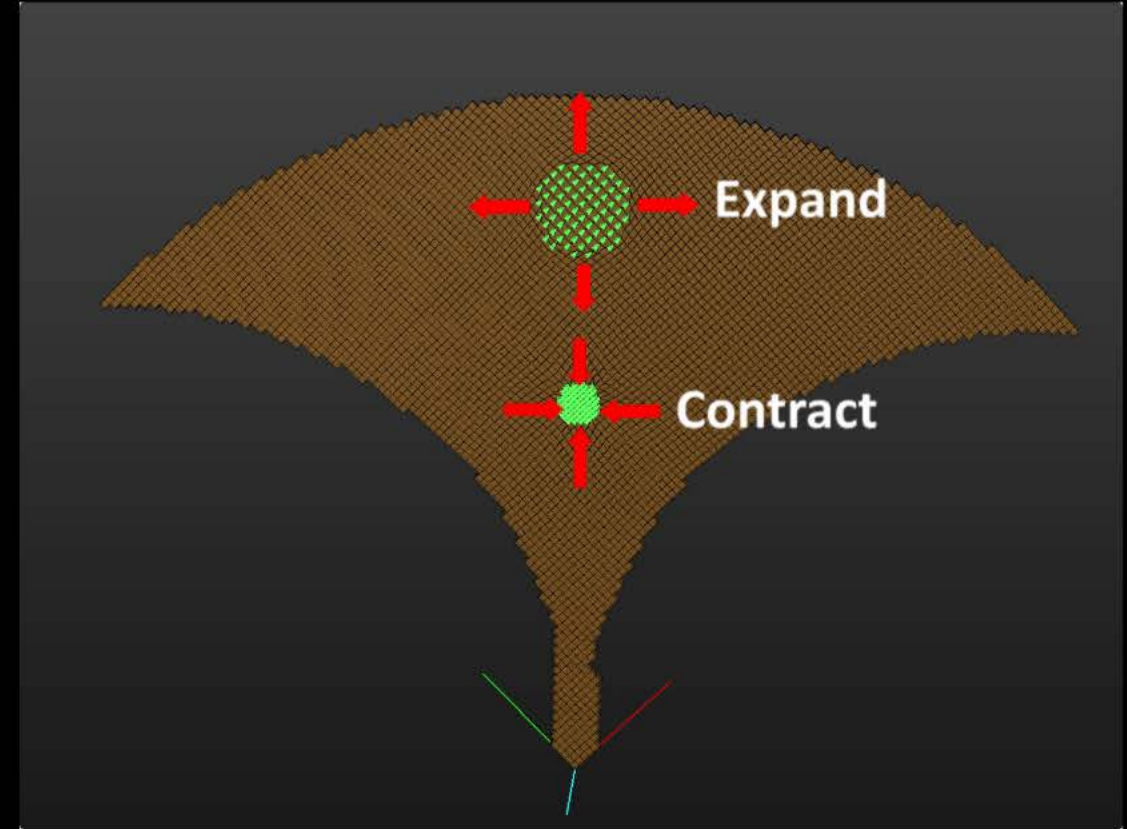


Optimizing for target deformation
on boundary cells

EXAMPLE : SOFT ROBOTIC FISH

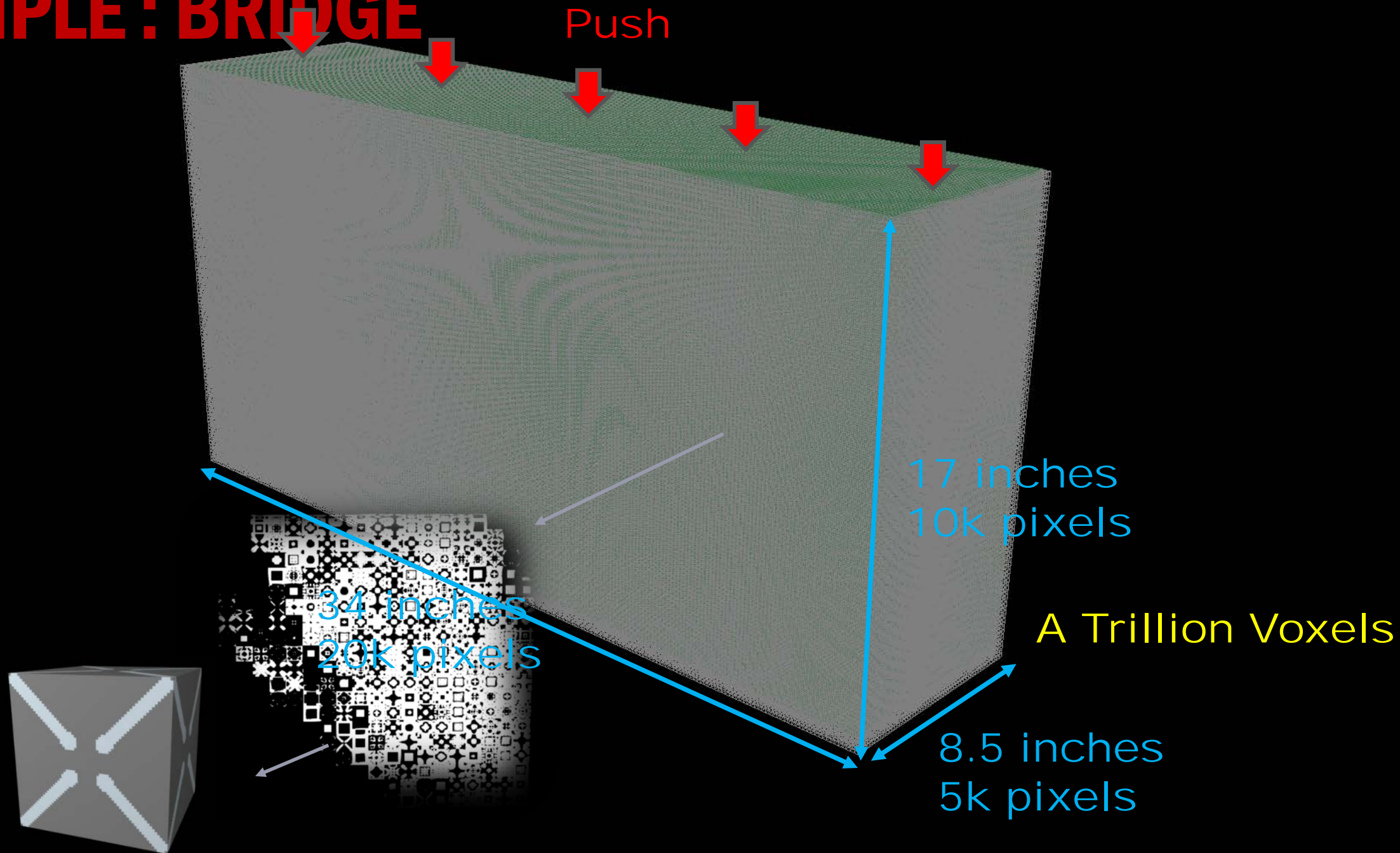


