# **Computer-on-Watch: Imagery Analysis**

# **Greg Angelides**

**MIT ILP R&D Conference** 

14 November 2019



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# **Global AI Technology Race**



"Al is probably the most important thing humanity has ever worked on. I think of it as something more profound than electricity or fire."

**Google CEO Sundar Pichai, January 2018** 



"For years I've been telling people that the internet was the appetizer, and that AI is the main course. AI is the way of the future, something whose impact will be broader and deeper." Baidu CEO Robin Li, November 2018



"Artificial intelligence is the future, not only for Russia, but for all humankind... Whoever becomes the leader in this sphere will become the ruler of the world."

**Russian president Vladimir Putin, September 2017** 

Significant global efforts to develop advanced AI systems and lead in this key field



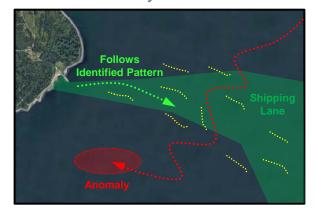
# **Example Applications of Al**

### **High-Throughput Data Collection**

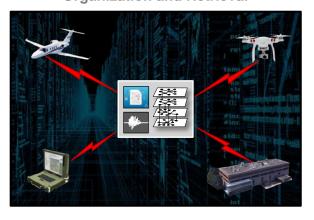
AI Supporting Data Analysis



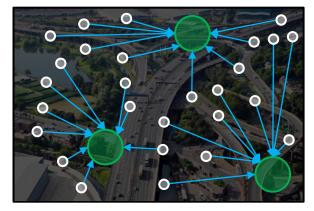
Pattern-of-Life Anomaly Detection



#### **Communications** Organization and Retrieval

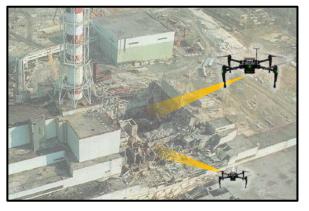


Logistics Resource Allocation



### Hazardous Area Assessment

**UAVs\* Surveil Danger Zones** 



Autonomous Transport UAV\* Autonomous Resupply

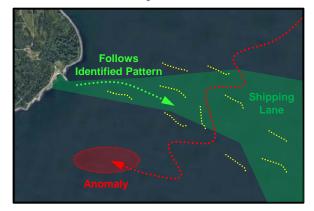




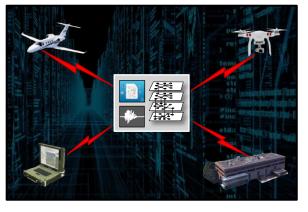
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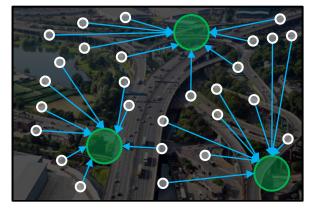
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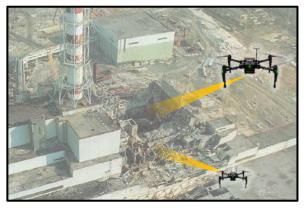


Logistics Resource Allocation



### Hazardous Area Assessment

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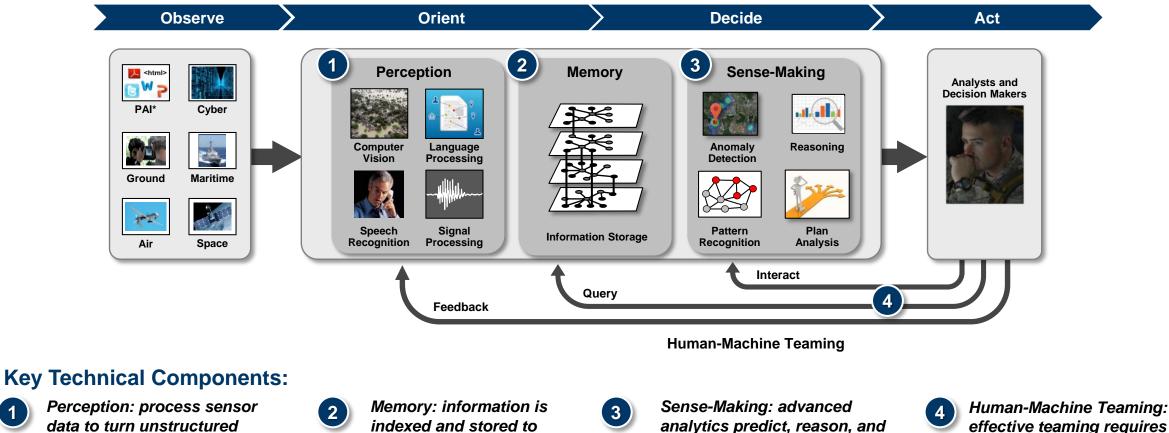
Autonomous Transport UAV\* Autonomous Resupply





# **Cognitive Computer on Watch Framework**

### A cognitive assistant to support 24/7 data analysis



and *Human-Machine Teaming:* effective teaming requires efficient interaction and a natural language interface

information

content into structured

support decision making

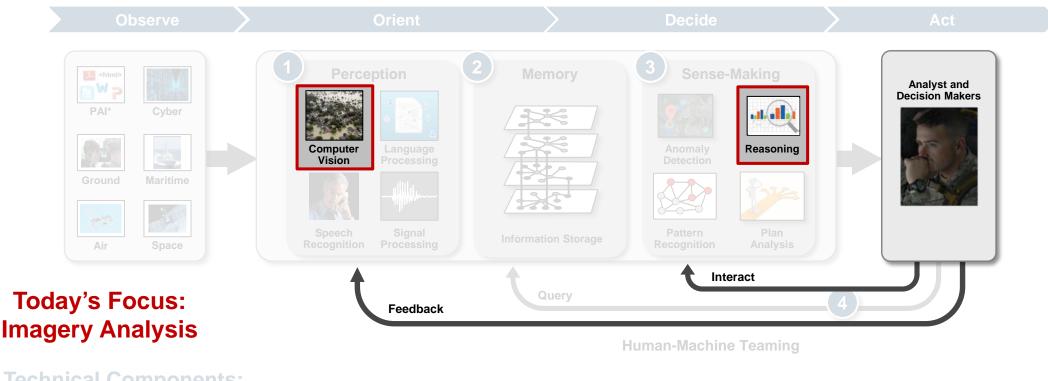
facilitate search and retrieval

of historical data



# **Cognitive Computer on Watch Framework**

### A cognitive assistant to support 24/7 data analysis



### **Key Technical Components:**



Perception: process sensor data to turn unstructured content into structured information Memory: information is indexed and stored to facilitate search and retrieval of historical data Sense-Making: advanced analytics predict, reason, and support decision making Human-Machine Teaming: effective teaming requires efficient interaction and a natural language interface