Target 1: flapping down

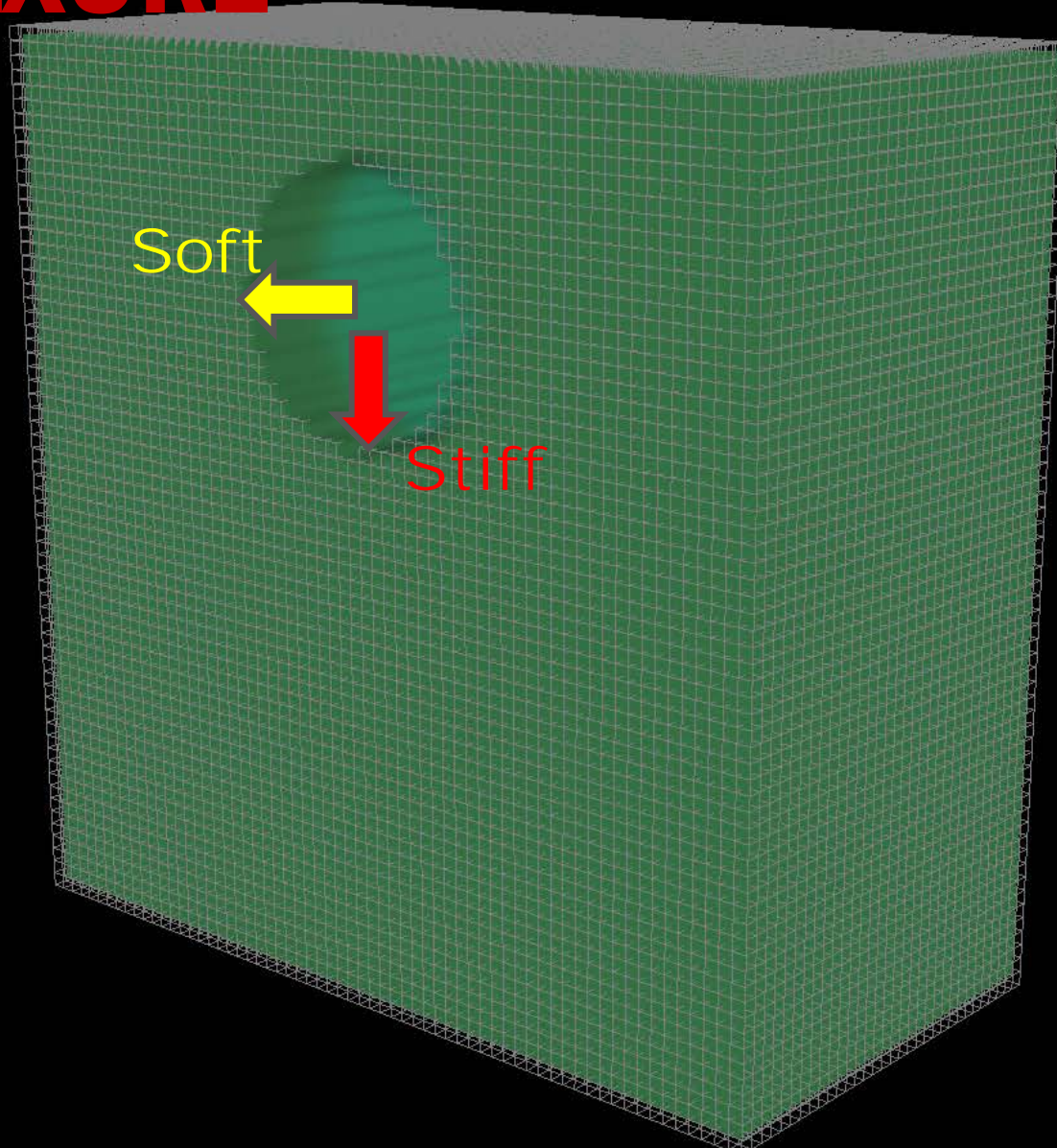


Target 2: flapping up

EXAMPLE: BRIDGE



EXAMPLE : FLEXURE



Multiple objectives