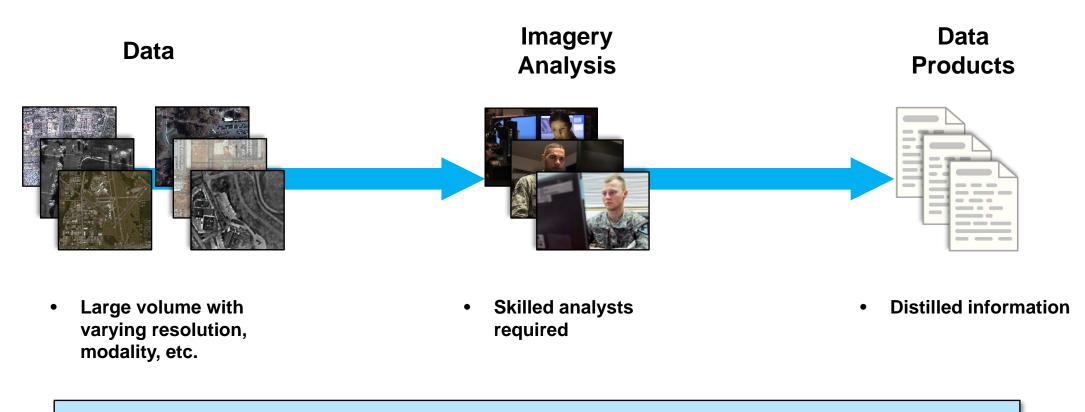
• Introduction



- Accelerating Imagery Analysis
- Interactive and Interpretable AI
- Summary



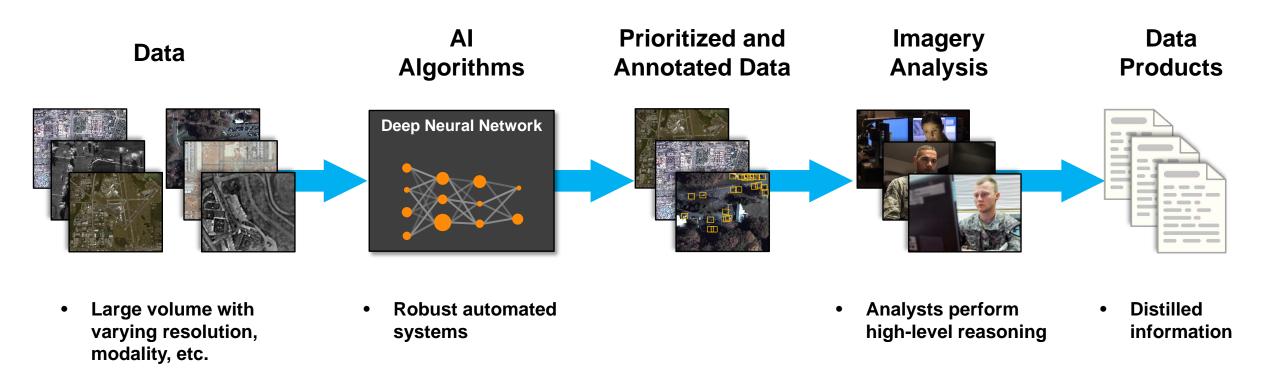
# **Current Image Processing Pipeline**



• Challenging for limited numbers of skilled analysts to assess large volume of collected imagery



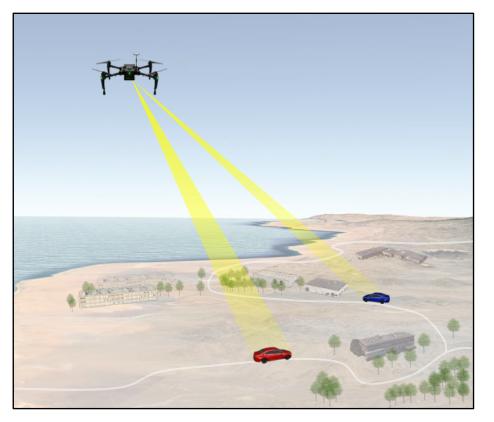
# **Image Processing Pipeline Leveraging AI**



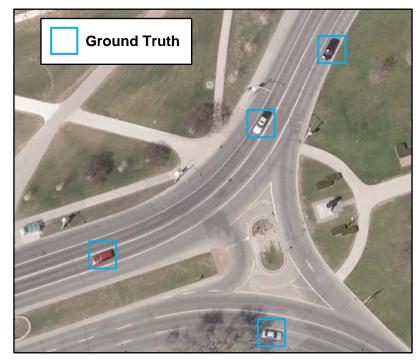
- Challenging for limited numbers of skilled analysts to assess large volume of collected imagery
- Goal: Leverage advances in computer vision to extract relevant information from traditional sensors



# Vehicle Classification and Detection



# Training Data: Cars Overhead with Context (COWC) Research Dataset\*



- Overhead imagery with 15 cm resolution
- Data collected from six locations, across four countries
- 5,284 100x100m images
- 32,716 annotated cars, 58,247 annotated negative examples

\* Mundhenk, T. Nathan, et al. "A Large Contextual Dataset for Classification, Detection and Counting of Cars with Deep Learning." European Conference on Computer Vision. Springer International Publishing, 2016.