Topology Optimization Iterations

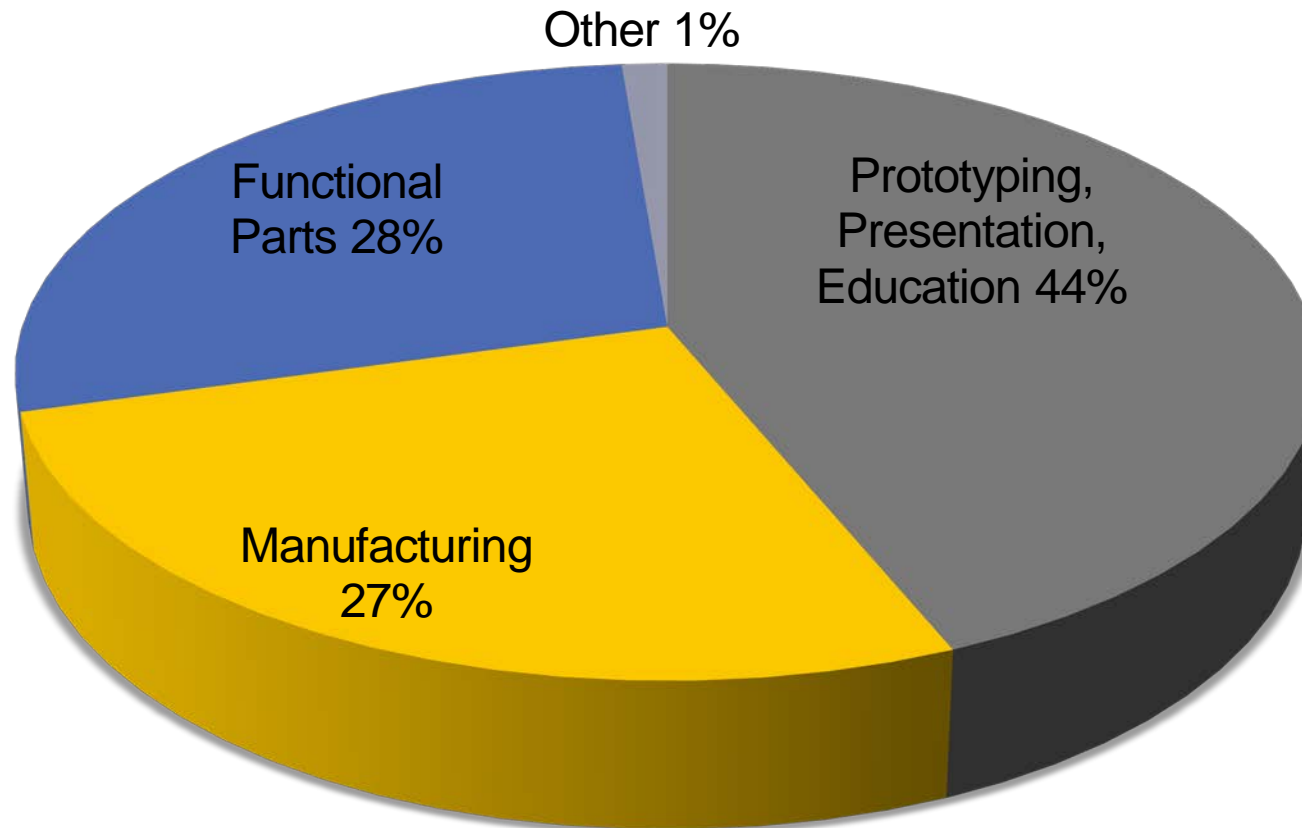


SUMMARY: THREE FUNDAMENTAL QUESTIONS

- 1. How to compute the space of possible material properties?**
- 2. How to discover material families with extreme properties?**
- 3. How to synthesize designs with desired function?**