• Goal: Differentiate cars from car-like objects (boats, trailers, etc.)

### **Example Manually Annotated Training Images**



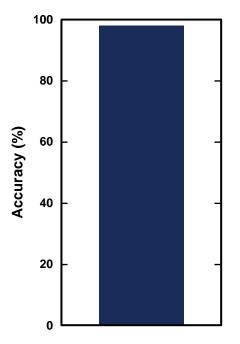
Training Data: Manually labeled 90,963 car and background examples

Estimated labeling time: >250 hours\*

• Very high classification accuracy achievable with sufficient training data

\*Based on a rate of 10 seconds per sample

## Classification Model Performance





Accuracy

### **Data Rich Environments**

- Labels are free or crowd sourced
- Data is easy to collect

# **Data Starved Environments**

- Data may be challenging to label for machine learning applications
- Data are difficult to collect because content of interest is rare

# Learning Curve Human-Level Performance Deep Learning Breakthroughs

**Data Starved** 

**Environments** 

Number of Labeled Samples

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Data Rich

Environments



Accuracy

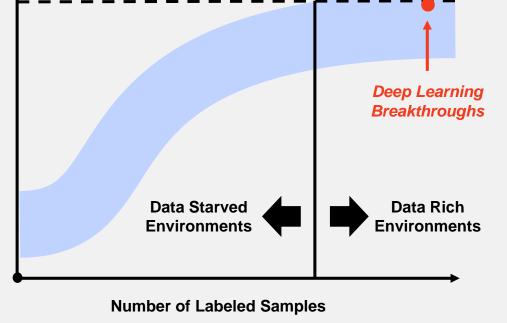
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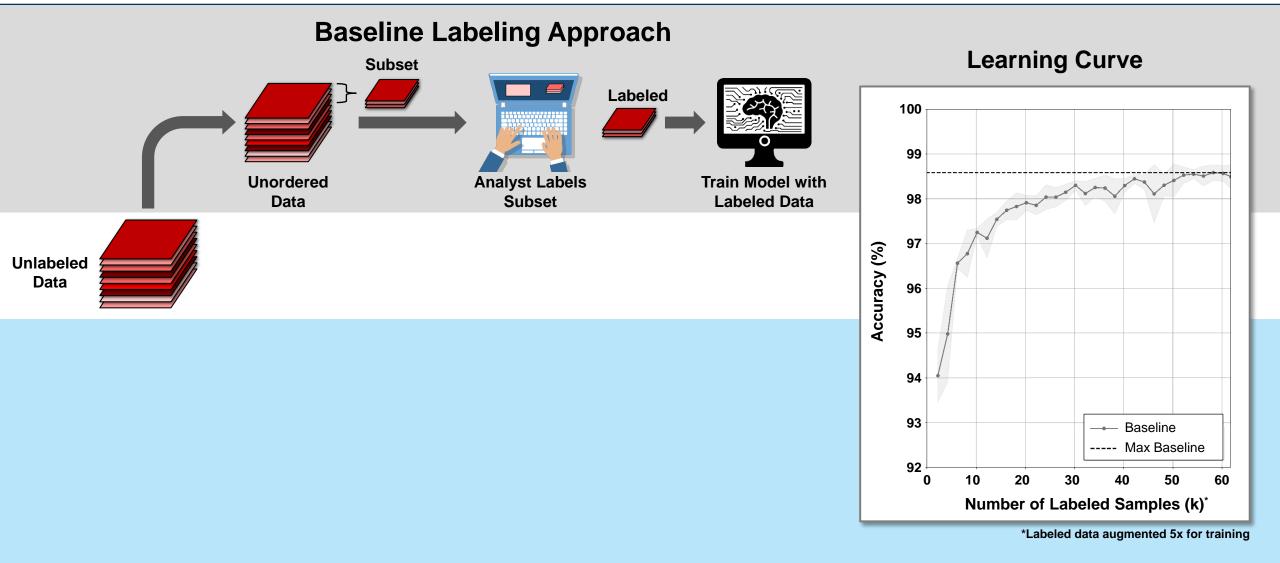
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# Learning Curve





# Impact of Data Quantity on System Performance



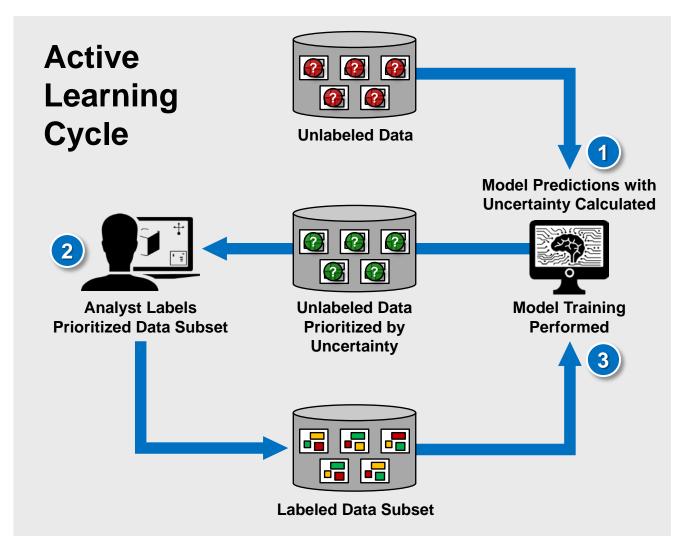


# **Overview:**

- In an active learning framework, training samples are prioritized for labeling according to model uncertainty
- This prioritizes samples that will have the largest impact on model performance

# Technical Challenge:

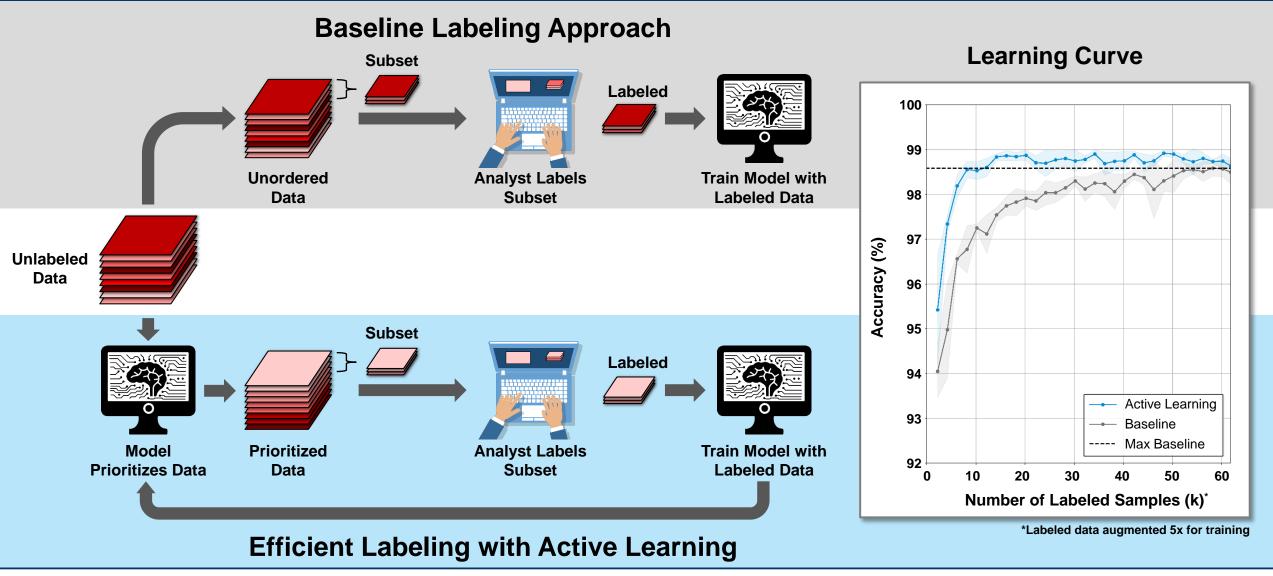
- *Limitation:* Accurate estimation of model uncertainty is challenging
- Solution Employed: Uncertainty estimated by sampling multiple model architectures\*