OUTLOOK

Multi-material 3D printing will become an important manufacturing method

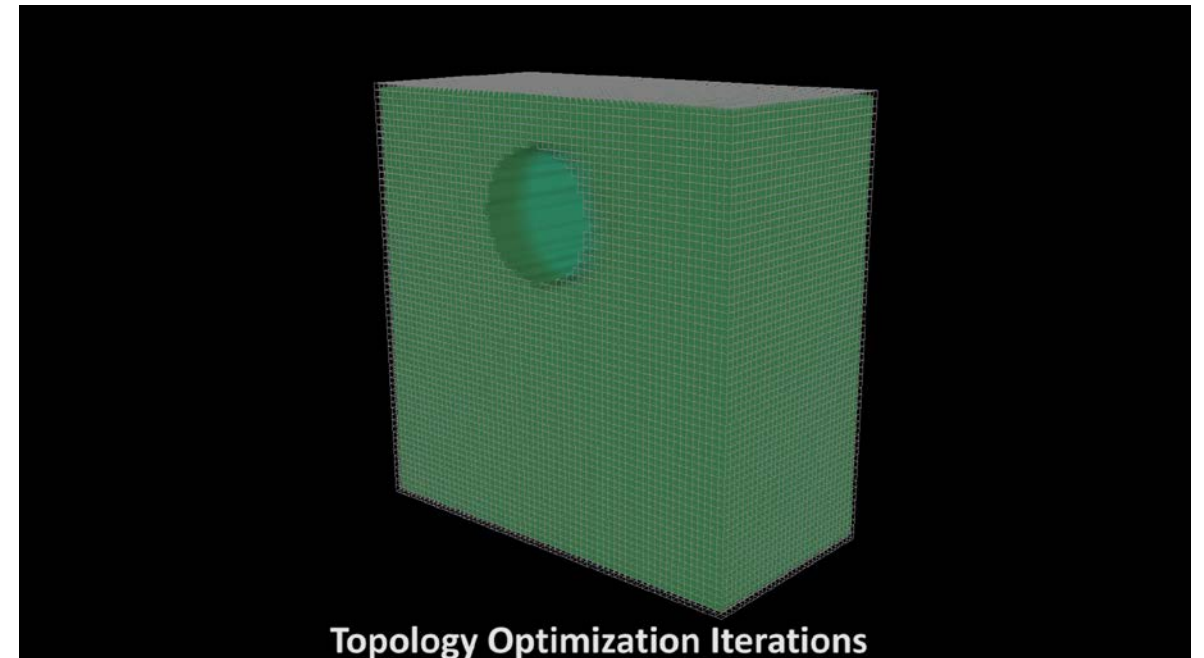
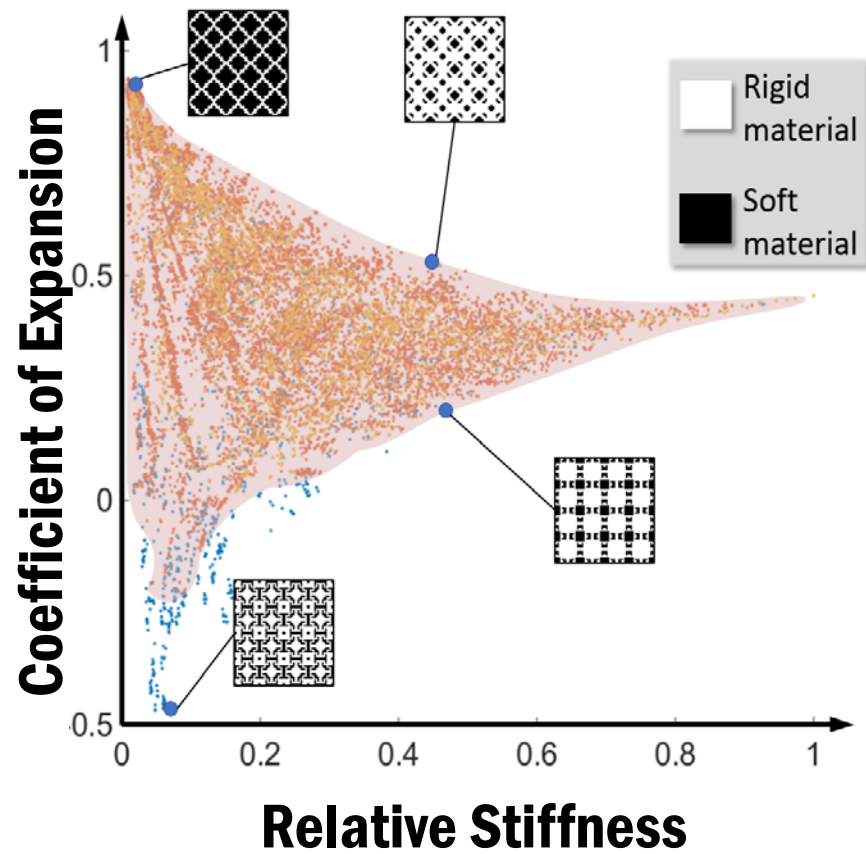