\* Gal, Yarin, and Zoubin Ghahramani. "Bayesian convolutional neural networks with Bernoulli approximate variational inference." arXiv preprint arXiv:1506.02158 (2015).



# Impact of Data Quantity on System Performance





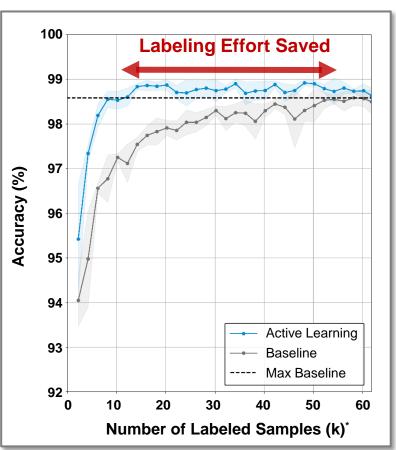
## Highlights

• Efficient labeling reveals that only ~1/5 of the data need to be labeled to achieve maximum baseline performance

### Samples Prioritized with Active Learning



# Learning Curve



\*Labeled data augmented 5x for training



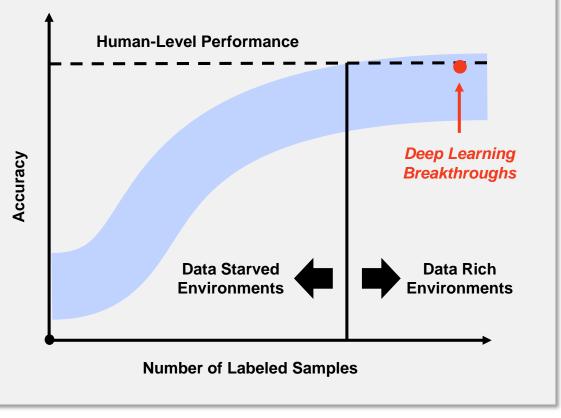
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Learning Curve





- Limited real data available for training AI systems on many targets of interest
- Simulation can be used to generate training data on these targets

# **Example Simulation Environments Developed**



Toronto, Ontario

Ft. Devens (Ayer, MA) • 8.3 km<sup>2</sup>



Joint Base Cape Cod (JBCC)

• 340 km<sup>2</sup>



- Unity game engine simulations incorporate real-world information
  - Height maps
  - Tree locations
  - Road locations
  - Building locations

• Implemented semi-automated procedural pipeline to build real-world environments



- Training data: EO imagery, LWIR imagery\*
- Object level truth data: category, positions, detection boxes
- Pixel level truth data: category (segmentation masks), range, incident angle to ground



### **EO Image**

### **Ground Truth**



- Simulation enables generation of massive amounts of accurately labeled and diverse training data
- Utilizing simulated data with the training of real-world models is an open area of research

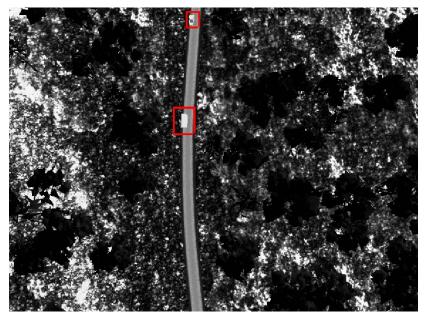
\* Hsu et al. Empirical LWIR Scene Simulation Based on E/O Satellite and Airborne LWIR Imagery