Source: Wohlers Report

OUTLOOK

Computational methods will redefine the design process

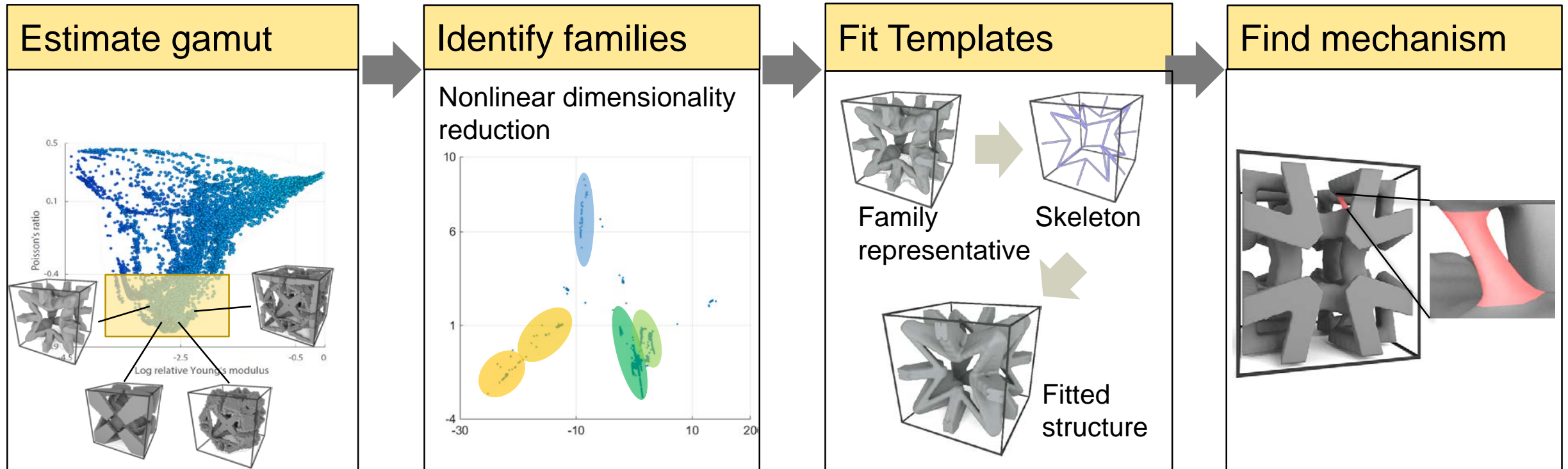
- Engineers will specify material properties and not materials
- Engineers will specify product function and not individual elements



OUTLOOK

Computational methods will redefine the process of scientific discovery

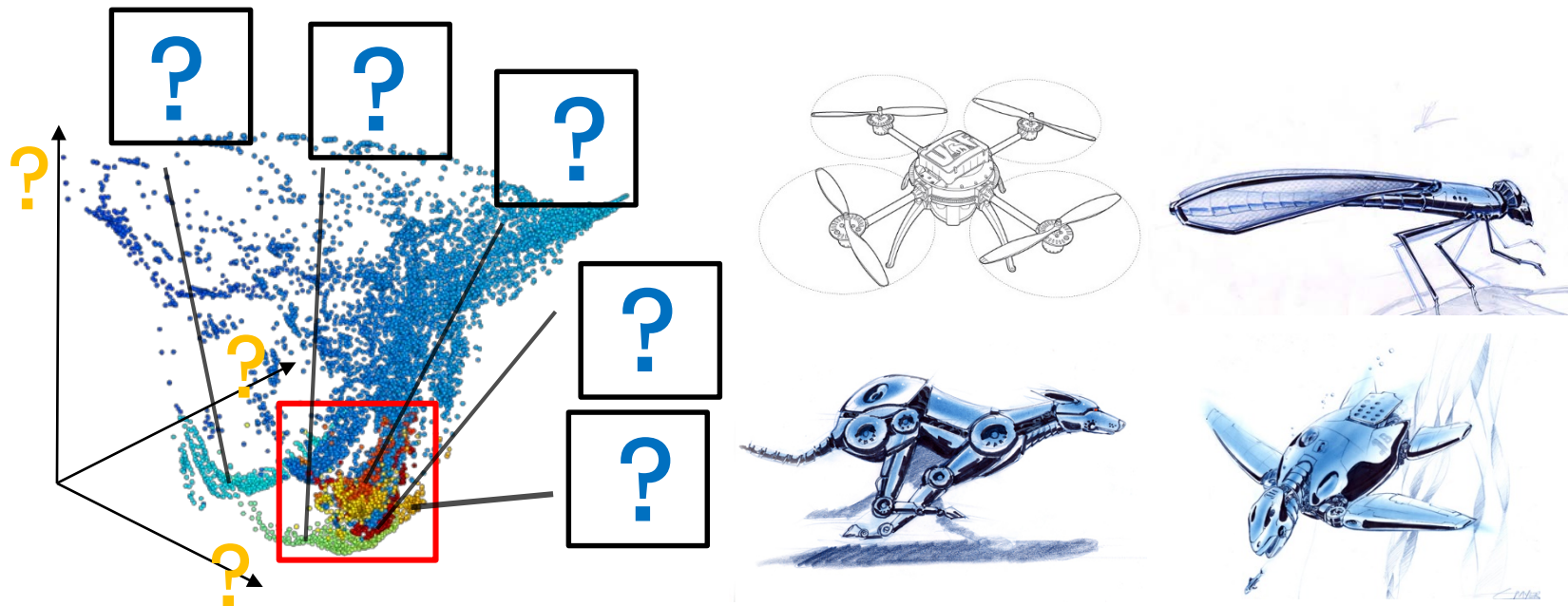
- Material discovery will become more automated, relying on physical simulation, data generation, and machine learning