# **Example IR Vehicle Detections**



- Vehicle detection model trained on large amounts of simulated overhead imagery
- Very high performance achieved on simulation environments (~90% precision and recall)
  - Simulation currently leveraged for initial algorithm development and hardware-in-the-loop testing
  - Approaches for transferring simulation trained models to real-world applications currently being investigated



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# Outline

- Introduction
- Accelerating Imagery Analysis
- Interactive and Interpretable AI
- Summary



# **Example Human-Machine Teaming:** Visual Question Answering Problem

FRENCEN NENGEN

### **Today** Ask questions by querying a database

SELECT COUNT(\*) FROM cars, buildings WHERE ST\_Contains(ST\_GeomFromGeoHash('9qqj7nmxncg'), ST\_GeomFromGeoHash(building.geo)) AND ST\_Contains(ST\_GeomFromGeoHash('9qqj7nmxncg'), ST\_GeomFromGeoHash(car.geo))) AND ST\_Azimuth(ST\_GeomFromGeoHash(building.geo), ST\_GeomFromGeoHash(car.geo)) < 3\*pi()/2 AND ST\_Azimuth(ST\_GeomFromGeoHash(building.geo), ST\_GeomFromGeoHash(car.geo)) > pi()/2 **Desired Future** Ask questions through natural language

- 1. How many cars are south of the large building?
- 2. Are there any airplanes in the region?
- 3. How many helicopters are pointing east?

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CoW: Imagery Analysis- 23 GA 11/14/2019



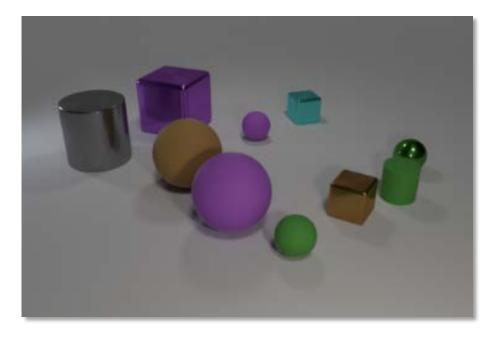
# **Visual Question Answering with Machine Learning**

• CLEVR Visual Reasoning Research Dataset

Transparency by Design

**Visual Reasoning Network** 

**Question:** *How many spheres are left of the cyan object?* 



Language parsing network **Output: series of sub-tasks** Find Cyan Objects Look Left Image processing network Find Spheres Count Answer: 4

### • Transparency by Design<sup>1</sup> (TbD) networks are performant (99.1% accuracy) and produce interpretable outputs

CoW: Imagery Analysis- 24 GA 11/14/2019 1. David Mascharka, Philip Tran, Ryan Soklaski, and Arjun Majumdar. "Transparency by Design: Closing the Gap Between Performance and Interpretability in Visual Reasoning." *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition* (CVPR), 2018.

Outputs



# **Transparency by Design Approach to Visual Question Answering**

# Question: How many cars are south of the large building?

Parse question and identify sub-tasks:



Find large building



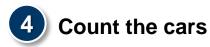








Find cars in region south of the large building



Answer: 23

- Transparency by Design networks can be combined with advanced analytics to provide rich access to imagery data
- Interpretable decisions allow for review and understanding of algorithm results



- Modern machine learning techniques provide a means of extracting information from high-throughput sensors on relevant time scales
  - Automated exploitation for rapid analysis
- Methods for developing AI systems in environments with limited training data is an active area of research
  - Active learning approaches can make more efficient use of data, reducing labeling requirements
  - Simulation can provide large volume of supplemental data when real data is limited
    - Research ongoing into best way to leverage simulated environments for real-world use
- Continued development of interactive and interpretable machine learning systems key for providing advanced decision support tools
  - Transparency by Design networks can be combined with advanced analytics to provide rich access to imagery data



- Bob Bond
- Curt Davis
- Constantine Frost
- Vijay Gadepally
- Dan Griffith
- Rick Heinrichs
- Bernadette Johnson
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- Alicia Kendall
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- Paul Metzger
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