OUTLOOK

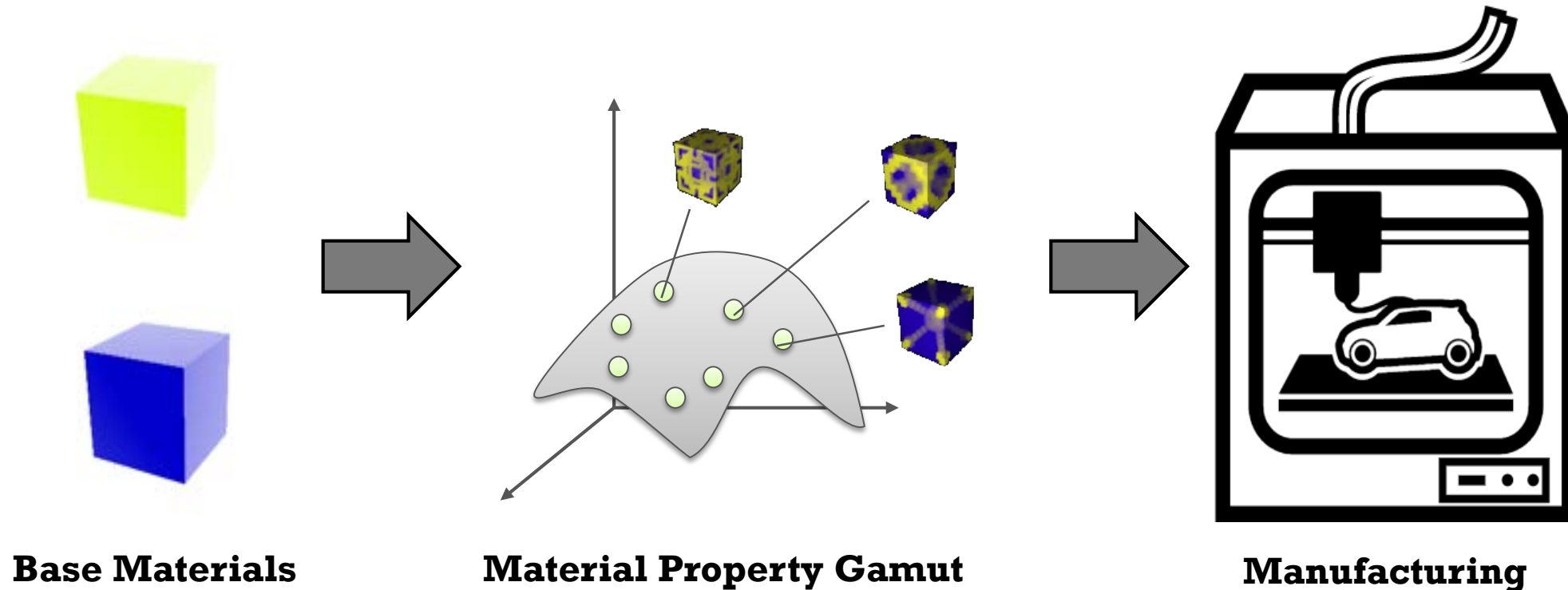
Computational methods will redefine cyber-physical system design and mechanism understanding

- Agile drones, fast walkers, efficient swimmers
- Discover the optimal underlying mechanisms



OUTLOOK

Computational methods will guide the development of new manufacturing processes



THANK YOU